

## **V.S.B. ENGINEERING COLLEGE, KARUR**

### **Department of Electronics and Communication Engineering**

**TITLE** : Signs with smart connectivity for better  
Road Safety

**DOMAIN NAME** : Internet of Things

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### **Coding :**

```
#include<Servo.h>
```

```
int us = 6;
```

```
int servo = 7;
```

```
Servo servo1;
```

```
void setup() {
```

```
    Serial.begin(9600);
```

```
    servo1.attach(servo);
```

```
    pinMode(2,INPUT);
```

```
    pinMode(4,OUTPUT);
```

```
    pinMode(11,OUTPUT);
```

```
    pinMode(12,OUTPUT);
```

```
    pinMode(13,OUTPUT);
```

```
    pinMode(A0,INPUT);
```

```
digitalWrite(2,LOW);  
digitalWrite(11,HIGH);  
  
}  
  
void loop() {  
  
    long duration, inches, cm;  
  
    pinMode(us, OUTPUT);  
    digitalWrite(us, LOW);  
    delayMicroseconds(2);  
    digitalWrite(us, HIGH);  
    delayMicroseconds(5);  
    digitalWrite(us, LOW);  
  
    pinMode(us, INPUT);  
    duration = pulseIn(us, HIGH);  
  
    inches = microsecondsToInches(duration);  
    cm = microsecondsToCentimeters(duration);  
  
    servo1.write(0);  
  
    if(cm < 30)  
    {  
        servo1.write(120);
```

```
    Serial.println("A Person Arrived, Door is Opening.....");  
    delay(2000);  
}  
else  
{  
    servo1.write(0);  
    Serial.println("Door is Closed.....");  
}
```

```
int pir = digitalRead(2);
```

```
if(pir == HIGH)  
{  
    digitalWrite(4,HIGH);  
    delay(3000);  
}  
else if(pir == LOW)  
{  
    digitalWrite(4,LOW);  
}
```

```
float value=analogRead(A0);  
float temp=(((value/1024)*5.0199)-0.5)*100;
```

```
Serial.print("temp is ");  
Serial.println(temp);  
delay(3000);  
if(temp > 20)  
{
```

```
    digitalWrite(12,HIGH);
    digitalWrite(13,LOW);
}
else
{
    digitalWrite(12,LOW);
    digitalWrite(13,LOW);
}
}

long microsecondsToInches(long microseconds) {
    return microseconds / 74 / 2;
}

long microsecondsToCentimeters(long microseconds) {
    return microseconds / 29 / 2;
}
```

