## **ASSINGNMENT-IV**

Team ID	PNT2002TMID46618
Student Name	Vijayalakshmi.V
Student Roll Number	821019104051
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## **CODE:**

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "co65hn"
#define DEVICE_TYPE "ManiMD"
#define DEVICE_ID "manimd07"
#define TOKEN "0708012359"
#define speed 0.034 #define led 14 char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/manimd/fmt/json"; char topic[] = "iot-
2/cmd/led/fmt/String"; char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup() {
```

```
Serial.begin(115200);
         pinMode(led, OUTPUT);
         pinMode(trigpin, OUTPUT);
    wifiConnect();
         mqttConnect();
} void loop() { bool isNearby =
dist < 100; digitalWrite(led,
isNearby);
     publishData();
     delay(500);
     if (!client.loop()) {
       mqttConnect();
    }
}
void wifiConnect() {
     Serial.print("Connecting to "); Serial.print("Wifi");
      WiFi.begin("Wokwi-GUEST", "", 6);
      while (WiFi.status() != WL_CONNECTED) {
          delay(500);
          Serial.print(".");
 }
                 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
} void mqttConnect()
{
  if (!client.connected()) {
```

```
Serial.print("Reconnecting MQTT client to ");
      Serial.println(server); while (!client.connect(clientId, authMethod,
      token)) { Serial.print("."); delay(500);
      }
  }
  initManagedDevice();
  Serial.println();
 }
}
void initManagedDevice() { if
   (client.subscribe(topic)) {
      // Serial.println(client.subscribe(topic));
      Serial.println("IBM subscribe to cmd OK");
    } else {
      Serial.println("subscribe to cmd FAILED");
   } } void
publishData()
{ digitalWrite(trigpin,LOW);
   digitalWrite(trigpin,HIGH);
   delayMicroseconds(10);
   digitalWrite(trigpin,LOW);
   duration=pulseIn(echopin,
   HIGH);
   dist=duration*speed/2;
   if(dist<100){
        String payload = "{\"Alert
        Distance\":"; payload += dist; payload
        +="}";
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    }
} if(dist>100){
        String payload = "{\"Distance\":";
        payload += dist; payload += "}";
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload); if(client.publish(publishTopic, (char*) payload.c_str())) {        Serial.println("Publish OK");
        }else {
            Serial.println("Publish FAILED");
        }
}
```

## OUTPUT



## when object is near to the ultrasonic sensor



