ASSIGNMENT 4

Date	24/10/22
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Project Name	Smart Waste Management System For Metropolitan Cities.

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Upload document with wokwi share link and images of ibm cloud

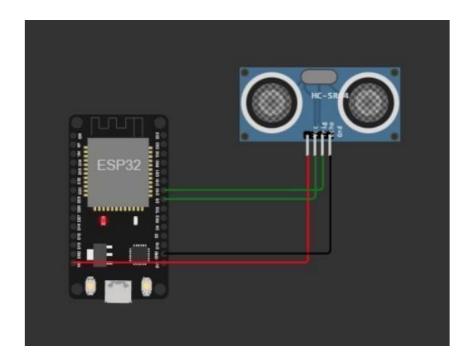
CODE:

```
#include<WiFi.h>
#include<PubSubClient.h>WiFiClientwifiClient;
#defineORG"nhpwjc"
#defineDEVICE_TYPE"NodeMCU"#defineD
EVICE ID"USEYOURID"#defineTOKEN"USE
YOUR TOKEN"
#definespeed0.034
charserver[]
=ORG".messaging.internetofthings.ibmcloud.com";charpublishTo
pic[] ="iot-2/evt/Data/fmt/json";chartopic[] ="iot-
2/cmd/home/fmt/String";charauthMethod[]="use-token-
auth";chartoken[] =TOKEN;
charclientId[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
PubSubClient
              client(server, 1883,wifiClient);void
publishData();
constinttrigpin=5;
constintechopin=18;S
tringcommand;Stringd
ata="";
 longduration
;floatdist;
tup()
  Serial.begin(115200);pinM
  ode(trigpin,OUTPUT);
```

```
pinMode(echopin, INPUT);
 wifiConnect(); mqttConnect();
} void loop() {
 publishData(); delay(500);
 if (!client.loop()) { mqttConnect();
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status() !=
 WL_CONNECTED) { delay(500);
    Serial.print(".");
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() { if
 (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
   while (!client.connect(clientId, authMethod, token)) { Serial.print(".");
    delay(500);
    initManagedDevice(); Serial.println();
  } }
void
       initManagedDevice()
  (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic)); Serial.println("subscribe to
   cmd OK");
 } else {
    Serial.println("subscribe to cmd FAILED"); } }
void publishData()
{ digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
```

```
delayMicroseconds(10);digitalWrite
  (trigpin, LOW);duration=pulseIn(ech
  opin, HIGH);dist=duration*speed/2;i
  f(dist<100){
      Stringpayload="{\"Alertdistance\":";payload+=d
      ist;
      payload+="}";Serial.print("\n");Se
      rial.print("Sendingpayload:");
      Serial.println(payload);
      if(client.publish(publishTopic,(char*)payload.c_str())){
            Serial.println("PublishOK");
      }else{
            Serial.println("PublishFAILED");
      }
   }
}</pre>
```

CONNECTIONS:



OUTPUT:

