

# **EMERGING METHODS FOR EARLY DETECTION OF FOREST FIRES**

## **VIDEO ANALYSIS**

### **OPEN CV FOR VIDEO PROCESSING**

<b>Date</b>	04 November 2022
<b>Team ID</b>	PNT2022TMID37860
<b>Project Name</b>	Emerging Methods for Early Detection of Forest Fires

***Importing The ImageDataGenerator Library*** import keras from  
keras.preprocessing.image import ImageDataGenerator ***Define the  
parameters/arguments for ImageDataGenerator class***  
train\_datagen=ImageDataGenerator(rescale=1./255,shear\_range=0.  
2,rotation\_range=180,zoom\_range=0.2, horizontal\_flip=True)  
test\_datagen=ImageDataGenerator(rescale=1./255) ***Applying  
ImageDataGenerator functionality to trainset***  
x\_train=train\_datagen.flow\_from\_directory(r'/content/drive/MyDri

```
ve/ Dataset/Train_set',target_size=(128,128),batch_size=32,  
class_mode='binary')
```

Found 436 images belonging to 2 classes.

### ***Applying ImageDataGenerator functionality to testset***

```
x_test=test_datagen.flow_from_directory(r'/content/drive/MyDrive  
/ Dataset/Test_set',target_size=(128,128),batch_size=32,  
class_mode='binary')
```

Found 121 images belonging to 2 classes.

### ***Import model building libraries***

```
#To define Linear initialisation import Sequential  
from keras.models import Sequential #To add  
layers import Dense from keras.layers import  
Dense  
#To create Convolution kernel import Convolution2D  
from keras.layers import Convolution2D  
#import Maxpooling layer  
from keras.layers import MaxPooling2D  
#import flatten layer from  
keras.layers import Flatten  
import warnings  
warnings.filterwarnings('ignore'  
)
```

### ***Initializing the model***

```
model=Sequential()
```

### ***Add CNN Layer***

```
model.add(Convolution2D(32,  
(3,3),input_shape=(128,128,3),activation='relu'))
```

*#add maxpooling layer*

```
model.add(MaxPooling2D(pool_size=(2,2)))
```

*#add flatten layer*

```
model.add(Flatten()) Add Hidden  
Layer
```

*#add hidden layer* model.add(Dense(150,activation='relu'))

*#add output layer*

```
model.add(Dense(1,activation='sigmoid'))
```

**Configure the learning process**

```
model.compile(loss='binary_crossentropy',optimizer="adam",metrics=[  
"accuracy"])
```

**Train**

**the**

**model**

```
model.fit_generator(x_train,steps_per_epoch=14,epochs=10,validation_  
data=x_test,validation_steps=4)
```

Epoch 1/10

14/14 [=====] - 97s 7s/step - loss:  
1.3060 - accuracy: 0.7775 - val\_loss: 0.5513 -  
val\_accuracy: 0.8512

Epoch 2/10

14/14 [=====] - 26s 2s/step - loss:  
0.3178 - accuracy: 0.8807 - val\_loss: 0.1299 -  
val\_accuracy: 0.9421

Epoch 3/10

14/14 [=====] - 26s 2s/step - loss:  
0.2226 - accuracy: 0.9106 - val\_loss: 0.1311 -  
val\_accuracy: 0.9421

Epoch 4/10

14/14 [=====] - 31s 2s/step - loss:

0.1836 - accuracy: 0.9174 - val\_loss: 0.1129 -  
val\_accuracy: 0.9339  
Epoch 5/10  
14/14 [=====] - 30s 2s/step - loss:  
0.1675 -  
accuracy: 0.9243 - val\_loss: 0.0925 - val\_accuracy: 0.9669

Epoch 6/10  
14/14 [=====] - 26s 2s/step - loss:  
0.1884 - accuracy: 0.9289 - val\_loss: 0.1287 -  
val\_accuracy: 0.9339

Epoch 7/10  
14/14 [=====] - 28s 2s/step - loss:  
0.1724 - accuracy: 0.9335 - val\_loss: 0.0926 -  
val\_accuracy: 0.9752

Epoch 8/10  
14/14 [=====] - 26s 2s/step - loss:  
0.1510 - accuracy: 0.9404 - val\_loss: 0.0757 -  
val\_accuracy: 0.9752 Epoch 9/10

14/14 [=====] - 26s 0.173 -  
2s/step - loss: 2  
accuracy: 0.9174 - val\_loss: 0.0537 - val\_accuracy: 0.9835

Epoch 10/10  
14/14 [=====] - 26s 0.154 -  
2s/step - loss: 6  
accuracy: 0.9312 - val\_loss: 0.0573 - val\_accuracy: 0.9835  
<keras.callbacks.History at 0x7f05d66a9c90>

### ***Save The Model***

```
model.save("forest1.h5")
```

## **Predictions**

```
#import load_model
from keras.model from
keras.models import
load_model #import
image class from keras
from tensorflow.keras.preprocessing import image #import
numpy import numpy as np #import cv2 import cv2
#load the saved model model =
load_model("forest1.h5")
img=image.load_img(r'/content/drive/MyDrive/Dataset/
te st_set/forest/
0.48007200_1530881924_final_forest.jpg')
x=image.img_to_array(img) res =
cv2.resize(x, dsize=(128, 128),
interpolation=cv2.INTER_CUBIC)
#expand the image shape
x=np.expand_dims(res,axis=0)
pred= model.predict(x)

1/1 [=====] - 0s
126ms/step pred
array([[0.]],
dtype=float32) OpenCV
```

## **For Video Processing**

pip install twilio

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: twilio in  
/usr/local/lib/python3.7/dist-packages (7.15.1)

Requirement already satisfied: pytz in /usr/local/lib/python3.7/dist-packages (from twilio) (2022.5)

Requirement already satisfied: requests>=2.0.0 in /usr/local/lib/python3.7/dist-packages (from twilio) (2.23.0)

Requirement already satisfied: PyJWT<3.0.0,>=2.0.0 in /usr/local/lib/python3.7/dist-packages (from twilio) (2.6.0) Requirement already satisfied: urllib3!=1.25.0,!1.25.1,<1.26,>=1.21.1 in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (1.24.3)

Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (2022.9.24)

Requirement already satisfied: idna<3,>=2.5 in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (2.10)

Requirement already satisfied: chardet<4,>=3.0.2 in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (3.0.4)

pip install playsound

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: playsound in /usr/local/lib/python3.7/dist-packages (1.3.0)

*#import opencv library*

import cv2 *#import*

*numpy* import numpy

as np

*#import image function from keras*

from keras.preprocessing import

image *#import load\_model from*

*keras*

from keras.models import load\_model

*#import client from twilio API* from

twilio.rest import Client

```
#import playsound package from  
playsound import playsound
```

WARNING:playsound:playsound is relying on another python subprocess. Please use `pip install pygobject` if you want playsound to run more efficiently.

```
#load the saved model  
model=load_model("forest1.h  
5") #define video  
video=cv2.VideoCapture(0) #define  
the features name=['forest','with  
fire']
```