

## ASSIGNMENT 4

### PYTHON PROGRAMMING

ASSIGNMENT DATE	17 OCTOBER 2022
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MAXIMUM MARKS	2

Question:

Write code and connections in wowki for ultrasonic sensor. Whenever distance is less than 100cms send “alert” to IBM cloud and display in device recent events.

Program Code:

```
#include <WiFi.h> //library for wifi

#include <PubSubClient.h> //library for MQTT

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

// credentials of IBM Accounts

#define ORG "n6rl9n"//IBM Organition ID

#define DEVICE_TYPE "ElangoIoT"//Device type mentioned in ibm watson IOT
Platform

#define DEVICE_ID "06112002"//Device ID mentioned in ibm watson IOT Platform

#define TOKEN "98765432" //Token

String data3;

// Customise the above values

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name

char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event

perform and format in which data to be send
```

```

char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;// client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the
predefined client id by passing parameter like server id,portand wificredential

const int trigpin = 5;
const int echopin = 18;
const int ledpin = 2;
long duration ;
float distance;
#define sound_speed 0.034
void setup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, OUTPUT);
  pinMode(ledpin, OUTPUT);
  wificonnect();
  mqttconnect();
}
void loop()
{

```

```
digitalWrite(trigpin, LOW);  
digitalWrite(trigpin, HIGH);  
delayMicroseconds(10);  
digitalWrite(trigpin, LOW);  
duration= pulseIn(echopin,HIGH);  
distance = duration * sound_speed /2;  
if(distance<=100)  
{  
  PublishData(distance);  
  delay(1000);  
  if (!client.loop())  
  {  
    mqttconnect();  
  }  
  digitalWrite(ledpin, HIGH);  
  Serial.println("Alert !!");  
  Serial.println(distance);  
}  
else  
{  
  digitalWrite(ledpin, LOW);  
}  
delay(10); // this speeds up the simulation  
}  
  
// Retrieving to Cloud
```

```

void PublishData(float distance)
{
    mqttconnect();// Function call for connecting to ibm

    // creating the String in in form JSon to update the data to ibm cloud
    String payload = "{\"Alert !! \": ";
    payload += distance;
    payload += "}";
    Serial.print("Sending payload : ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str()))
    {
        Serial.println("Publish ok");// If it sucessfully upload data on the cloud
        then it will print publish ok in Serial monitor or else it will print publish
        failed
    }
    else
    {
        Serial.println("Publish failed");
    }
}

void mqttconnect()
{
    if (!client.connected())
    {

```

```
Serial.print("Reconnecting client to ");

Serial.println(server);

while (!client.connect(clientId, authMethod, token))

{

Serial.print(".");

delay(500);

}

initManagedDevice();

Serial.println();

}

}

void wificonnect() // Function defination for wificonnect

{

Serial.println();

Serial.print("Connecting to ");

WiFi.begin("Wokwi-GUEST", "", 6); // Passing the wifi credentials to establish

the connection

while (WiFi.status() != WL_CONNECTED)

{

delay(500);

Serial.print(".");

}

Serial.println("");

Serial.println("WiFi connected");

Serial.println("IP address: ");
```

```
Serial.println(WiFi.localIP());

}

void initManagedDevice()
{
  if (client.subscribe(subscribetopic))
  {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  }
  else
  {
    Serial.println("subscribe to cmd FAILED");
  }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++)
  {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3);
}
```

```
if(data3=="lighton")  
{  
  Serial.println(data3);  
}  
else  
{  
  Serial.println(data3);  
}  
data3="";  
}
```









