Assignment -4

Distance Detection Using Ultrasonic Sensor

Assignment Date	27 October 2022	
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Maximum Marks	2 Marks	

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

WOKWI LINK: https://wokwi.com/projects/346502216516895315

```
#include <WiFi.h>//library for wifi #include
<PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned intpayloadLength);
#define ORG "f59trs"//IBM ORGANITION ID
#define DEVICE TYPE "ultrasonicsensor"//Device type mentioned inibm watson IOT
#define DEVICE ID "distancedetection"//Device ID mentioned in ibmwatson IOT
Platform
#define TOKEN "AlGMGaaF01nawa1QA3"
String data3;
float dist;
//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";//Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name andtype of event perform
char subscribetopic[] = "iot-2/cmd/test/fmt/String";//
char authMethod[] = "use-token-auth";// authentication methodchar token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//clientid
WiFiClient wifiClient; // creating the instance for wificlient
```

```
PubSubClient client(server, 1883, callback, wifiClient);
int LED = 4; int
trig = 5; int echo =
18; void setup()
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10); wificonnect();
mqttconnect();
void loop()// Recursive Function
 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);float dist
  = (dur * 0.0343)/2; Serial.print
  ("Distancein cm"); Serial.println(dist);
  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
     mqttconnect();
 * retrieving to
void PublishData(float dist) { mqttconnect();//function call for connecting
      creating the String in in form JSon to update the data toibm cloud
  String object;
```

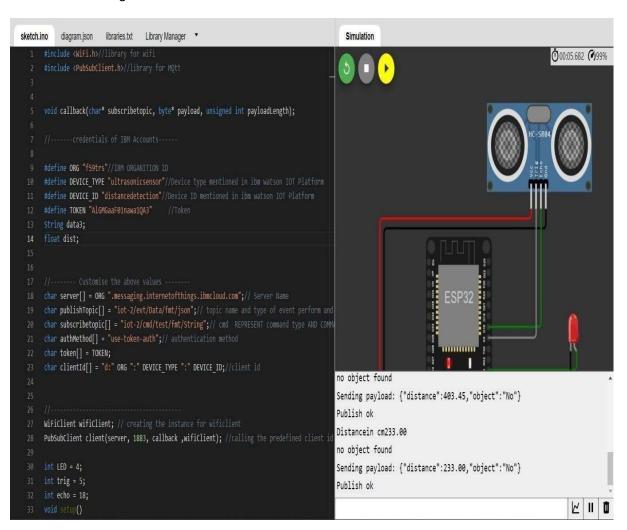
```
if (dist <100)
     digitalWrite(LED,HIGH);
     Serial.println("object is near");object =
     "Near";
     digitalWrite(LED,LOW); Serial.println("no
     object found");object = "No";
  String payload = "{\"distance\":";payload +=
  payload += "," "\"object\":\"";payload +=
  object;
  payload += "\"}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish ok");// if it successfully upload dataon the cloud then it will
print publish ok in Serial monitor or else it will print publish failed
  } else {
     Serial.println("Publish failed");
void mqttconnect() {
  if (!client.connected()) { Serial.print("Reconnecting
     client to ");Serial.println(server);
     while (!!!client.connect(clientId, authMethod, token)) {
        Serial.print(".");
        delay(500);
       initManagedDevice();
       Serial.println();
```

```
void wificonnect() //function defination for wificonnect
  Serial.print(n); Serial.print("Connecting
  to");
  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentialsto establish the
  while (WiFi.status() != WL CONNECTED) {
     delay(500);
     Serial.print(".");
  Serial.println(""); Serial.println("WiFi
  connected");Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) { Serial.println((subscribetopic));
     Serial.println("subscribe to cmd OK");
  } else {
     Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned intpayloadLength)
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
     //Serial.print((char)payload[i]);data3 +=
     (char)payload[i];
 digitalWrite(LED,HIGH);
```

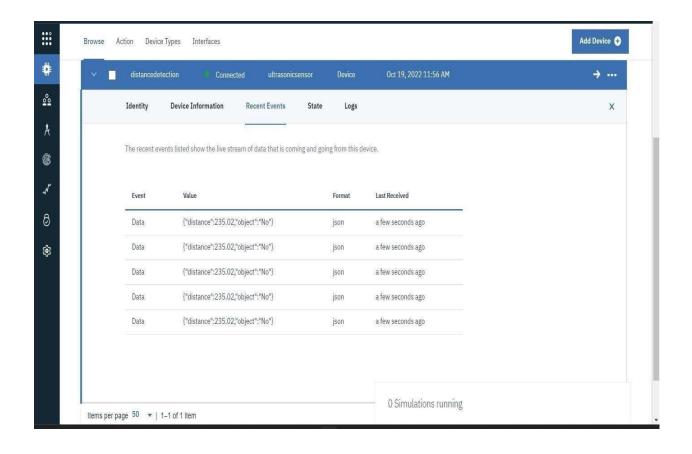
```
// digitalWrite(LED,LOW);
// }
data3="";
```

OUTPUT:

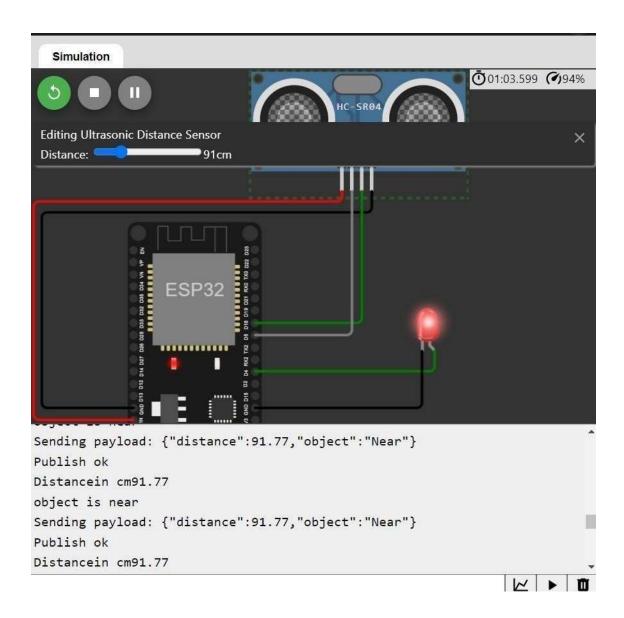
When object is not near to the ultrasonic sensor



Data sent to the IBM cloud device when the object is far



When object is nearer to the ultrasonic sensor



Data sent to the IBM cloud device when the object is near

