#### **Assignment-4**

### Distance Detection Using Ultrasonic Sensor

Assignment Date	27 October 2022
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Maximum Marks	2 Marks

### **Question-1:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

WOKWI LINK: https://wokwi.com/projects/346502216516895315

```
#include <WiFi.h>//library for wifi #include
<PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned intpayloadLength);
//----credentials of IBM Accounts-----
#define ORG "f59trs"//IBM ORGANITION ID
#define DEVICE TYPE "ultrasonicsensor"//Device type mentioned inibm watson IOT
Platform
#define DEVICE_ID "distancedetection"//Device ID mentioned in ibmwatson IOT
#define TOKEN "AlGMGaaF01nawa1QA3"
String data3;
float dist;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";//Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name andtype of event perform
and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";//
char authMethod[] = "use-token-auth";// authentication methodchar token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//clientid
WiFiClient wifiClient; // creating the instance for wificlient
```

```
PubSubClient client(server, 1883, callback, wifiClient);
int LED = 4; int
trig = 5; int echo =
18; void setup()
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10); wificonnect();
mqttconnect();
void loop()// Recursive Function
 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);float dist
  = (dur * 0.0343)/2; Serial.print
  ("Distancein cm");Serial.println(dist);
  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
     mqttconnect();
void PublishData(float dist) { mqttconnect();//function call for connecting
  String object;
```

```
if (dist <100)
     digitalWrite(LED,HIGH);
     Serial.println("object is near");object =
     "Near";
     digitalWrite(LED,LOW); Serial.println("no
     object found");object = "No";
  String payload = "{\"distance\":";payload +=
  payload += "," "\"object\":\"";payload +=
  object;
  payload += "\"}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish ok");// if it successfully upload dataon the cloud then it will
   } else {
     Serial.println("Publish failed");
void mqttconnect() {
  if (!client.connected()) { Serial.print("Reconnecting
     client to ");Serial.println(server);
     while (!!!client.connect(clientId, authMethod, token)) {
        Serial.print(".");
        delay(500);
      initManagedDevice();
      Serial.println();
```

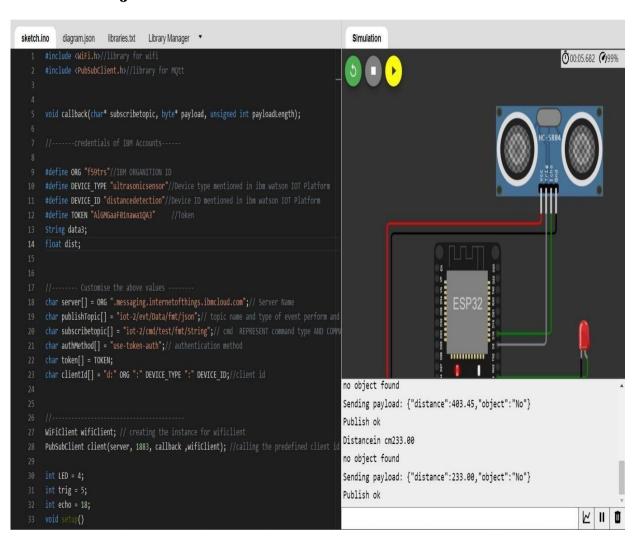
```
void wificonnect() //function defination for wificonnect
   Serial.println(); Serial.print("Connecting
  to");
   WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentialsto establish the
  while (WiFi.status() != WL_CONNECTED) {
     delay(500);
     Serial.print(".");
   Serial.println(""); Serial.println("WiFi
   connected");Serial.println("IP address: ");
   Serial.println(WiFi.localIP());
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) { Serial.println((subscribetopic));
     Serial.println("subscribe to cmd OK");
   } else {
     Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned intpayloadLength)
   Serial.print("callback invoked for topic: ");
   Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
     //Serial.print((char)payload[i]);data3 +=
     (char)payload[i];
 / digitalWrite(LED,HIGH);
```

```
// digitalWrite(LED,LOW);

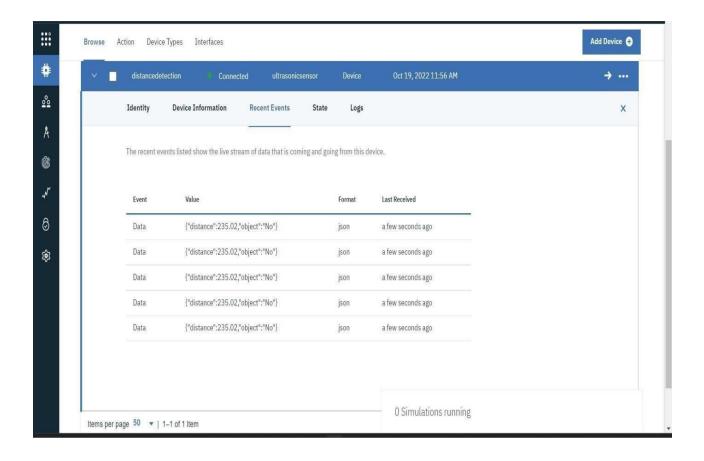
// }
data3="";
}
```

### **OUTPUT:**

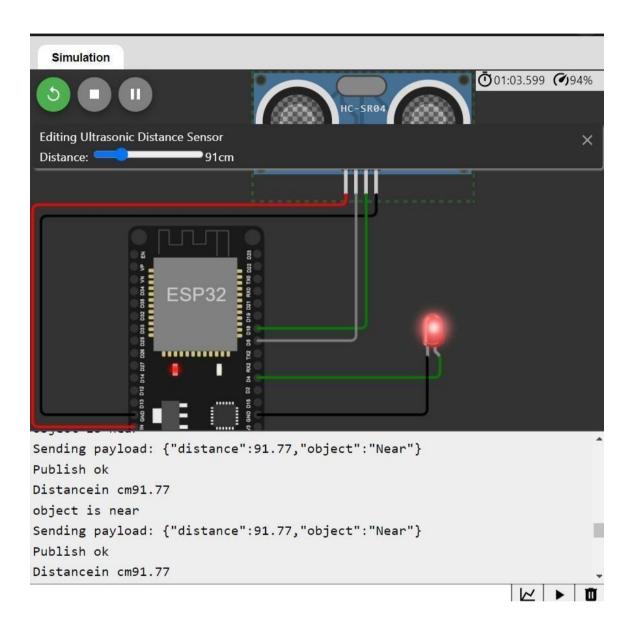
## When object is not near to the ultrasonic sensor



# Data sent to the IBM cloud device when the object is far



## When object is nearer to the ultrasonic sensor



# Data sent to the IBM cloud device when the object is near

