Python code for blinking LED:

```
# calling header file for GPIO's
import RPi.GPIO as IO
of PI
                                         # calling for time to
import time
provide delays in program
IO.setmode (IO.BOARD)
                            # programming the GPIO by BOARD pin
numbers, GPIO21 is called as PIN40
IO.setup(40,IO.OUT)
                                # initialize digital pin40 as an
output.
IO.output(40,1)
                                     # turn the LED on (making
the voltage level HIGH)
time.sleep(1)
                                      # sleep for a second
                                     # turn the LED off (making
IO.cleanup()
all the output pins LOW)
time.sleep(1)
                                     #sleep for a second
#loop is executed second time
IO.setmode (IO.BOARD)
IO.setup(40,IO.OUT)
IO.output(40,1)
time.sleep(1)
IO.cleanup()
time.sleep(1)
#loop is executed third time
IO.setmode (IO.BOARD)
IO.setup(40,IO.OUT)
IO.output(40,1)
time.sleep(1)
IO.cleanup()
time.sleep(1)
```

Python code for Trafficlight using Rasperry pi:

```
    from gpiozero import Button, TrafficLights, Buzzer
    from time import sleep
    buzzer = Buzzer(15)
    button = Button(21)
    lights = TrafficLights(25, 8, 7)
```

Write python code for blinking LED and traffic lights for Rasperry pi

```
7.
8. while True:
              button.wait_for_press()
9.
               buzzer.on()
10.
                light.green.on()
11.
                sleep(1)
 12.
                lights.amber.on()
 13.
 14.
                sleep(1)
                lights.red.on()
 15.
 16.
                sleep(1)
 17.
                lights.off()
                 buzzer.off()
 18.
```

OUTPUT

Run your Powershell coding (F5)