

Assignment -4

Assignment Date	10 Oct 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

Program:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
```

```
WiFiClient wifiClient;
```

```
#define ORG "kr9fjo"
#define DEVICE_TYPE "TestDeviceType"
#define DEVICE_ID "12345"
#define TOKEN "VJsSC148dk1dCN3UqS"
#define speed 0.034
```

```
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/abcd_1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
```

```
const int trigpin=5;
const int echopin=18;
String command;
String data="";
String lat="14.167589";
String lon="80.248510";
String name="point2";
String icon="";
```

```
long duration;
int dist;

void setup()
{
    Serial.begin(115200);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifiConnect();
    mqttConnect();
}

void loop() {

    publishData();
    delay(500);

    if (!client.loop()) {
        mqttConnect();
    }
}

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(1000);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
```

```

if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
} else {
    Serial.println("subscribe to cmd FAILED");
}
}

void publishData()
{
    digitalWrite(trigpin,LOW);
    digitalWrite(trigpin,HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin,LOW);
    duration=pulseIn(echopin,HIGH);
    dist=duration*speed/2;

    if(dist<100){
        dist=100-dist;
        icon="fa-trash";
    }else{
        dist=0;
        icon="fa-trash-o";
    }
    DynamicJsonDocument doc(1024);
    String payload;
    doc["Name"]=name;
    doc["Latitude"]=lat;
    doc["Longitude"]=lon;
    doc["Icon"]=icon;
    doc["FillPercent"]=dist;
    serializeJson(doc, payload);
    delay(3000);
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    } else {
        Serial.println("Publish FAILED");
    }
}
}

```

Output:

The screenshot displays the WOKWI IoT simulator interface. The left pane shows the 'sketch.ino' file with the following code:

```
1 #include <WiFi.h>
2 #include <PubSubClient.h>
3 #include <ArduinoJson.h>
4
5 WiFiClient wificlient;
6
7 #define ORG "kr9fjo"
8 #define DEVICE_TYPE "TestDeviceType"
9 #define DEVICE_ID "12345"
10 #define TOKEN "VjsSC148dk1dCN3Uq5"
11 #define speed 0.034
12
13 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
14 char publishTopic[] = "iot-2/evt/abcd_1/fmt/json";
15 char topic[] = "iot-2/cmd/home/fmt/String";
16 char authMethod[] = "use-token-auth";
17 char token[] = TOKEN;
18 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
19 PubSubClient client(server, 1883, wificlient);
20 void publishData();
21
22 const int trigpin=5;
23 const int echopin=18;
24 String command;
25 String data="";
26 String lat="14.167589";
27 String lon="80.248510";
28 String name="point2";
29 String icon="";
30
31 long duration;
32 int dist;
33
34 void setup()
35 {
36   Serial.begin(115200);
37   pinMode(trigpin, OUTPUT);
```

The right pane shows a simulation of an ESP32 microcontroller board connected to an HC-SR04 ultrasonic sensor module. The sensor's VCC pin is connected to the ESP32's 5V pin, GND to GND, and the Trig pin to pin 5. The Echo pin is connected to pin 18. The simulation window includes a play button, a plus button, and a settings button. A Windows watermark is visible in the bottom right corner of the simulation area.

