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Project	IOT BASED SMART CROP
	PROTECTION SYSTEM FOR
	AGRICULTURE

Utilization of algorithm ,dynamic programming,optimization

dynamic programming is an optimization approach that transforms a complex problem into a sequence of simpler problems; its essential characteristic is the multistage nature of the optimization procedure. More so than the optimization techniques described previously, dynamic programming provides a general frameworkfor analyzing many problem types. Within this framework a variety of optimization techniques can be employed to solve particular aspects of a more general formulation. Usually creativity is required before we can recognize that a particular problem can be cast effectively as a dynamic program; and often subtle insights are necessary to resigure 11.1 Street map with intersection delays.

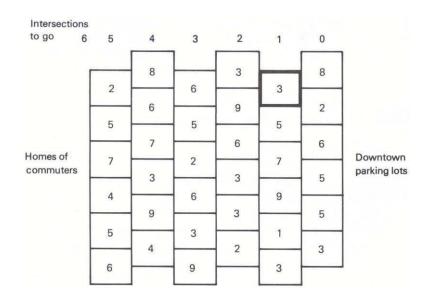


Figure 11.2 Compact representation of the network.

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Algorithm 2: AR-TO-BE CONVERSION ALGORITHM if scheduling lease type= = Immediate lease then: if resources required are available at the time then: allocate resources to Immediate lease else reject Immediate lease and print message else if scheduling lease type= = BE then: Queue BE lease and set state of lease to queue. if scheduling lease type= =AR then: if no AR lease is running on required time slot & resources are free then: allocate resources to AR else if AR not getting resources & going to be rejected by the scheduler then: Provide dynamic choice for AR lease convertible to BE lease if accepted then: convert this AR to BE, queue BE lease and set state of lease to queue else reject AR. else if scheduling lease type== DLS then: slack=(deadline-start time) / duration if slack < 1.1 then reject lease and print message to extend dead line or submit lease as AR lease else find a single time slot which can satisfy complete lease within deadline if new lease is not schedulable as above then: find multiple slots which together can satisfy this if new lease is not schedulable by any of the above methods then: find leases to be rescheduled & reschedule deadline leases else reject new lease & print message else print message invalid lease type

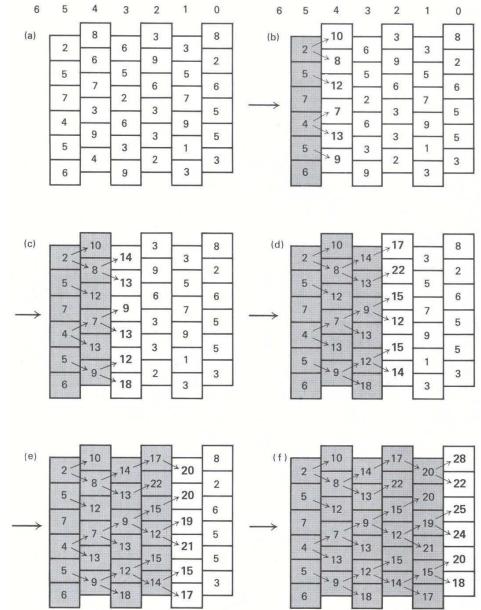


Figure 11.6 Solution by forward induction.

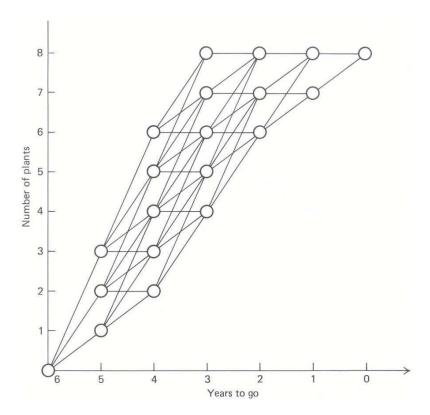


Figure 11.8 Allowable capacity (states) for each tage

plus the plant costs, which depend upon the year of construction and whether 1, 2, or 3 plants are completed. Measured in thousands of dollars, these costs are

$$1500 + c_n x_{n_r}$$

the one additional plant is the \$1500 common cost plus the \$5200 cost per plant, for a total of \$6700. (All costs are measured in thousands of

dollars.) The column headed $d_{1*}(s_1)$ gives the optimal decision function, which specifies the optimal number of plants to construct, given the current state of the system.

Now let us consider what action we should take with two years (stages) to go. Tableau 2 indicates the possible costs of each state:

Tah	lean	1To	hlea

S_2	0	1	2	$v_{2}(s_{2})$	$d_2^*(s_2)$
8	0	_	-	0	0
7	6,700	7,000	_	6,700	0
6	_	13,700	12,500	12,500	2