## ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

## **SOURCE CODE:**

```
int t=2;
int e=3;
void setup()
Serial.begin(9600);
 pinMode(t,OUTPUT);
 pinMode(e,INPUT);
pinMode(12,OUTPUT
);
void loop()
//ultrasonic sensor
 digitalWrite(t,LOW);
 digitalWrite(t,HIGH);
 delayMicroseconds(10);
 digitalWrite(t,LOW); float
 dur=pulseIn(e,HIGH); float
 dis=(dur*0.0343)/2;
 Serial.print("Distance is:
"); Serial.println(dis);
if(dis > = 100)
 { digitalWrite(8,HIGH
  );
```

```
digitalWrite(7,HIGH
   );
}

//Buzzer For ultrasonic Sensor
if(dis>=100) { for(int i=0;
i<=30000; i=i+10)
{ tone(12,i);
delay(1000);
noTone(12);
delay(1000);
}</pre>
```

