

Assignment - 4

Assignment Date	22 October 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

Solution:

```
// Pins    const    int
TRIG_PIN = 7; const int
ECHO_PIN = 8;

// Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;

void setup() {

    // The Trigger pin will tell the sensor to range find
    pinMode(TRIG_PIN,                OUTPUT);
    digitalWrite(TRIG_PIN, LOW);

    //Set Echo pin as input to measure the duration of
    //pulses coming back from the distance sensor
    pinMode(ECHO_PIN, INPUT);

    // We'll use the serial monitor to view the sensor output
    Serial.begin(9600);
}
```

```

void loop() {

    unsigned long t1;
    unsigned long t2;
    unsigned long
    pulse_width;
    float cm; float
    inches;

    // Hold the trigger pin high for at least 10 us

    digitalWrite(TRIG_PIN,
    HIGH); delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW);

    // Wait for pulse on echo pin while (
    digitalRead(ECHO_PIN) == 0 );

    // Measure how long the echo pin was held high (pulse width)
    // Note: the micros() counter will overflow after ~70 min t1 =
    micros();
    while ( digitalRead(ECHO_PIN) == 1);
    t2 = micros(); pulse_width
    = t2 - t1;

    // Calculate distance in centimeters and inches. The constants // are
    found in the datasheet, and calculated from the assumed speed //of
    sound in air at sea level (~340 m/s). cm = pulse_width / 58.0;
    inches = pulse_width / 148.0;

    // Print out results if (
    pulse_width > MAX_DIST ) {
    Serial.println("Out of range");
    } else {
    Serial.println("*****");
    Serial.print("The Measured Distance in cm : ");
    Serial.println(cm);

```

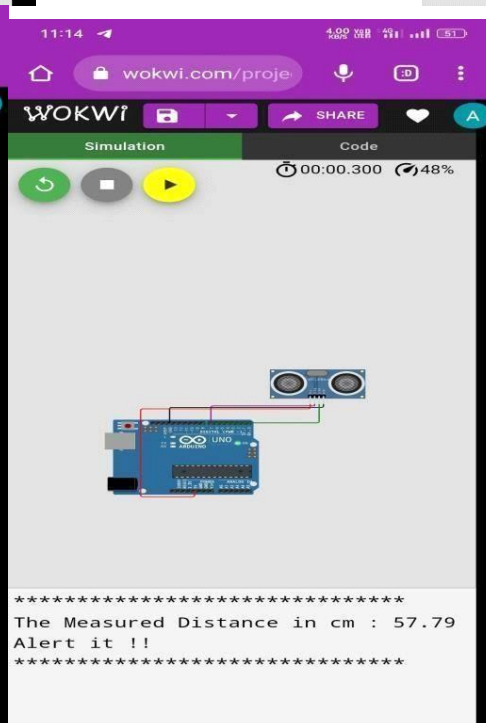
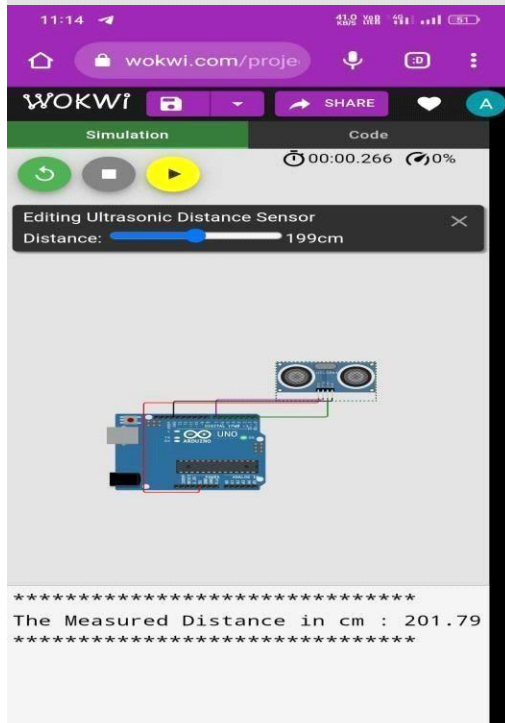
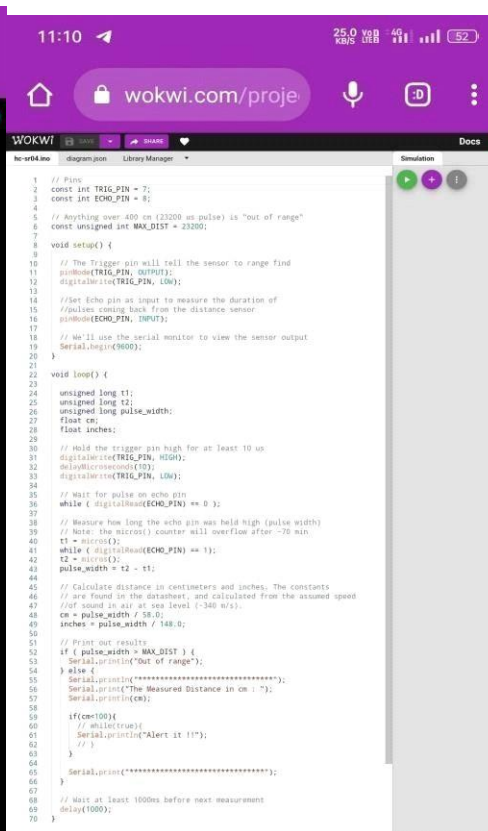
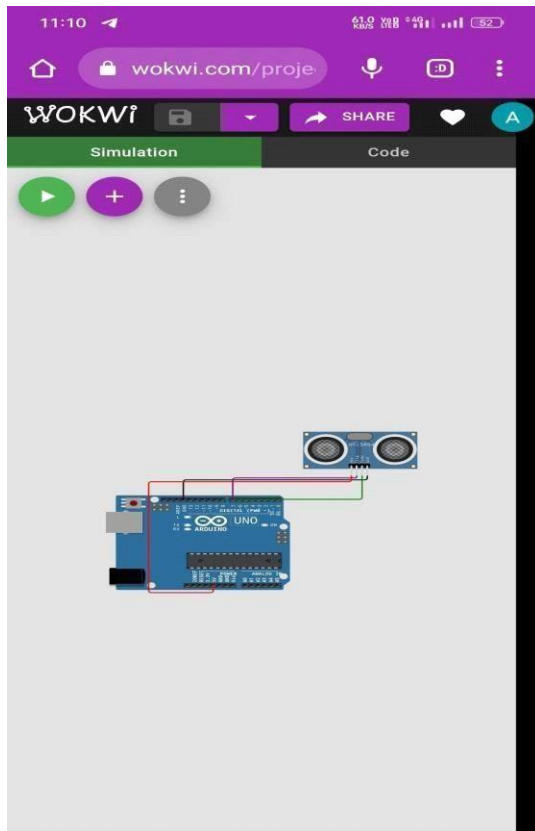
```
if(cm<100){  
  // while(true){  
    Serial.println("Alert!!");  
  // }  
}  
  
Serial.print("*****"); }  
  
// Wait at least 1000ms before next measurement delay(1000);  
}
```

Output:

- If the distance is less than 100 cms , it alerts.

- If the distance is more than 100 cms, it won't alert.

- Simulation and code execution



Project Link:

<https://wokwi.com/projects/346136429340918356>