ASSIGNMENT 4

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Maximum marks	2 marks

Question:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

Solution:

Source code:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic,byte* payload, unsigned int
payloadLength);
#define ORG "9zsxrs"
#define DEVICE_TYPE "iot"
#define DEVICE_ID "5"
#define TOKEN "45964596"
String data3;
char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[]="iot-2/evt/distance/fmt/json";
```

```
char subscribeTopic[]="iot-2/cmd/test/fmt/String";
char authMethod[]="use-token-auth";
char token[]=TOKEN;
char clientID[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback, wifiClient);
#define ECHO PIN 2
#define TRIG PIN 4
#define led 5
void setup() {
  // put your setup code here, to run once:
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(TRIG PIN, OUTPUT);
  pinMode(ECHO PIN, INPUT);
  wificonnect();
  mqttconnect();
}
float readDistanceCM() {
  digitalWrite(TRIG PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG PIN, LOW);
  int duration=random(1,200);
  //Serial.println(duration);
  //duration = pulseIn(ECHO PIN, HIGH);
  return duration ;
  //Serial.println(duration);
}
void loop() {
  float distance = readDistanceCM();
  //Serial.println(distance);
  bool isNearby = distance < 100;</pre>
```

```
digitalWrite(led, isNearby);
  Serial.print("Measured distance: ");
  Serial.println(distance);
  if (distance<100) {</pre>
    PublishData2(distance);
  }else{
    PublishData1(distance);
  }
  //PublishData(distance);
  delay(1000);
  if(!client.loop()){
   mqttconnect();
  }
  //delay(2000);
}
void PublishData1(float dist) {
  mqttconnect();
  String payload= "{\"distance\":";
  payload += dist;
  payload+="}";
  Serial.print("Sending payload:");
  Serial.println(payload);
  if(client.publish(publishTopic,(char*)payload.c str())){
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
  }
}
void PublishData2(float dist){
  mqttconnect();
  String payload= "{\"ALERT\":";
  payload += dist;
  payload+="}";
```

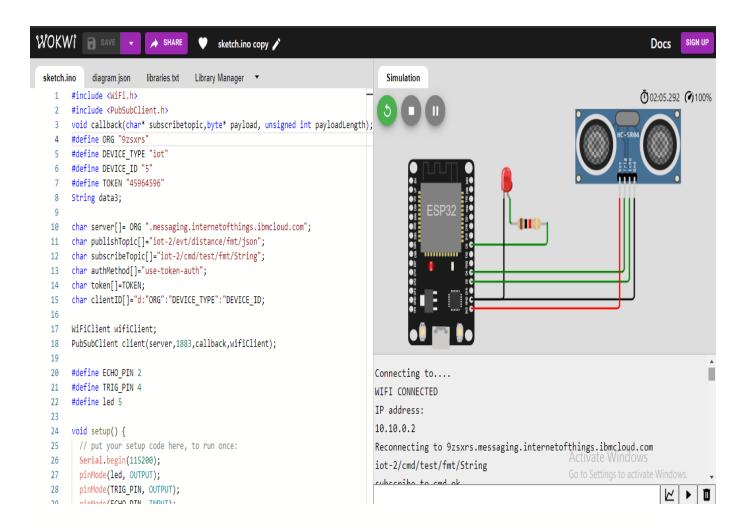
```
Serial.print("Sending payload:");
 Serial.println(payload);
 if(client.publish(publishTopic,(char*)payload.c_str())) {
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
 }
}
void mqttconnect() {
 if(!client.connected()){
    Serial.print("Reconnecting to ");
    Serial.println(server);
    while(!!!client.connect(clientID, authMethod, token)){
      Serial.print(".");
     delay(500);
    }
    initManagedDevice();
    Serial.println();
 }
}
void wificonnect() {
 Serial.println();
 Serial.print("Connecting to");
 WiFi.begin("Wokwi-GUEST","",6);
 while (WiFi.status()!=WL CONNECTED) {
   delay(500);
   Serial.print(".");
  }
 Serial.println("");
 Serial.println("WIFI CONNECTED");
 Serial.println("IP address:");
 Serial.println(WiFi.localIP());
}
void initManagedDevice(){
  if (client.subscribe(subscribeTopic)) {
    Serial.println((subscribeTopic));
```

```
Serial.println("subscribe to cmd ok");
  }else{
    Serial.println("subscribe to cmd failed");
  }
}
void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength) {
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++) {</pre>
    data3 += (char)payload[i];
  }
  Serial.println("data:"+ data3);
  if (data3=="lighton") {
    Serial.println(data3);
    digitalWrite(led,HIGH);
  }else{
    Serial.println(data3);
    digitalWrite(led,LOW);
  }
  data3="";
}
```

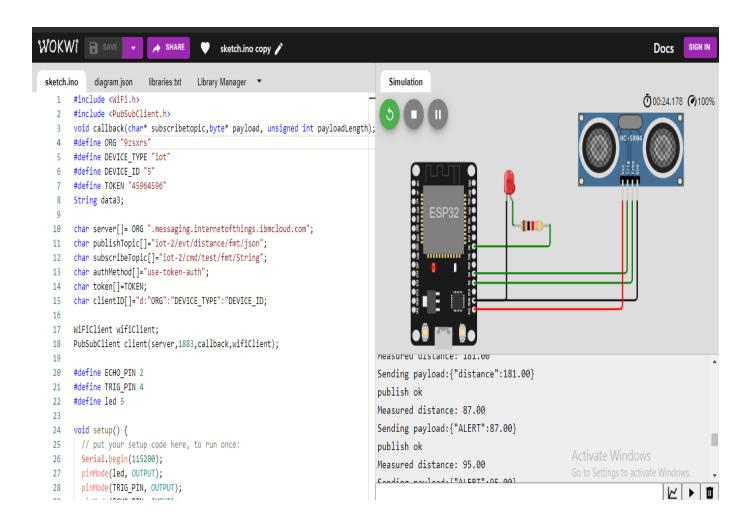
Wokwi project link:

https://wokwi.com/projects/347324125989044820

Normal Case:



Alert Case:



Cloud storage:

