# Assignment -4 Wokwi Connection for the Ultrasonic Sensor

Assignment Date	31 October 2022
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Maximum Marks	2 Marks

#### Question:

Write code and connections in wokwi for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

#### **Solution:**

```
Program:
#include <WiFi.h>
#include < PubSubClient.h >
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
```

```
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
}
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
 }
}
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
```

```
}
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) {
   Serial.print(".");
   delay(500);
  }
  initManagedDevice();
  Serial.println();
 }
}
void initManagedDevice() {
 if (client.subscribe(topic)) {
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
  String payload = "{\"Normal Distance\":";
  payload += dist;
```

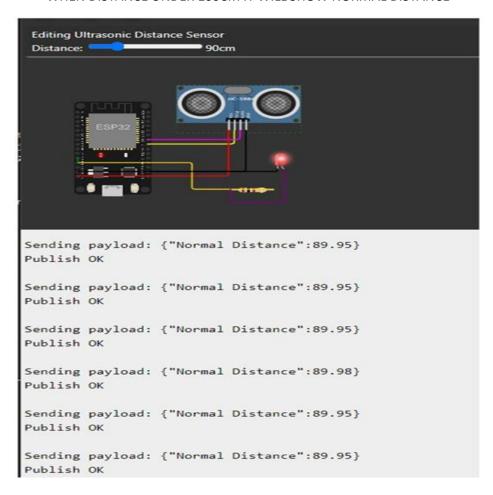
```
payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
  }
 }
  if(dist>101 && dist<111){
  String payload = "{\"Alert distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
   digitalWrite(led,HIGH);
  }
Else
{
   Serial.println("Publish FAILED");
 }
 }
 }
 void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
 Serial.print("callback invoked for topic:");
 Serial.println(subscribeTopic);
 for(int i=0; i<payloadLength; i++){</pre>
  dist += (char)payload[i];
 }
```

```
Serial.println("data:"+ data3);
if(data3=="lighton"){
   Serial.println(data3);
   digitalWrite(led,HIGH);
}
data3="";
}
```

## **Output:**

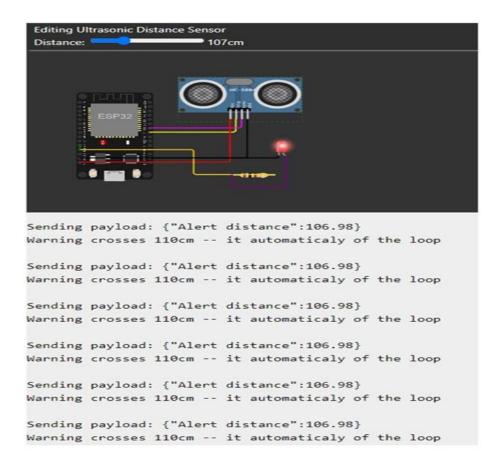
#### Case 1:

#### WHEN DISTANCE UNDER 100CM IT WILL SHOW NORMAL DISTANCE



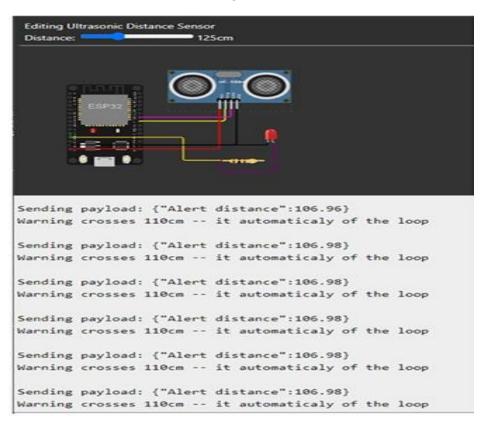
#### Case 2:

WHEN DISTANCE CROSS 100CM IT WILL SHOW ALERT WITH WARNING MESSAGE DISTANCE



Case 3:

WHEN IT CROSS ABOVE 110CM IT TOTALLY MOVE TO IFF STATE ONCE IT REDUCE TO 110CM IT ON AGAIN



## **IBM Cloud Output**

## NORMAL DISTANCE

## Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	["Normal Distance":89.95]	json	a few seconds ago
Data	("Normal Distance":89.95)	json	a few seconds ago
Data	["Normal Distance";89.95]	json	a few seconds ago
Data	("Normal Distance":89.95)	json	a few seconds ago
Data	("Normal Distance";89.95)	json	a few seconds ago

### **ALERT DISTANCE**

# Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	["Alert distance":106.98]	json	a few seconds ago
Data	{"Alert distance":107.03}	json	a few seconds ago
Data	("Alert distance":106.98)	json	a few seconds ago
Data	("Alert distance":106.98)	json	a few seconds ago
Data	("Alert distance":106.98)	json	a few seconds ago