Project Development Phase

Project Development Delivery of Sprint 1

Team ID	PNT2022TMID41963
Project Name	Signs with smart connectivity for Better road safety
Maximum Marks	4 Marks

Signs with smart connectivity for Better road safety

Sprint Goals:

- 1. Create and initialize accounts in various public APIs like OpenWeather API
 - 2. Write a Python program that outputs results given the inputs like weather and location.

Program Code: Weather.py:

```
# Python code importrequestsasreqs defget(myLocation,APIKEY):

apiURL=f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid=
{APIKEY}"

responseJSON= (reqs.get(apiURL)).json() returnObject=
{
  "temperature" : responseJSON['main']['temp'] -273.15, "weather"
  : [responseJSON['weather'][_]['main'].lower()
  for_inrange(len(responseJSON['weather']))],
  "visibility" : responseJSON['visibility']/100, # visibility in percentage where 10km is
  100% and 0km is 0%
} if("rain"inresponseJSON): returnObject["rain"] =
  [responseJSON["rain"][key] forkeyinresponseJSON["rain"]]
  return(returnObject) brain.py
```

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

weatherData=weather.get(myLocation,APIKEY)
finalSpeed=localityInfo["usualSpeedLimit"]
if"rain"notinweatherDataelselocalityInfo["usualSpeedLimit"]/2
finalSpeed=finalSpeedifweatherData["visibility"]>35elsefinalSpeed/2
if(localityInfo["hospitalsNearby"]): # hospital zone doNotHonk=True
else: if(localityInfo["schools"]["schoolZone"]==Fals e): # neither
school nor hospital zone doNotHonk=False else:

```
# school zone now= [dt.now().hour,dt.now().minute] activeTime=
[list(map(int,_.split(":"))) for_inlocalityInfo["schools"]["activeTime"]]
doNotHonk=activeTime[0][0]<=now[0]<=activeTime[1][
0] andactiveTime[0][1]<=now[1]<=activeTime[1][1]
return({
    "speed" : finalSpeed,
    "doNotHonk" : doNotHonk
})
# UTILITY LOGIC SECTION ENDS main.py</pre>
```

The code that runs in a forever loop in the microcontroller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
# IMPORT SECTION STARTS
importbrain
# IMPORT SECTION ENDS
# --- ------ -----
# USER INPUT SECTION STARTS myLocation="Chennai,IN"
APIKEY="9cd610e5fd400c74212074c7ace0d62
c" localityInfo= { "schools" :
{ "schoolZone":
True,
"activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
"hospitalsNearby": False,
"usualSpeedLimit": 40# in km/hr
# USER INPUT SECTION ENDS
# --- - -
# MICRO-CONTROLLER CODE STARTS
print(brain.processConditions(myLocation,APIKEY,localityInfo))
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR
PLANNED
SPRINT SCHEDULE
# MICRO-CONTROLLER CODE ENDS
Output:
# Code Output
{'speed': 40, 'doNotHonk': False}
```