

Assignment -4

Assignment Date	25 Octber 2022
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Student Roll Number	GCTC1914L12
Maximum Marks	2 Marks

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Upload document with wokwi share link and images of ibm cloud

CODE

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
```

```
const int trigpin=5;
const int echopin=18;
String command;
String data="";
```

```
long duration;
float dist;
```

```

void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);

  publishData();
  delay(500);

  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
  Serial.println(WiFi.localIP());
}

void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

```

```

void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    }
  }

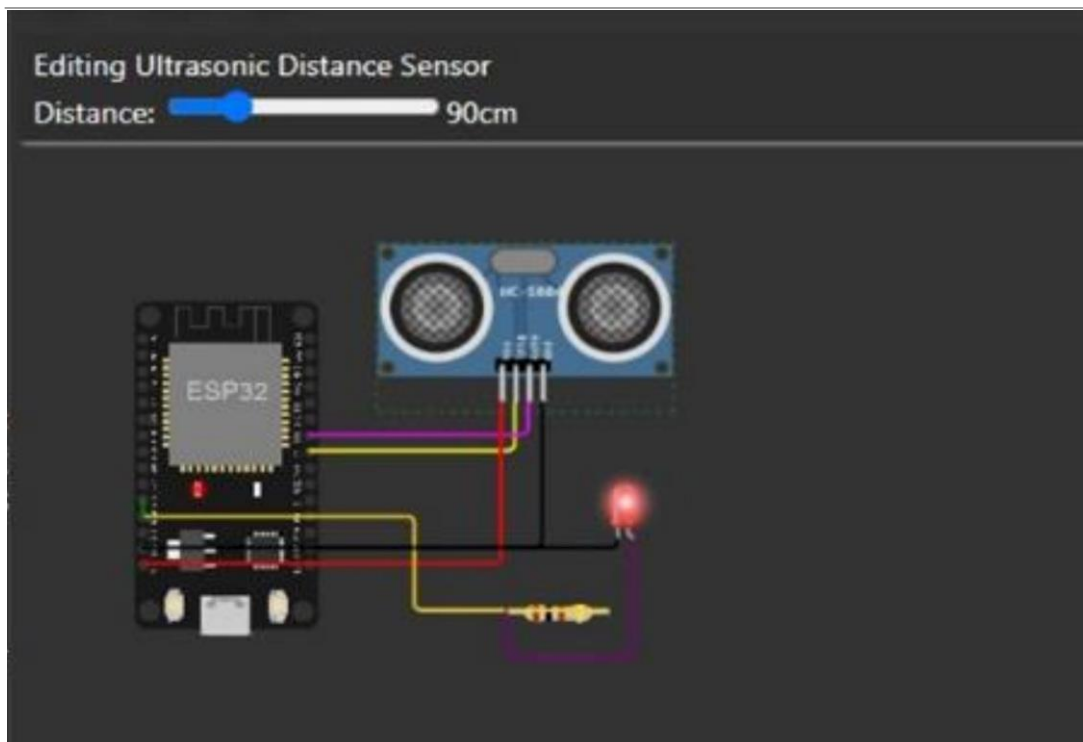
  if(dist>101 && dist<111){
    String payload = "{\"Alert distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if(client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
      digitalWrite(led,HIGH);
    }else {
      Serial.println("Publish FAILED");
    }
  }
}

```

```
}  
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){  
  Serial.print("callback invoked for topic:");  
  Serial.println(subscribeTopic);  
  for(int i=0; i<payloadLength; i++){  
    dist += (char)payload[i];  
  }  
  Serial.println("data:" + data3);  
  if(data3=="lighton"){  
    Serial.println(data3);  
    digitalWrite(led,HIGH);  
  }  
  data3="";  
}
```

NODE-RED



Sending payload: L"Normal Distance":89.9S}
Publish OK

Sending payload: "fJorma1 D1st ance":85.US}
Publi sh OK

Sending payload: ('9lormal Distance":89.9S}
Publish OK

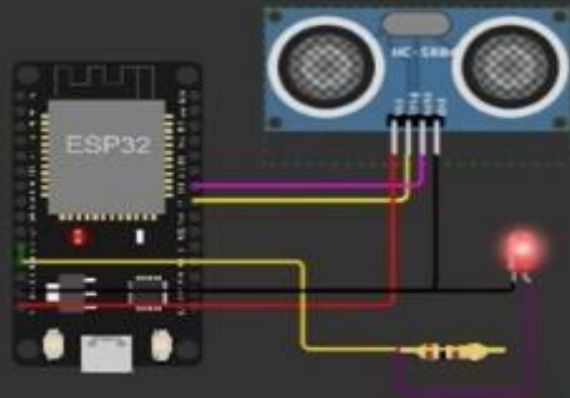
Sending payload: "fto ma1 Di sl ance":89.98}
Pub11 sh OK

Sending payload: ("loornal Di st ance":89.9S}
PubIi sh OF

Sending payload : {"fJorma 1 D i stance ": 89 . 95}
Publish OK

Editing Ultrasonic Distance Sensor

Distance:  107cm



Sending payload: {"Alert distance":106.98}

Warning crosses 110cm -- it automaticaly of the loop

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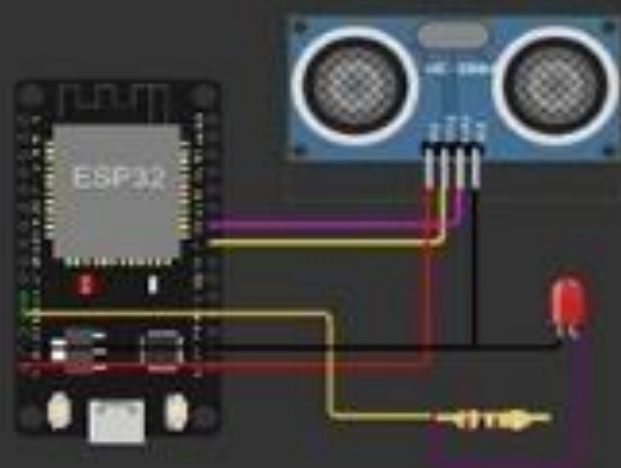
Warning crosses 110cm -- it automaticaly of the loop

Sending payload: {"Alert distance":106.98}

Warning crosses 110cm -- it automaticaly of the loop

Editing Ultrasonic Distance Sensor

Distance:  125cm



Sending payload: {"Alert distance":106.96}
Warning crosses 110cm -- it automaticaly of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automaticaly of the loop

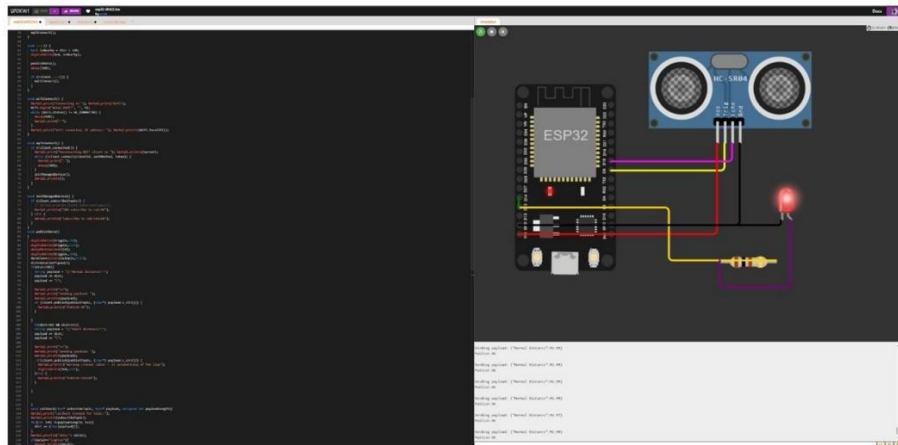
Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automaticaly of the loop

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Warning crosses 110cm -- it automaticaly of the loop

OUTPUT



Connection Information

Basic connection information about this device.

Device ID	Assignment4
Device Type	nodeMcu
Date Added	23 Oct 2022 07:20
Added By	920219104302@smartinternz.com
Connection Status	Disconnected
	Last Connected: 23 Oct 2022 16:57
	Client Address: 145.40.94.93 Insecure
	Duration: 3 minutes
	Data Transferred: 14.4 KB

Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago