IBM ASSIGNMENT-4

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sketch.ino

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
#define ECHO_PIN 2
#define TRIG_PIN 4
#define LED 5
//----credentials of IBM Accounts-----
#define ORG "hb4ofc"//IBM ORGANITION ID
#define DEVICE_TYPE "Device_1"//Device type mentioned in ibm watson IOT Platform
#define DEVICE ID "1001"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "10000001"
                            //Token
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event
perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
```

```
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, wifiClient); //calling the predefined client id
by passing parameter like server id, portand wificredential
void setup()// configureing the ESP32
{
  Serial.begin(115200);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
  pinMode(LED,OUTPUT);
 delay(10);
  Serial.println();
 wificonnect();
 mqttconnect();
}
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
}
```

```
void loop()// Recursive Function
{
 float distance = readDistanceCM();
 bool isNearby = distance < 100;</pre>
 digitalWrite(LED, isNearby);
  Serial.print("Measured distance: ");
 Serial.println(distance);
 delay(100);
 if (isNearby == 1){
 PublishData(distance);
  }
 delay(1000);
 if (!client.loop()) {
   mqttconnect();
 }
}
/*....retrieving to
Cloud....*/
void PublishData(float distance) {
 mqttconnect();//function call for connecting to ibm
 /*
    creating the String in in form JSon to update the data to ibm cloud
  */
  String payload = "{\"Alert\":""\"";
 payload += distance;
 payload += " is less than 100cms\"";
  payload += "}";
```

```
Serial.print("Sending payload: ");
  Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud
then it will print publish ok in Serial monitor or else it will print publish
failed
  } else {
   Serial.println("Publish failed");
  }
}
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
     initManagedDevice();
     Serial.println();
  }
}
```

```
void wificonnect() //function defination for wificonnect
  Serial.println();
  Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
the connection
 while (WiFi.status() != WL_CONNECTED) {
    delay(500);
   Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
```

diagram.json

```
{
  "version": 1,
  "author": "A Rahul Ebenezer A",
  "editor": "wokwi",
  "parts": [
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -17.57, "left": -
116.71, "attrs": {} },
   {
      "type": "wokwi-led",
      "id": "led1",
      "top": -16.04,
      "left": 21.83,
      "attrs": { "color": "red" }
    },
      "type": "wokwi-resistor",
      "id": "r1",
      "top": 41.63,
      "left": 48.17,
      "attrs": { "value": "1000" }
   },
    { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": -69.2, "left": 151.85,
"attrs": {} }
  ],
```

```
"connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [] ],
    [ "led1:A", "r1:1", "green", [ "v0" ] ],
    [ "r1:2", "esp:D5", "green", [ "v0" ] ],
    [ "led1:C", "esp:GND.1", "black", [ "v0" ] ],
    [ "esp:D4", "ultrasonic1:TRIG", "green", [ "h246.49", "v-79.83" ] ],
    [ "esp:D2", "ultrasonic1:ECHO", "green", [ "h0" ] ],
    [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h262.72", "v-104.77" ] ],
    [ "ultrasonic1:VCC", "esp:3V3", "red", [ "v0" ] ]
]
}
libraries.txt
# Wokwi Library List
# See https://docs.wokwi.com/guides/libraries
```

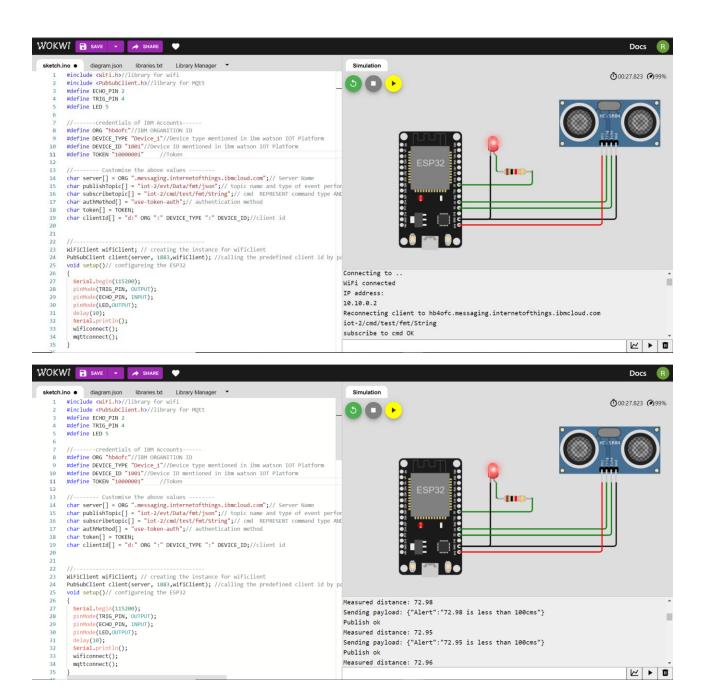
" See Heeps.,, does.wokwi

Automatically added based on includes:

PubSubClient

ArduinoJson

PICTURE:



LINK:

https://wokwi.com/projects/346493354999022162

CLOUD OUTPUT:

