Assignment 4

QUESTION:

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Upload document with wokwi share link and images of ibm cloud

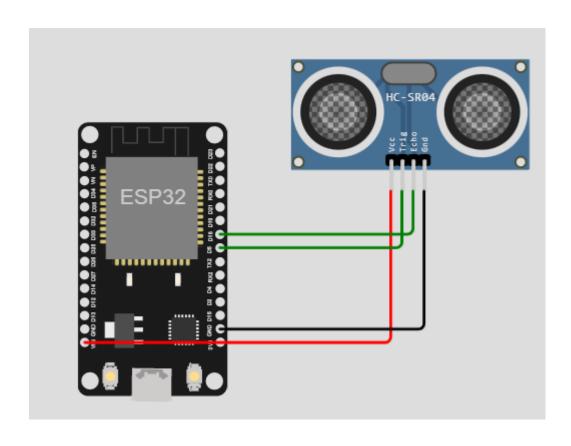
CODE:

```
#include <WiFi.h>
#include < PubSubClient.h >
WiFiClient wifiClient;
String data3;
#define ORG "3yngbh"
#define DEVICE TYPE "Assignment"
#define DEVICE ID "1234"
#define TOKEN "234567890"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
Serial.begin(115200);
pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
```

```
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
 }
}
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) {
   Serial.print(".");
   delay(500);
  initManagedDevice();
  Serial.println();
 }
}
void initManagedDevice() {
 if (client.subscribe(topic)) {
 // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
  Serial.println("subscribe to cmd FAILED");
 }
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
```

```
if(dist<100){
 String payload = "{\"Alert Distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish OK");
 }
}
 if(dist>100){
 String payload = "{\"Distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish OK");
 }else {
  Serial.println("Publish FAILED");
 }
}
}
```

CIRCUIT



CIRCUIT OUTPUT

Sending payload: {"Alert distance":93.96}

Publish OK

CLOUD RESPONDED IMAGE

Event	Value	Format	Last Received
Data	('West distance' (93.96)	[son.	a few seconds ago
Dota	("Nert distance"/93.96)	json	a few seconds ago
Doto	("Nert distance"/93.96)	json	a few seconds ago
Dots	("West distance" (93.%)	json	a few seconds ago
Cots	("West distance" (93.96)	jnon	a few seconds ago

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