ASSIGNMENT-4

DISTANCE DETECTION USING ULTRASONIC SENSOR

TEAM ID: PNT2022TMID52298

NAME: K. ANUSHA

REGISTER NUMBER: 963519106009

PROJECT TITLE: Gas leakage monitering and alerting system.

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance isless than 100 cms send "alert" to IBM cloud and display in device recent events

CODE:

```
diagram.json •
esp32-blink.ino
                                   libraries.txt •
                                                 Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

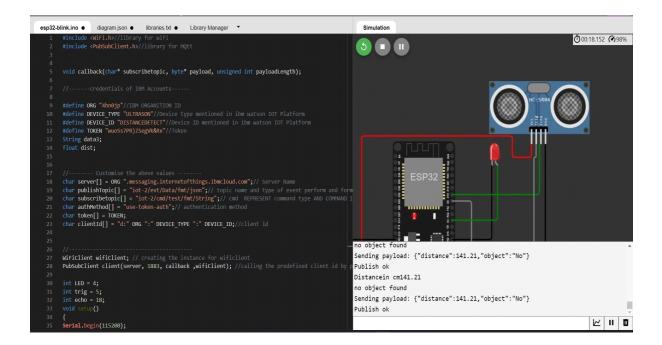
```
### Serial.println(")

### Serial.println()

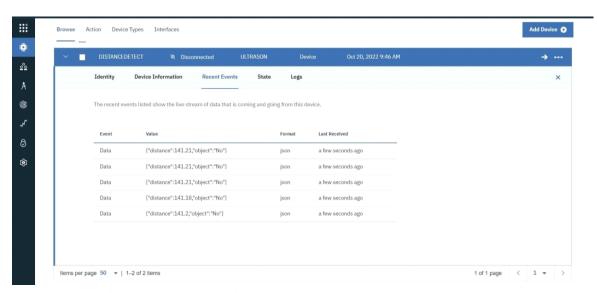
###
```

```
esp32-blink.ino ●
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager *
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

OUTPUT:

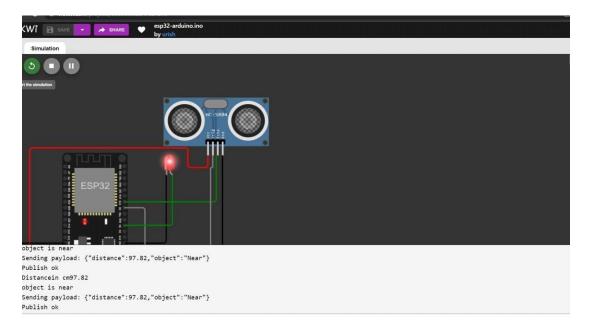


Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor

when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

