ASSINGNMENT-IV

| Team ID | PNT2002TMID46618 |
|---------------------|------------------|
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CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "co65hn"
#define DEVICE_TYPE "ManiMD"
#define DEVICE_ID "manimd07"
#define TOKEN "0708012359"
#define speed 0.034 #define led 14 char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/manimd/fmt/json"; char topic[] =
"iot2/cmd/led/fmt/String"; char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5; const int echopin=18;
String command; String data="";
long duration;
float dist; void
setup() {
Serial.begin(1
15200);
```

```
pinMode(led,
OUTPUT);
pinMode(trigp
in, OUTPUT);
    wifiConnect();
mqttConnect(); } void loop() {
bool is Nearby = dist < 100;
digitalWrite(led, isNearby);
     publishData();
     delay(500);
     if (!client.loop()) {
       mqttConnect();
     } }
void wifiConnect() {
     Serial.print("Connecting to "); Serial.print("Wifi");
      WiFi.begin("Wokwi-GUEST", "", 6); while
      (WiFi.status() != WL_CONNECTED) {
      delay(500);
           Serial.print(".");
 }
                 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
} void mqttConnect()
{ if (!client.connected()) {
  Serial.print("Reconnect
  ing MQTT client to ");
```

```
Serial.println(server); while (!client.connect(clientId, authMethod,
      token)) { Serial.print("."); delay(500);
       }
   }
  initManagedDevice();
  Serial.println();
 } }
void initManagedDevice() { if
    (client.subscribe(topic)) {
      // Serial.println(client.subscribe(topic));
      Serial.println("IBM subscribe to cmd OK"); }
    else {
      Serial.println("subscribe to cmd FAILED");
    } } void publishData()
{ digitalWrite(trigpin,LOW);
   digitalWrite(trigpin,HIGH);
   delayMicroseconds(10);
   digitalWrite(trigpin,LOW);
   duration=pulseIn(echopin,
   HIGH); dist=duration*speed/2;
   if(dist<100){
         String payload = "{\"Alert Distance\":";
         payload += dist; payload
         +="}";
         Serial.print("\n");
         Serial.print("Sending payload: ");
         Serial.println(payload);
         if (client.publish(publishTopic, (char*) payload.c_str())) {
           Serial.println("Publish OK");
         }
} if(dist>100){
```

```
String payload = "{\"Distance\":"; payload
       += dist; payload += "}";
       Serial.print("\n");
       Serial.print("Sending payload: ");
       Serial.println(payload); if(client.publish(publishTopic,
       (char*) payload.c_str())) { Serial.println("Publish OK");
       }else {
         Serial.println("Publish FAILED");
       }
}
```

OUTPUT



when object is near to the ultrasonic sensor



