ASSIGNMENT-4

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ASSIGNMENT 4:

Write code and connections in wokwi for ultrasonic sensors.

Whenever distance is less than 100cmssend"alert"to IBM cloud and display in device recent events.

Upload document with wokwi share link and images of IBM cloud

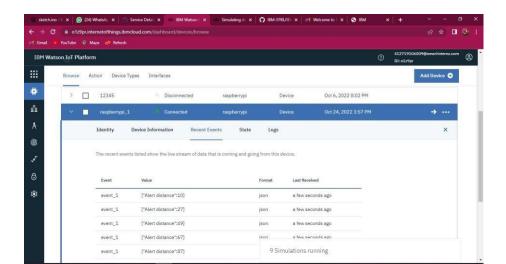
CODE:

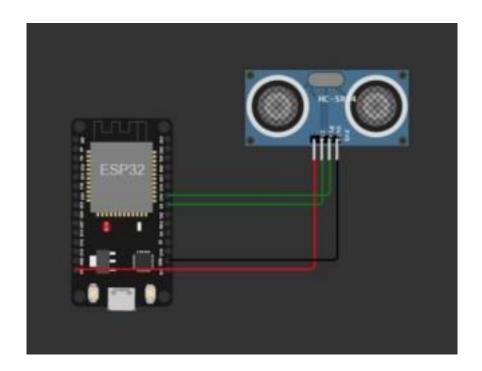
```
#include<WiFi.h>#include
<PubSubClient.h>WiFiClien
twifiClient;
#defineORG "o1z9pr"
#define DEVICE_TYPE
"raspberrypi"#define DEVICE ID
"USE YOUR ID"#defineTOKEN"USE
YOURTOKEN"
#definespeed0.034
char server[] =
ORG".messaging.internetofthings.ibmcloud.com";charpubli
shTopic[] = "iot-
2/evt/raspberrypi_1/fmt/json";chartopic[]="iot-
2/cmd/home/fmt/String"; char
authMethod[] = "use-
tokenauth";chartoken[] =
TOKEN;
charclientId[]="d:"ORG":"DEVIC
E_TYPE":"DEVICE_ID;
PubSubClient client(server,
wifiClient);voidpublishData();
```

```
const int
   trigpin=5;constintechop
   Stringcommand;
   Stringdata="";
 long
   duration; float
dist;
 voidsetup()
   {
     Serial.begin(115200);pinMode(tr
     igpin, OUTPUT);pinMode(echopin,
     INPUT);wifiConnect();
     mqttConnect();
 voidloop() {
     publishData();
     delay(500);
 if (!client.loop())
     {mqttConnect();
     }
   }
 voidwifiConnect(){
     Serial.print("Connecting to ");
     Serial.print("Wifi");WiFi.begin("Wokwi-GUEST","", 6); while
     (WiFi.status() != WL_CONNECTED)
       {delay(500);
       Serial.print(".");
     Serial.print("WiFi connected, IP address:
   ");Serial.println(WiFi.localIP());}
 voidmqttConnect(){
if
 (!client.connected())
       {Serial.print("Reconnecting MQTT client to
       "); Serial.println(server);
       while(!client.connect(clientId,authMethod,token))
       { Serial.print("."); delay(500); }
       initManagedDevice(); Serial.println();
     }
 voidinitManagedDevice(){
     if(client.subscribe(topic)){
       //Serial.println(client.subscribe(topic));
       Serial.println("subscribetocmdOK");
```

```
}
  else
  {
    Serial.println("subscribetocmdFAILED");
} voidpublishData()
{ digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);dela
  yMicroseconds(10);digitalWrite(
  trigpin, LOW);
  duration=pulseIn(echopin,HIGH);dis
  t=duration*speed/2;if(dist<100){
  Stringpayload="{\"Alertdistance\":";
  payload += dist;payload+=
    "}";
    Serial.print("\n");Serial.print("Sen
    ding payload:
    ");Serial.println(payload);
    if(client.publish(publishTopic,(char*)payload.c_str()))
    {Serial.println("PublishOK");
    } else {
      Serial.println("PublishFAILED");
    }
  }
}
```

CONNECTIONS:





OUTPUT:

