# Assignment - 4 Distance Detection Using Ultra Sonic Sensor

Assignment Date	19 October 2022
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Maximum Marks	2 Marks

#### Question 1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK: https://wokwi.com/projects/346228322074624596

#### CODE:

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
#define ORG "f59trs"//IBM ORGANITION ID
#define DEVICE TYPE "ultrasonicsensor"//Device type mentioned in ibm watson
IOT Platform
#define DEVICE_ID "distancedetection"//Device ID mentioned in ibm watson IOT
#define TOKEN "AlGMGaaF01nawa1QA3" //Token
String data3;
float dist;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of
event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
```

```
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the
predefined client id by passing parameter like server id, portand
wificredential
int LED = 4;
int trig = 5;
int echo = 18;
void setup()
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo, INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
void loop()// Recursive Function
 digitalWrite(trig,LOW);
 digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);
  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
   mqttconnect();
/*.....retrieving to
void PublishData(float dist) {
 mqttconnect();//function call for connecting to ibm
    creating the String in in form JSon to update the data to ibm cloud
```

```
String object;
  if (dist <100)</pre>
    digitalWrite(LED, HIGH);
    Serial.println("object is near");
    object = "Near";
  else
    digitalWrite(LED, LOW);
    Serial.println("no object found");
    object = "No";
  String payload = "{\"distance\":";
  payload += dist;
  payload += "," "\"object\":\"";
  payload += object;
  payload += "\"}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud
failed
  } else {
    Serial.println("Publish failed");
void mqttconnect() {
 if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
     initManagedDevice();
     Serial.println();
```

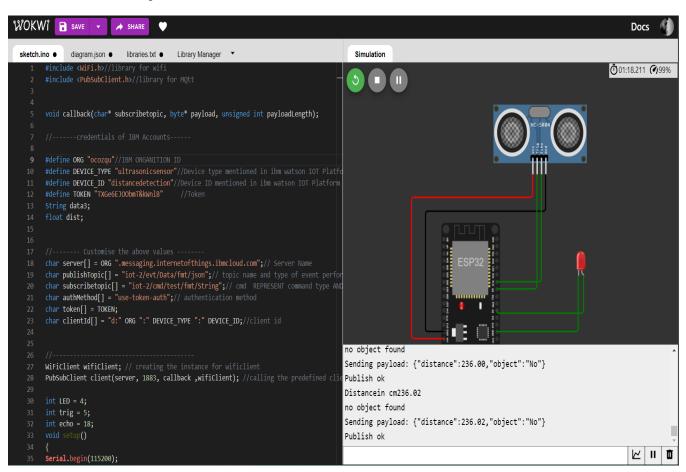
```
void wificonnect() //function defination for wificonnect
  Serial.println();
  Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
 while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
void initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
   Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {</pre>
   //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
     if(data3=="Near")
// Serial.println(data3);
```

```
// digitalWrite(LED,LOW);

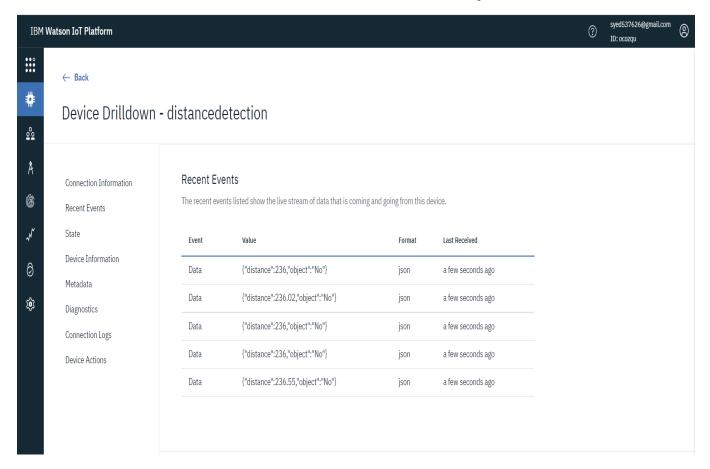
// }
data3="";
}
```

#### **OUTPUT:**

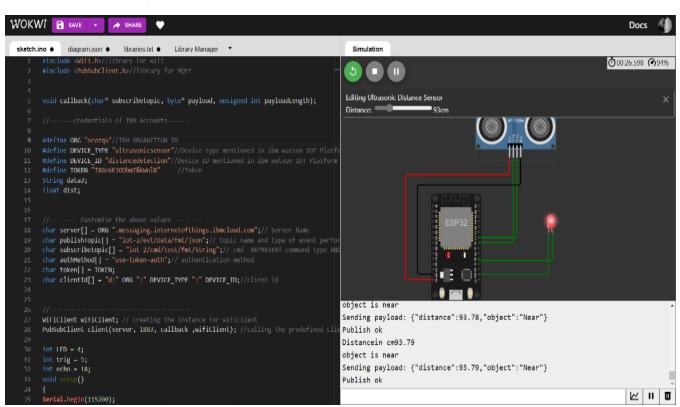
When the object is not near to ultrasonic sensor



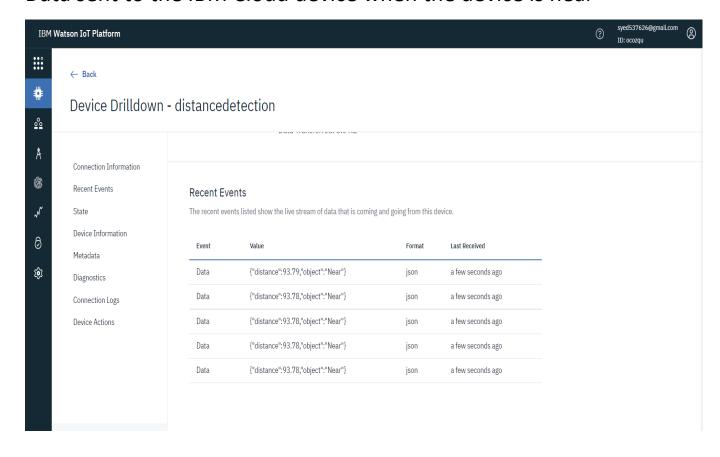
## Data sent to the IBM Cloud device when the object is far



## When the object is nearer to the ultrasonic sensor



## Data sent to the IBM Cloud device when the device is near



https://wokwi.com/projects/346228322074624596