

ASSIGNMENT 1

TEAM ID: PNT2022TMID52298

NAME : M Mary Lincy

REGISTER NUMBER: 963519106023

PROJECT TITLE: Gas leakage monitoring and alarting system

SOURCE CODE :

```
//LDR sensor-----
```

```
int sensorReading = 0;
```

```
//LDR sensor-----
```

```
//Ultrasonic sensor-----
```

```
int inches = 0;
```

```
int cm = 0;
```

```
int triggerPin = 13;
```

```
int echoPin = 12;
```

```
int default = 0;
```

```
long readUltrasonicDistance(int triggerPin,int echoPin)
```

```
{
```

```
    pinMode(triggerPin, OUTPUT);
```

```

digitalWrite(triggerPin, LOW);
delayMicroseconds(2);
digitalWrite(triggerPin, HIGH);
delayMicroseconds(10);
digitalWrite(triggerPin, LOW);
pinMode(echoPin, INPUT);
return pulseIn(echoPin, HIGH);
}

//Ultrasonic sensor-----

//Gas sensor-----

int adcPin = 0;
int adcValue = 0;
float v;
float rs,ppm;

int buttonState = 0;
void setup() {

//LDR sensor-----

    pinMode(8, OUTPUT);
    pinMode(A0, INPUT);

    Serial.begin(9600);
//LDR sensor-----

//Ultrasonic sensor-----

    pinMode(2, OUTPUT);
    cm = 0.01723*readUltrasonicDistance(triggerPin, echoPin);

```

```

    default = cm;

    Serial.print(default);

//Ultrasonic sensor-----

//PIR sensor-----

    pinMode(3, INPUT);

    pinMode(9, OUTPUT);

//PIR sensor-----


//Motor-----


    pinMode(5, OUTPUT);

    pinMode(4, INPUT);


//Motor-----

    pinMode(7, OUTPUT);

    pinMode(A1, INPUT);
}

void loop() {/#####

//LDR sensor-----

    sensorReading = analogRead(A0);


    if(sensorReading < 900){
        digitalWrite(8, HIGH);
    }else{
        digitalWrite(8, LOW);
    }

//LDR sensor-----


//Ultrasonic sensor-----

```

```
cm = 0.01723*readUltrasonicDistance(triggerPin, echoPin) ;  
if(cm < default){  
    digitalWrite(2,HIGH);  
    delay(50);  
    digitalWrite(2,LOW);  
}else{  
    digitalWrite(2,LOW);  
  
}
```

```
//Ultrasonic sensor-----
```

```
//PIR sensor-----
```

```
    int value = digitalRead(3);  
    if (value == 1)  
    {  
        tone(9, 440, 1000);  
    }  
}
```

```
//PIR sensor-----
```

```
//Motor-----
```

```
    buttonState = digitalRead(4);  
    if(buttonState == 1){  
        digitalWrite(5,0);  
    }  
    else{  
        digitalWrite(5,HIGH);  
    }  
}
```

```
//Motor-----
```

```
//Gas sensor-----
```

```
int sensor_gas = analogRead(A1);
```

```
if(sensor_gas >= 400){
```

```
    digitalWrite(7,HIGH);
```

```
}
```

```
else{
```

```
    digitalWrite(7,LOW);
```

```
}
```

```
//-----
```

```
delay(1000);
```

```
}
```

