## **ASSIGNMENT 4**

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## **CODE:**

```
int t=2;
        int e=3;
void setup()
         Serial.begin(9600);
         pinMode(t,OUTPUT);
         pinMode(e,INPUT);
         pinMode(12,OUTPUT
        );
void loop()
         //ultrasonic sensor
         digitalWrite(t,LOW);
         digitalWrite(t,HIGH);
         delayMicroseconds(10);
         digitalWrite(t,LOW); float
         dur=pulseIn(e,HIGH); float
         dis=(dur*0.0343)/2;
        Serial.print("Distance is:
         "); Serial.println(dis);
         //LED ON if(dis>=100)
         { digitalWrite(8,HIGH
```

```
);
digitalWrite(7,HIGH
);
}

//Buzzer For ultrasonic Sensor
if(dis>=100) { for(int i=0;
i<=30000; i=i+10)
{ tone(12,i);
delay(1000);
noTone(12);
delay(1000);
}
```

