Project Development Phase Sprint-4

Date	11 November 2022
Team ID	PNT2022TMID24074
Project Name	Virtual Eye - Life Guard for
	Swimming Pools to Detect
	Active Drowning
Maximum Marks	8 Marks

Source Code:

```
import re
import numpy as np
import os
from flask import Flask, app,request,render_template
from tensorflow.keras import models
from tensorflow.keras.models import load model
from tensorflow.keras.preprocessing import image
from tensorflow.python.ops.gen_array_ops import concat
from tensorflow.keras.applications.inception_v3 import preprocess_input
import cvlib as cv
from cvlib.object_detection import draw_bbox
import cv2
import time
import numpy as np
from playsound import playsound
import requests
from flask import Flask, request, render_template, redirect, url_for
#Loading the model
from cloudant.client import Cloudant
# Authenticate using an IAM API key
client = Cloudant.iam('2eb40045-a8d6-450d-9d24-52cc7cbb2810-
bluemix','Ud0wunTPOI_8h5ZtEqi1IXk1gIKeYLmpUsCn0Ee08T4z', connect=True)
# Create a database using an initialized client
my_database = client.create_database('my_database')
app=Flask(__name___)
#default home page or route
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```
@app.route('/')
def index():
    return render template('index.html')
@app.route('/index.html')
def home():
    return render_template("index.html")
#registration page
@app.route('/register')
def register():
    return render_template('register.html')
@app.route('/afterreg', methods=['POST'])
def afterreg():
    x = [x for x in request.form.values()]
    print(x)
    data = {
    '_id': x[1], # Setting _id is optional
    'name': x[0],
    'psw':x[2]
    print(data)
    query = {'_id': {'$eq': data['_id']}}
    docs = my_database.get_query_result(query)
    print(docs)
    print(len(docs.all()))
    if(len(docs.all())==0):
        url = my database.create document(data)
        #response = requests.get(url)
        return render_template('register.html', pred="Registration Successful,
please login using your details")
    else:
        return render_template('register.html', pred="You are already a
member, please login using your details")
@app.route('/login')
def login():
    return render_template('login.html')
@app.route('/afterlogin',methods=['POST'])
```

```
def afterlogin():
    user = request.form[' id']
    passw = request.form['psw']
    print(user,passw)
    query = {'_id': {'$eq': user}}
    docs = my_database.get_query_result(query)
    print(docs)
    print(len(docs.all()))
    if(len(docs.all())==0):
        return render_template('login.html', pred="The username is not
found.")
    else:
        if((user==docs[0][0][' id'] and passw==docs[0][0]['psw'])):
            return redirect(url_for('prediction'))
        else:
            print('Invalid User')
@app.route('/logout')
def logout():
    return render_template('logout.html')
@app.route('/prediction')
def prediction():
    return render template('prediction.html')
@app.route('/result',methods=["GET","POST"])
def res():
    webcam = cv2.VideoCapture('drowning.mp4')
    if not webcam.isOpened():
        print("Could not open webcam")
        exit()
    t0 = time.time() #gives time in seconds after 1970
still for
    centre0 = np.zeros(2)
    isDrowning = False
    #this loop happens approximately every 1 second, so if a person doesn't
move,
```

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#or moves very little for 10seconds, we can say they are drowning
   #loop through frames
   while webcam.isOpened():
       # read frame from webcam
       status, frame = webcam.read()
       if not status:
           print("Could not read frame")
           exit()
       # apply object detection
       bbox, label, conf = cv.detect_common_objects(frame)
       #simplifying for only 1 person
       if(len(bbox)>0):
           bbox0 = bbox[0]
           #centre = np.zeros(s)
           centre = [0,0]
           #for i in range(0, len(bbox)):
               #centre[i]
=[(bbox[i][0]+bbox[i][2])/2,(bbox[i][1]+bbox[i][3])/2 ]
           centre = [(bbox0[0]+bbox0[2])/2,(bbox0[1]+bbox0[3])/2]
           #make vertical and horizontal movement variables
           hmov = abs(centre[0]-centre0[0])
           vmov = abs(centre[1]-centre0[1])
           #there is still need to tweek the threshold
           #this threshold is for checking how much the centre has moved
           x=time.time()
           threshold = 10
           if(hmov>threshold or vmov>threshold):
               print(x-t0, 's')
               t0 = time.time()
               isDrowning = False
           else:
               print(x-t0, 's')
               if((time.time() - t0) > 10):
                   isDrowning = True
```

```
#print('bounding box: ', bbox, 'label: ' label ,'confidence: '
conf[0], 'centre: ', centre)
            #print(bbox,label ,conf, centre)
            print('bbox: ', bbox, 'centre:', centre, 'centre0:', centre0)
            print('Is he drowning: ', isDrowning)
            centre0 = centre
            # draw bounding box over detected objects
        out = draw_bbox(frame, bbox, label, conf,isDrowning)
        #print('Seconds since last epoch: ', time.time()-t0)
        # display output
        cv2.imshow("Real-time object detection", out)
        if(isDrowning == True):
            playsound('alarm.mp3')
            webcam.release()
            cv2.destroyAllWindows()
            return render_template('prediction.html',prediction="Emergency !!!
The Person is drowining")
        if cv2.waitKey(1) & 0xFF == ord('g'):
            break
    # release resources
    webcam.release()
    cv2.destroyAllWindows()
""" Running our application """
if __name__ == "__main__":
 app.run(debug=True)
```