# ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	1 <sup>st</sup> November 2022
Team ID	PNT2022TMID24214
Name & Register Number	Karna. Mounika (111419106049)
Mark	2Marks

### Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events

#### **CODE**:

```
esp32-blink.ino ● diagram.json ●
                                   libraries.txt •
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo, INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
          mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
| creating the String in in form JSon to update the data to ibm cloud
| ''/
| String object;
| if (dist <100) |
| digitalWrite(LED,HIGH);
| Serial.println("object is near");
| object = "Near";
| digitalWrite(LED,LOW);
| Serial.println("no object found");
| object = "No";
| }
| String payload = "(\"distance\":";
| payload += dist;
| payload += object\":\"";
| payload += object\":\"";
| payload += "\"";
| Serial.println(payload);
| Serial.println(payload);
```

```
dagram.gon | biraries.tot | Library.Manager |

fi (client.publish(publishTopic, (char*) payload.c_str())) {

serial.println("publish ok");// if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed |

serial.println("publish failed");

} else {

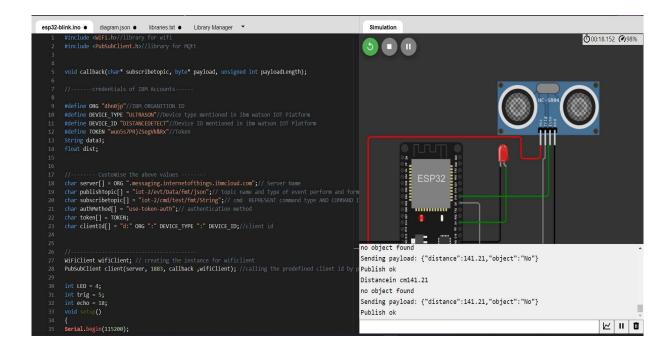
serial.println("publish failed");
}

fi (client.connected()) {

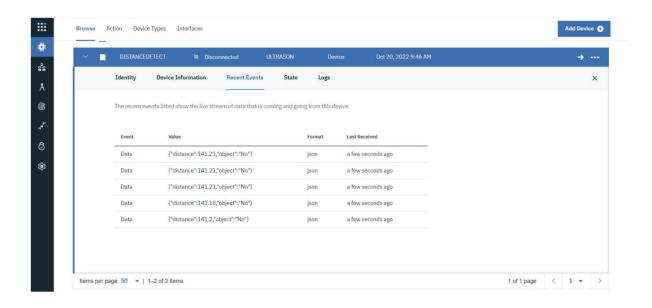
if (client.connec
```

```
esp32-blink.ino
                    diagram.json •
                                       libraries.txt ●
                                                       Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL_CONNECTED) {
            delay(500);
            Serial.print(".");
          Serial.println("");
          Serial.println("WiFi connected");
          Serial.println("IP address: ");
Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
            Serial.println("subscribe to cmd FAILED");
        void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {
   //Serial.print((char)payload[i]);</pre>
            data3 += (char)payload[i];
```

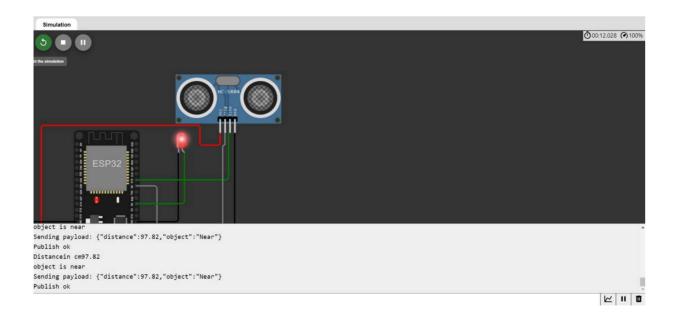
#### **OUTPUT**:



## Data send to the IBM cloud device when the object is far



## When object is near to the ultrasonic sensor



## Data sent to the IBM Cloud Device when the object is near

