## **PROJECT OBJECTIVES**

Date	17 November 2022
Team ID	PNT2022TMID43224
Project Name	lot based smart crop protection for agriculture

## By the end of this project we will:

- @.Gain knowledge of Watson lot Platform
- @.Connectinglot devices to the Watson lot Plateform and exchange the sensor data.
- @.Gain knowledge on Cloudant DB.
- @.Gain knowledge on using the Clarifai service.
- @.Gain knowledge of storing images in IBM object storage and retrieving images.
- @.Creating a web application thrugh which the user interacts ith the devices.

## **Project flow:**

- @.The device will detect the animals and birdsusing the Clarifai service.
- @.If any animal or bird is detected the image will be captured and stored in the IBM cloud object service.
- @.lt also generates an alarm and avoid animals and birds from desroying the crop.
- @.The image URL will be stored in the IBM Cloudant DB service.
- @.The device will also moniter the soil moisture level, temperature, and humidity values and send them to the IBM IOT platform.
- @.The image will be retrieved from object storage and displayed in the web application.
- @.A web application is developed to visualize the soil moisture, temperatur, and humidity values.
- @.Userscan also control the mniters through web applications.

TO accompolish this, we have to complete all thr activities andtasks listed below,

@.Create and configure IBM cloud services

create IBM Waston iot platform.

create a device & configure the IBM platform.

create Node-RED service.

create a database in Cloudant DB to store location data.

- create a cloud object storage service and create a bucket to store the images.
- @.Develop a python script to publish the sensor parameters like Temperature Humidity, and Soil moisture to the IBM lot platform and detect he animals and birds in the video streaming using Clarifai.
- @.Develop a web application using Node=RED service, Display the image in the Node-RED web UI and also display the temperature humidity and soil moisture levels. Integrate the buttons in the UI to control the motors.