

```
#!/usr/bin/env python
```

```
# coding: utf-8
```

```
# In[ ]:
```

```
import drive
```

```
drive.mount('/content/drive')
```

```
get_ipython().system('unzip drive/My\\Drive/dataset.zip')
```

```
# In[ ]:
```

```
# import necessarylib.
```

```
from tensorflow.keras.preprocessing.image import ImageDataGenerator
```

```
# In[ ]:
```

```
#image Data Agumentation
```

```
#setting parameter for Image Data agumentation to the traing data
```

```
train_datagen = ImageDataGenerator (rescale=1./255, shear_range=0.2, zoom_range=0.2,  
horizontal_flip=True)
```

```
#Image Data agumentation to the testing data
```

```
test_datagen=ImageDataGenerator(rescale=1./255)
```

```
# In[ ]:
```

```
#Loading our data and performing data agumentation
```

```
#performing data agumentation to train data
```

```
x_train = train_datagen.flow_from_directory('/content/dataset/train_set', target_size=(64, 64),  
batch_size=5, color_mode='rgb', class_mode='categorical')
```

```
#performing data agumentation to test data
```

```
x_test = test_datagen.flow_from_directory('/content/dataset/test_set', target_size=(64, 64),  
batch_size=5, color_mode='rgb', class_mode='categorical')
```

```
# In[4]:
```

```
#Importing Neccessary Libraries
```

```
import numpy as np #used for numerical analysis
```

```
import tensorflow #open source used for both ML and DL for computation
```

```
from tensorflow.keras.models import Sequential #it is a plain stack of Layers
```

```
from tensorflow.keras import layers #A Layer consists of a tensor-in tensor-out computation function
```

```
#Dense layer is the regular deeply connected neural network Layer
```

```
from tensorflow.keras.layers import Dense, Flatten
```

```
#Flatten-used for flattening the input or change the dimension
```

```
from tensorflow.keras.layers import Conv2D, MaxPooling2D #Convolutional Layer
```

```
#MaxPooling2D-for downsampling the image
```

```
from keras.preprocessing.image import ImageDataGenerator
```

```
# In[6]:
```

```
classifier=Sequential()
```

# First convolution layer and pooling

```
classifier.add(Conv2D(32, (3, 3), input_shape=(64, 64, 3), activation='relu'))
```

```
classifier.add(MaxPooling2D(pool_size=(2, 2)))
```

# Second convolution layer and pooling

```
classifier.add(Conv2D(32, (3, 3), activation='relu'))
```

# input\_shape is going to be the pooled feature maps from the previous convolution I

```
classifier.add(MaxPooling2D(pool_size=(2, 2)))
```

# Flattening the Layers

```
classifier.add(Flatten())
```

# In[7]:

# Adding a fully connected Layer

```
classifier.add(Dense (units=128, activation='relu'))
```

```
classifier.add(Dense (units=4, activation='softmax'))
```

```
# softmax for more than 2
```

```
classifier.summary()
```

```
# In[8]:
```

```
#Compiling the model
```

```
# Compiling the CNN
```

```
# categorical_crossentropy for more than 2
```

```
classifier.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
```

```
# In[10]:
```

```
# Save the model
```

```
classifier.save('disaster.h5')
```

```
model_json = classifier.to_json()
```

```
with open("model-bw.json", "w") as json_file:
```

```
    json_file.write(model_json)
```

```
# In[21]:
```

```
from tensorflow.keras.models import load_model
```

```
from keras.preprocessing import image
```

```
model = load_model("disaster.h5") #Loading the model
```

```
# In[14]:
```

```
from tensorflow.keras.preprocessing import image
```

```
import numpy as np
```

```
img = image.load_img('/content/dataset/test_set/Flood/1009.jpg', target_size=(64,64))
```

```
img
```

```
#Loading of the image
```

```
# In[13]:
```

```
x= image.img_to_array(img)
```

```
x
```

```
#image to array
```

```
# In[15]:
```

```
x = np.expand_dims(x,axis = 0)
```

```
x
```

```
#changing the shape
```

```
# In[16]:
```

```
from tensorflow.keras.preprocessing import image
```

```
import numpy as np
```

```
img = image.load_img('/content/dataset/test_set/Flood/1009.jpg', target_size=(64,64))
```

```
x= image.img_to_array(img)
```

```
x = np.expand_dims(x,axis = 0)
```

```
pred = np.argmax(model.predict(x))
```

```
Output=['earthquake','cyclone','flood','wildfire']
```

```
Output[pred]
```

```
#predicting the class
```

```
# In[ ]:
```

```
get_ipython().system('pip install flask')
```

```
from flask import Flask, render_template, request
```

```
# Flask-It is our framework which we are going to use to r #request-for accessing file which was  
uploaded by the user #import operator
```

```
import cv2
```

```
# opencv library
```

```
from tensorflow.keras.models import load_model
```

```
#to load our
```

```
import numpy as np
```

```
#import os
```

```
from werkzeug.utils import secure_filename
```

```
app = Flask(__name__)
```



```

template_folder="templates"

# initializ # Loading the model
model=load_model('disaster.h5')
print("Loaded model from disk")


@app.route('/', methods=['GET'])
def index():
    return render_template('home.html')

@app.route('/home', methods=['GET'])
def home():
    return render_template('home.html') @app.route('/intro', methods=['GET'])
def about():
    return render_template('intro.html')

@app.route('/upload', methods=['GET', 'POST'])
def predict():
    cap= cv2.VideoCapture (0)
while True:
    cap= cv2.VideoCapture (0)
    _, frame = cap.read()
    #capturing the video frame values #Simulating mirror image
    frame = cv2.flip(frame, 1)

#Loop over frames from the video file stream
    while True:
        # read the next frame from the file

```

```

    (grabbed, frame) = cap.read()

# if the frame was not grabbed, then we have reach # of the stream

    if not grabbed:
        break

# if the frame dimensions are empty, grab them

    if W is None or H is None:

        (H, W) = frame.shape[:2]

# clone the output frame, then convert it from BGR # ordering and resize the frame to a fixed
224x224

    output = frame.copy()

    frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)

    frame = cv2.resize(frame, (64, 64))

    #frame = frame.astype("float32")

    x=np.expand_dims (frame, axis=0)

    result = np.argmax (model.predict(x), axis=-1)

```

```
index=['Cyclone', 'Earthquake', 'Flood', 'Wildfire']
```

```
result=str(index[result[0]])
```

```
#print (result)
```

```
#result=result.tolist()
```

```
cv2.putText(output, "activity: {}".format(result), (10, 120), cv2.FONT_HERSHEY_PLAIN, 1,  
(0,255,255), 1)
```

```
#playaudio ("Emergency it is a disaster")
```

```
cv2.imshow("Output", output)
```

```
key = cv2.waitKey(1) & 0xFF
```

```
# if the 'q' key was pressed, break from the loop
```

```
if key == ord("q"):
```

```
    break
```

```
# release the file pointers
```

```
print("[INFO] cleaning up...")
```

```
vs.release()
```

```
return render_template("upload.html")
```

```
if __name__ == "__main__":
```

```
    app.run(host='0.0.0.0', port=8000, debug=False)
```

# In[ ]: