# Smart Waste Management System for MetropolitanCities

## **ASSIGNMENT 4**:

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud anddisplay in device recent events.

Upload document with wokwi share link and images of ibm cloud

### **CODE:**

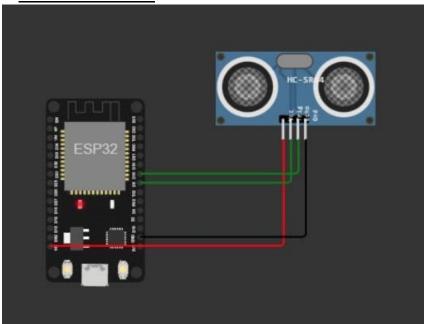
```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
#define DEVICE_TYPE "NodeMCU"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
void publishData();
const int trigpin=5;
const int echopin=18;
  pinMode(trigpin, OUTPUT);
```

```
pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
void loop() {
 publishData();
 delay(500);
 if (!client.loop()) {
   mqttConnect();
/oid wifiConnect() {
 while (WiFi.status() != WL_CONNECTED) {
   delay(500);
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
 if (!client.connected()) {
     delay(500);
   initManagedDevice();
   Serial.println();
void initManagedDevice() {
 if (client.subscribe(topic)) {
void publishData()
 digitalWrite(trigpin, LOW);
 digitalWrite(trigpin, HIGH);
```

```
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
   String payload = "{\"Alert distance\":";
   payload += dist;
   payload += "}";

   Serial.print("\n");
   Serial.print("Sending payload: ");
   Serial.printin(payload);
   if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
   } else {
        Serial.println("Publish FAILED");
   }
}</pre>
```

#### **CONNECTIONS:**



## **WOKWI LINK:**

https://wokwi.com/projects/347739718480298580

#### **OUTPUT:**

