



```

float x, y, z, temp;
void setup()
{
    pinMode(8, INPUT);
    pinMode(5, OUTPUT);
    pinMode(6, OUTPUT);
    pinMode(A5, INPUT);
    pinMode(A4, INPUT);
    Serial.begin(9600);
}
void loop()
{
    x=digitalRead(8);
    y=analogRead(A5);
    z=analogRead(A4);
    Serial.println(x);
    Serial.println(y);
    Serial.println(z);
    temp = (double)z / 1024;
    temp = temp * 5;
    temp = temp - 0.5;
    temp = temp * 100;
    if ( (x>0) )
    {
        if ((y<550)&&(temp>30))
        {
            digitalWrite(5, HIGH);
            digitalWrite(6, HIGH);
        }
        else if((y<550)&&(temp<30))
        {
            digitalWrite(5, HIGH);
            digitalWrite(6, LOW);
        }
        else if((y>550)&&(temp>30))
        {
            digitalWrite(5, LOW);
            digitalWrite(6, HIGH);
        }
        else if((y>550)&&(temp<30))
        {
            digitalWrite(5, LOW);
            digitalWrite(6, LOW);
        }
    }
    else
    {
        digitalWrite(5, LOW);
        digitalWrite(6, LOW);
    }
}
}

```