ASSIGNMENT-4

Ultrasonic sensor simulation in Wokwi

Date	29 October2022
Team ID	PNT2022TMID28837
project	SMART WASTE MANAGEMENT IN METROPOLITAN CITIES
Maximum Marks	2Marks

Question-1:

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

```
#include <WiFi.h>
#include
                <PubSubClient.h>
                                         void
callback(char*
                   subscribetopic,
                                        byte*
payload, unsigned int payloadLength);
#define ORG "Lotq5"
#define DEVICE TYPE "PSP32"
#define DEVICE_ID "WORKASSIGNMENT4"
#define TOKEN "345678" /
String data3;
charORG".messaging.internetofthings.ibmclou
d.com";
char publishTopic[] = "iot-
2/evt/Data/fmt/json";
char subscribetopic[] = "iot-
2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[]=TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin =5;
const int echoPin= 18;
#define SOUND SPEED 0.034 long
duration;
float distance;
 void setup() {
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
void loop() {
```

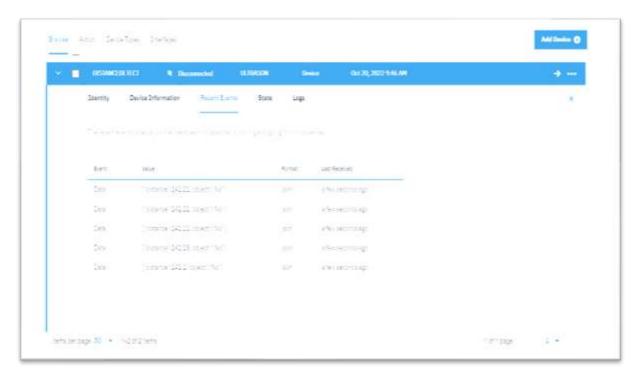
```
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
 duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND_SPEED/2;
Serial.print("Dista
nce (cm): ");
Serial.println(dist
ance);
if(distance<100)</pre>
Serial.println("ALE
RT!!");
delay(1000);
PublishData(distanc
e); delay(1000);
if (!client.loop())
mqttconnect();
}
}
delay(1000
);
} void
Serial.print("Reconnecting client to
");
Serial.println(server);
PublishDat a(float dist)
mqttconnect();
String payload = "{\"Distance\":"; payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than
100cms\""; payload += "}";
Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
}
else {
Serial.println("Publish failed");
}
}
void mqttconnect() {
(!client.connected()){
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod,
token)) { Serial.print("."); delay(500);
}
```

```
initManagedDevice();
Serial.println();
}
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() !=WL_CONNECTED)
{ d
elay(500);
Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() {
if(client.subscribe(subscribetopic))
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
}
else {
Serial.println("subscribe to cmd FAILED");
}
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
Serial.print("callback invoked for
topic:");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {</pre>
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
}
```

Diagram. json:

```
{
   "version": 1,
  "author": "Aravind",
   "editor": "wokwi",
   "parts": [
     { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67,
     "attrs": {} },
     { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17,
     "attrs": {} }
  ],
   "connections": [
     [ "esp:TX0", "$serialMonitor:RX", "", [] ],
[ "esp:RX0", "$serialMonitor:TX", "", [] ],
     "esp:VIN",
        "ultrasonic1:VCC",
        "red",
        [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
     ],
     [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
[ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
[ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
  ]
}
```

OUTPUT:



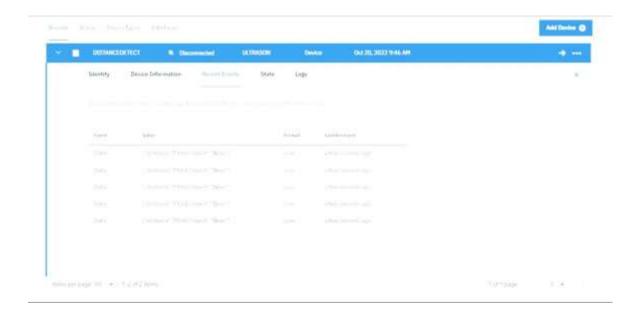
Data send to the IBM cloud device when the object is far:

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Data sent to the IBM Cloud Device when the object is near:



When object is near to the ultrasonic sensor:

