

TEAM ID : PNT2022TMID43421

Member 2 : Philomina Syndria Aruja

Assignment 4 :

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Program

```
const int TRIG_PIN=7;
const int ECHO_PIN=8;

const unsigned int MAX_DIST=23200;

void setup(){

    pinMode(TRIG_PIN,OUTPUT);
    digitalWrite(TRIG_PIN,LOW);
    pinMode(ECHO_PIN,INPUT);
    Serial.begin(9600);
}

void loop() {
    unsigned long t1;
    unsigned long t2;
    unsigned long pulse_width; float cm;
    float inches;

    digitalWrite(TRIG_PIN,HIGH); delayMicroseconds(10);
    digitalWrite(TRIG_PIN,LOW);

    while(digitalRead(ECHO_PIN)==0);

    t1= micros();
    while(digitalRead(ECHO_PIN)==1); t2= micros();
```

```

pulse_width=t2-t1;
cm=pulse_width/ 58 ;
inches=pulse_width/148.0;
if (pulse_width>MAX_DIST){
    Serial.println("Outofrange");
}
else{
    Serial.println("*****");
    Serial.print("TheMeasuredDistanceincm:");
    Serial.println(cm);

    if( cm < 100 ){

        Serial.println("Alert!!");

    }
    Serial.print("*****");
}
}
delay(1000);
}

```

Output:

1. If the distance is less than 100 cms ,it alerts.

IBM

sketchino copy - Wokwi Arduino X

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```
10 // The Trigger pin will tell the sensor to range find
```

```
14 //pulses coming back from the distance sensor
```

```
15 pinMode(ECHO_PIN, INPUT );
```

```
18 }
```

```
19 void loop() {
```

```
20   unsigned long t1;
```

```
21   unsigned long t2;
```

```
22   unsigned long pulse_width;
```

```
23   float cm;
```

```
24 }
```

The Mea en red Dr stance in etc: 2 68.00

*****Out of range

TneMeasuredDistanceincm:197.00

TheMeasuredDistanceincm:2.00

Alert!!

31°C
Cloudy



7.2 KBps
2.0 KBps

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ECE



```
10 // The Trigger pin will tell the sensor to range find
```

```
12 digitalWrite(TRIG_PIN, LOW);
```

```
15 pinMode(ECHO_PIN, INPUT );
```

```
21 unsigned long t2;
```

```
22 unsigned long pulse_width;
```

TheMeasuredDistanceincm:2.00

Alert!!

31°C
Cloudy



0.2 KBps
0.0 KBps

ENG
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The screenshot displays the Wokwi online Arduino IDE interface. On the left, the code editor shows a C++ program for an ultrasonic sensor. The code defines pins, sets up the sensor, and measures the distance. On the right, the simulation pane shows an Arduino Uno connected to an ultrasonic sensor. The serial monitor displays the output of the program, showing a measured distance of 91.00 cm, followed by an alert, and then 124.00 cm.

```

1 //Pins
2 const int TRIG_PIN = 7;
3 const int ECHO_PIN = 8;
4
5 //Anything over 400 cm (23200 us pulse) is "out of range"
6 const unsigned int MAX_DIST = 23200;
7
8 void setup(){
9
10    // The Trigger pin will tell the sensor to range find
11    pinMode(TRIG_PIN, OUTPUT);
12    digitalWrite(TRIG_PIN, LOW);
13    //Set Echo pin as input to measure the duration of
14    //pulses coming back from the distance sensor
15    pinMode(ECHO_PIN, INPUT );
16    // We'll use the serial monitor to view the sensor output
17    Serial.begin(9600);
18 }
19
20 void loop() {
21     unsigned long t1;
22     unsigned long t2;
23     unsigned long pulse_width;
24     float cm;
25     float inches;
  
```

Simulation Output:

```

*****
The Measured Distance in cm: 91.00
Alert!!
*****
The Measured Distance in cm: 124.00
*****
  
```