

O =

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int led = 13;
 2 int sensor = 2;
 3 int state = LOW;
   int val = 0;
   void setup() {
      pinMode(led, OUTPUT);
     pinMode (sensor, INPUT);
     Serial.begin(9600);
10
11
   void loop(){
     val = digitalRead(sensor);
15
     if (val == HIGH) {
       digitalWrite(led, HIGH);
       delay(500);
       if (state == LOW) {-
         Serial.println("Motion detected!");
          state = HIGH;
         digitalWrite(led, LOW);
          delay(500);
          if (state == HIGH) (
            Serial.println("Motion stopped'");
```

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14
      if (val == HIGH) {
15
        digitalWrite(led, HIGH);
16
        delay(500);
17
18
        if (state == LOW) {
19
          Serial.println("Motion detected!");
20
          state = HIGH;
21
22
23
      else
          digitalWrite(led, LOW);
74
delay(500);
if (state == HIGH) {
            Serial.println("Motion stopped!");
             state = LOW;
```