Develop a python script

Team ID	PNT2022TMID01046
Project Name	Smart waste management system for
	metropolitan cities

Step 1: Open python idle

Step2: Type the program

Step 3: Then click on file and save the document

Step 4: Then click on Run then Run Module

Step 5: output will be appeared in the idle window

Python script

```
// Project: Smart Waste Management
// Team ID: PNT2022TMID01046
import requests
import json
import ibmiotf.application
import ibmiotf.device
import time
import random
import sys

# watson device details

organization = "ms9s41"
devicType = "BIN1"
deviceId = "BIN1ID"
authMethod= "token"
authToken= "123456789"
```

```
#generate random values for randomo variables for distance and loadcell
def myCommandCallback(cmd):
   global a
   print("command recieved:%s" %cmd.data['command'])
    control=cmd.data['command']
   print(control)
try:
        deviceOptions={"org": organization, "type": devicType, "id": deviceId, "auth-method":authMethod, "auth-token":authToken}
        deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
        print("caught exception connecting device %s" %str(e))
        sys.exit()
# connect and send a datapoint "distance and loadcell" with value integer value into the cloud as a type of event for every 10
deviceCli.connect()
while True:
    distance= random.randint(10,70)
   loadcell= random.randint(5,15)
    data= {'dist':distance,'load':loadcell}
    if loadcell < 13 and loadcell > 15:
        load = "90 %"
    elif loadcell < 8 and loadcell > 12:
          load = "60 %"
    elif loadcell < 4 and loadcell > 7:
          load = "40 %"
```

```
else:
         load = "0 %"
   if distance < 15:
         dist = 'Risk warning:' 'Dumpster poundage getting high, Time to collect :) 90 %'
    elif distance < 40 and distance >16:
         dist = 'Risk warning:' 'dumpster is above 60%'
   elif distance < 60 and distance > 41:
         dist = 'Risk warning:' '40 %'
    else:
         dist = 'Risk warning:' '17 %'
   if load == "90 %" or distance == "90 %":
         warn = 'alert :' 'Risk Warning: Dumpster poundage getting high, Time to collect :)'
   elif load == "60 %" or distance == "60 %":
         warn = 'alert :' 'dumpster is above 60%'
    else :
         warn = 'alert :' 'No need to collect right now '
   def myOnPublishCallback(lat=10.939091,long=78.135731):
       print("Chennai")
       print("published distance = %s " %distance, "loadcell:%s " %loadcell, "lon = %s " %long, "lat = %s" %lat)
       print(load)
       print(dist)
       print(warn)
   time.sleep(10)
```

```
success=deviceCli.publishEvent ("IoTSensor","json",warn,qos=0,on_publish= myOnPublishCallback)
success=deviceCli.publishEvent ("IoTSensor","json",data,qos=0,on_publish= myOnPublishCallback)

if not success:
    print("not connected to ibmiot")
    time.sleep(10)

deviceCli.commandCallback=myCommandCallback
#disconnect the device
deviceCli.disconnect()
```

Screenshots Python script:

