ASSINGNMENT-IV

DISTANCE DETECTION USING ULTRASONIC SENSOR

Team Id	PNT2022TMID46638
Assignment date	29 Oct 2022
Project Name	Hazardous area monitoring for
	industrial plant powered by IOT
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100

cms send "alert" to ibm cloud and display in device recent events.

CODE:

```
#include <WiFi.h>
#include < PubSubClient.h >
WiFiClient wifiClient;
String data3;
#define ORG "co65hn"
#define DEVICE TYPE "ManiMD"
#define DEVICE ID "manimd07"
#define TOKEN "0708012359"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/manimd/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
```

```
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
    Serial.begin(115200);
         pinMode(led, OUTPUT);
         pinMode(trigpin, OUTPUT);
    wifiConnect();
         mqttConnect();
}
void loop() {
    bool isNearby = dist < 100;
     digitalWrite(led, isNearby);
    publishData();
    delay(500);
    if (!client.loop()) {
       mqttConnect();
     }
}
void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
      WiFi.begin("Wokwi-GUEST", "", 6);
```

```
while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
 }
                 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
      Serial.print("Reconnecting MQTT client to "); Serial.println(server);
      while (!client.connect(clientId, authMethod, token)) {
         Serial.print(".");
         delay(500);
      }
  }
  initManagedDevice();
  Serial.println();
}
void initManagedDevice() {
   if (client.subscribe(topic)) {
      // Serial.println(client.subscribe(topic));
      Serial.println("IBM subscribe to cmd OK");
   } else {
      Serial.println("subscribe to cmd FAILED");
   }
}
void publishData()
{
   digitalWrite(trigpin,LOW);
   digitalWrite(trigpin,HIGH);
   delayMicroseconds(10);
```

```
digitalWrite(trigpin,LOW);
   duration=pulseIn(echopin,HIGH);
   dist=duration*speed/2;
   if(dist<100){
        String payload = "{\"Alert Distance\":";
        payload += dist;
        payload += "}";
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {
           Serial.println("Publish OK");
        }
}
       if(dist>100){
       String payload = "{\"Distance\":";
       payload += dist;
       payload += "}";
       Serial.print("\n");
       Serial.print("Sending payload: ");
       Serial.println(payload);
         if(client.publish(publishTopic, (char*) payload.c str())) {
            Serial.println("Publish OK");
       }else {
         Serial.println("Publish FAILED");
       }
}
  }
```

OUTPUT



when object is near to the ultrasonic sensor



