

Signs with Smart Connectivity for Better Road Safety

Team ID :PNT2022TMID45862

Final code:

```
#include <LiquidCrystal.h> #define BLYNK_PRINT Serial #include <ESP8266WiFi.h>
```

```
#include <BlynkSimpleEsp8266.h>
```

```
char auth[] "Y4DBRJfvaDUee9LMZHCWT7pd=VL01RGU"; // Your
```

```
WiFi credentials. // Set password to " for open networks.
```

```
char said[] = "hellow";
```

```
char pass[] "12345678":
```

```
const int rs = D5, en D6, d4 D1, ds D2, d6 D3, d7 = D4; LiquidCrystal led(rs, en, d4, d5, d6, d7);  
int a=0;
```

```
BLYNK_WRITE(V2)
```

```
aparan.asInt();
```

```
void setup() { // set up the LCD's number of columns and rows: Serial.begin(9600);  
Blynk.begin(auth, ssid, pass); led.begin(16, 2);
```



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```
void loop() {
```

```
Blynk.run();
```

```
lcd.setCursor(0, 1); if(a+1)
```

```
{
```

```
lcd.print ("accident occurred"); Serial.print("hi");
```

```
}
```

```
Else
```

```
{
```

```
lcd.print("welcome");
```

```
}
```

```
#define BLYNK_PRINT Serial
```

```
#include <ESP8266WiFi.h>
```

```
#include <BlynkSimpleEsp8266.h>
```

```
char auth[q6FAQlggdiHlxAPEa116]; char said[] "hellow":
```

```
char pass 12345678":
```

```
String stri
```



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```
void setup() { Serial.begin(9600);

Blynk.begin(auth, said, pass);

void loop() {

Blynk.run();

if(Serial.available()>0)

str=Serial.readStringUntil('/');
}

// Serial.print(str); // Blynk.notify("location:");

Blynk.notify(str);
}

#include <TinyGPS++.h> #include <SoftwareSerial.h>

TinyGPSPlus : SoftwareSerial (3,4): attachInterrupt
(digitalPinToInterrupt (2), piezo, CHANGE);
}

void loop() { Serial.read();

// Serial.println(" ");
```



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```
delay(200);
```

```
C
```

```
digitalWrite(e,HIGH); digitalWrite(11,HIGH); digitalWrite(12,HIGH); delay(200);  
digitalWrite(12,LOW);
```

```
else if(n-2)
```

```
digitalWrite(6,LOW);
```

```
digitalWrite(11,LOW); digitalWrite(10,LOW); digitalWrite(9,LOW); digitalWrite(12,HIGH);  
delay(200); digitalWrite(12,LOW);
```

```
else if (1)
```

```
analogWrite(11,100); analogWrite(6,100); digitalWrite(12,HIGH); delay(200);  
digitalWrite(12,tov);
```

```
// while (az.available() > 0) // if (p.encode(as.read())) //displayinfo():
```

```
void displayInfo()
```

```
// Serial.print(F("Location: "));
```

```
Serial.print(gpe.location lat(), 63: Serial.print (FC", "
```



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```
Serial.print(ps/location, lng(), );
```

```
// Berial print (F("INVALID"))\
```

```
Serial.print(+10, 308125")
```

```
Serial.print(", Berial prias (7.3)
```

```
Serial.print(F(" Date/Time: ")); if (ps.date.isValid())
```

```
Serial.print(ps.date.outh());
```

```
Serial.print(F("/"));
```

```
Serial.print(ps.date.day()); Serial.print((
```

```
Serial.print(gps.date.year());
```

```
Serial.print(F(INVALID));
```

```
Serial.print(F()); if (gpe tine isValid())
```

```
if (gpe tine.bour() < 10) Serial.print(F(""));
```



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```
Serial.print(gps.time.hour());
```

```
}Serial.print(F(":")); if (gps.time.minute() < 10) Serial.print(F("0"));
```

```
Serial.print(gps.time.minute());
```

```
Serial.print(F(" "));
```

```
if (gps.time.second() < 10) Serial.print(F("0"));
```

```
Serial.print(gps.time.second()); Serial.print(F(" "));
```

```
if (gps.time.centisecond() < 10) Serial.print(F("0")); Serial.print(gps.time.centisecond());
```

```
// Serial.print(F(INVALID));
```

```
Serial.println();
```

```
void piezo()
```

```
while (available() > 0)
```

```
displayInfo();
```



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```
void setup() {
```

```
pinMode(D2, INPUT); pinMode(D3, OUTPUT);
```

```
digitalWrite(D2, LOW)
```

```
Serial.begin(3600);
```

```
void loop(){
```

```
a=digitalRead(D1); if (a==1)
```

```
Serial.print("1"); } else if (a==0)
```

```
if (b==1)
```

```
Serial.print("2");
```

```
d=digitalRead(D4); if (d==1)
```

```
Serial.print("3");
```

```
}
```

