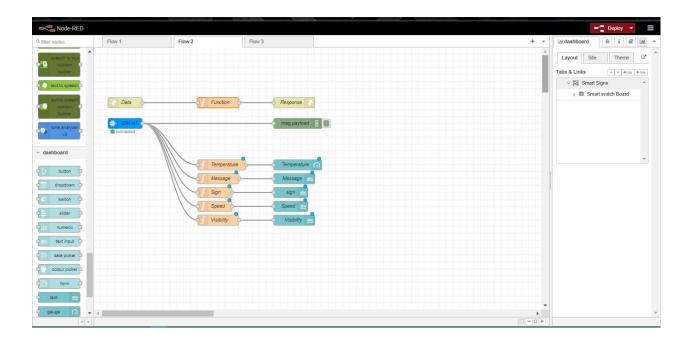
PROJECT DEVELOPMENT PHASE

Sprint-4

Team ID	PNT2022TMID29479
Project	SIGNS WITH SMART CONNECTIVITY FOR BETTER ROAD SAFETY
Batch	B2-2M4E

DEVELOPING ROUTE BASED ON THE PROGRAM:

Here based on the project the routing is developed by using appropriate nodes.

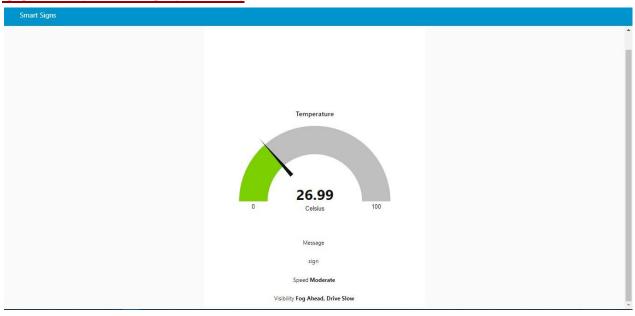


OUTPUT FOR NODE RED:

After making the proper connection between nodes the deploybutton is enabled and the result is displayed on the node-red dashboard.

It shows the result in a diagrammatic structure.

CODE IN PYTHON IDLE:



PROGRAM:

```
### Continue with the processing of the process of
```

Program used in the code:

import wiotp.sdk.device import time

```
import random
import ibmiotf.application
import ibmiotf.device
import requests, json
myConfig = {
  #Configuration
  "identity": {
     "orgId": "xfxok9",
     "typeId": "NodeMCU",
     "deviceId": "6385476358"
  },
  #API Key
  "auth": {
     "token": "9384731286"
  }
}
def myCommandCallback(cmd):
  print("Message received from IBM IoT Platform: %s" %
cmd.data['command'])
  m=cmd.data['command']
client = wiotp.sdk.device.DeviceClient(config=myConfig,logHandlers=None)
client.connect()
#OpenWeatherMap Credentials
BASE_URL =
"https://api.openweathermap.org/data/2.5/weather?"
```

```
CITY = "Chennai"
URL = BASE_URL + "q=" + "chennai" + "&appid=" +
"01df65417ab3968e3fc2a38c4aee27bb"
while True:
  response = requests.get(URL)
  if response.status_code == 200:data
    = response.json()
    main = data['main']
    temperature = main['temp']
    humidity = main['humidity']
    pressure = main['pressure']
    report = data['visibility']
    #messge part
    msg=random.randint(0,5)if
    msg==1:
      message="SLOW DOWN, SCHOOL IS NEAR"
    elif msg==3:
      message="SLOW DOWN, HOSPITAL NEARBY"
    elif msg==5:
      message="NEED HELP, POLICE STATION NEARBY"
    else:
      message=""
    #Speed part
    speed=random.randint(0,150)if
    speed>=100:
      speedMsg="SLOW DOWN, Speed Limit Exceeded"elif
    speed>=60 and speed<100:
```

```
speedMsg="Moderate Speed"
    else:
        speedMsg=""
     #Sign part
    sign=random.randint(0,5)if
    sign==1:
       signMsg="Right Diversion ->"
    elif sign==3:
       signMsg="Left Diversion <-"
    elif sign==5:
       signmsg="U Turn"
    else:
        signMsg=""
     #Visibility
    if temperature<=50:
       visibility="Fog Ahead, Drive Slow"else:
        visibility="Clear Weather"
  else:
    print("Error in the HTTP request") myData={'Temperature':temperature,
  'Message':message,
'Sign':signMsg, 'Speed':speedMsg, 'Visibility':visibility}
  client.publishEvent(eventId="status", msgFormat="json",
data=myData, qos=0, onPublish=None) print("Published
  data Successfully: %s", myData)
  client.commandCallback = myCommandCallback
  time.sleep(5)
```

client.disconnect()

Output displayed in Python Idle:

```
File Edit Shell Debug Options Window Help
Published data Successfully: %s ('Temperature': 300.14, 'Message': '', 'Sign': '', 'Speed': 'SLOW DOWN , Speed Limit Exceeded', 'Visibility': 'Clear Weather')
Published data Successfully: %s ('Temperature': 300.14, 'Message': '', 'Sign': '', 'Speed': 'SLOW DOWN , Speed Limit Exceeded', 'Visibility': 'Clear Weather')
Published data Successfully: %s ('Temperature': 300.14, 'Message': 'NEED HELP, POLICE STATION NEARBY', 'Sign': 'Left Diversion <-', 'Speed': 'Moderate Speed', 'Visibil
 ity': 'Clear Weather')
Published data Successfully: %s ('Temperature': 300.14, 'Message': 'SLOW DOWN , HOSPITAL NEARBY', 'Sign': '', 'Speed': 'SLOW DOWN , Speed Limit Exceeded', 'Visibility': 'Clear Weather')
: 'Clear Weather')
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Published data Successfully: %s ('Temperature': 300.14, 'Message': 'SLOW DOWN, SPeed Limit Exceeded', 'Visibility': 'Clear Weather')
   Clear Weather'}
   Clear Weather'
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 . Great weather ;
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                    d data Successfully: %s ('Temperature': 300.14, 'Message': 'SLOW DOWN , SCHOOL IS NEAR', 'Sign': '', 'Speed': 'SLOW DOWN , Speed Limit Exceeded', 'Visibility':
   Clear Weather'
                                                                                                                                                                                                                                                                                                                                                                                                            Ln: 205 Col: 0
```

The output of the code was displayed in python idle shellmode.