Assignment 4

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Submitted by:
B7-1A3E
M JAWERIYA SHARIEFF team leader
A R Rizwana
S Thaslima
I Jasheena
M Geetha
CODE:
#define trigPin 8
#define echoPin 9
#define buzzer 10
long duration;
float distanceInch;
int timer;
void setup() {
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
pinMode(buzzer, OUTPUT);
```

```
}
void loop() {
 digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distanceInch = duration * 0.0133 /2;
digitalWrite(buzzer, HIGH);
delay(50);
digitalWrite(buzzer, LOW);
timer = distanceInch * 10;
delay(timer);
}
FIGURE:
```

