FINAL CODE:

```
import time
import sys
import ibmiotf.application
import ibmiotf.device
import random
organization="ckuumt"
devicetype="zxcv"
deviceid="0987"
authMethod="token"
authToken="1234567891"
def myCommandCallback(cmd):
  print("Command received:%s"%cmd.data['command'])
  status=cmd.data['command']
  if status =="lighton":
    print("led in on")
  else:
      print("led is off")
try:
  deviceOptions={"org":organization,"type":devicetype,"id":deviceid,"auth-
method":authMethod,"auth-token":authToken}
  deviceCli=ibmiotf.device.Client(deviceOptions)
except Exception as e:
  print("Caught exception connecting device:%s"%str(e))
  sys.exit()
deviceCli.connect()
while True:
  time.sleep(5)
  Ultrasonic=random.randint(0,80)
```

```
Weight=random.randint(0,100)

lat=round(random.uniform(11.03,11.50),6)

long=round(random.uniform(76.80,76.90),6)

GPS=str(lat)+str(',')+str(long)

myData={'Ultrasonic':Ultrasonic,'Weight':Weight,'GPS':GPS}

def myOnpublishCallback():

print("Published Ultrasonic=%sCm"%Ultrasonic,"Weight:%s kg"%Weight,"GPS:%s"%GPS)

success=deviceCli.publishEvent("IoTSensor","json",data=myData,qos=0,on_publish=myOnpublishCallback)

if not success:

print("Not connected to IoTF")

time.sleep(1)

deviceCli.commandCallback=myCommandCallback

deviceCli.disconnect()
```

FINAL OUTPUT:











