

Assignment - 4

Write code and connections in wokwi for ultrasonic. Whenever distance is less than 100 cm's send "alert" to IBM cloud and display in device recent.

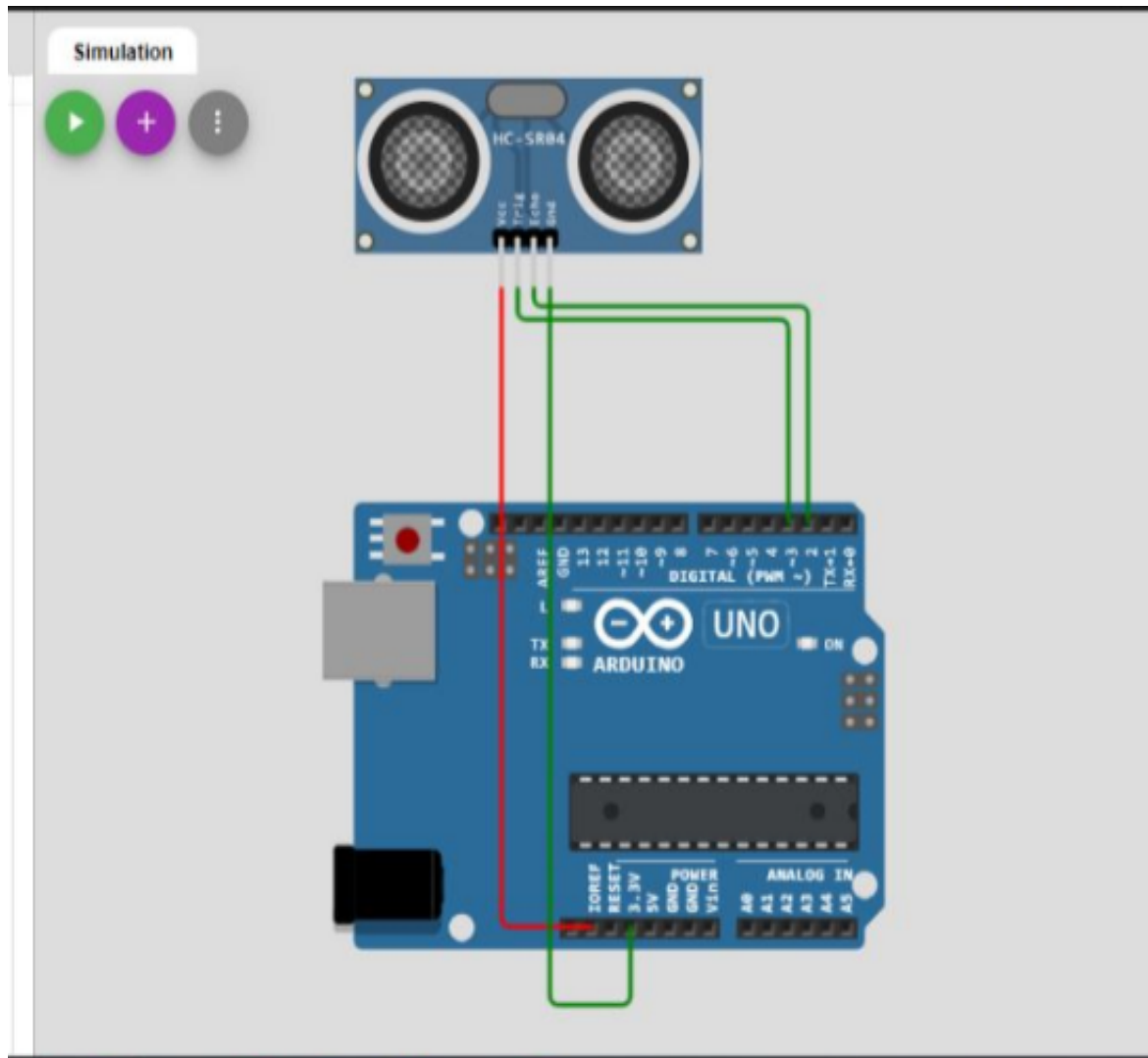
PROGRAM:

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization ="m040km"
#define deviceType=" Arduino"
#define deviceId ="12345"
#define authMethod ="use-token-auth"
#define authToken ="2YvKHr)ujgdHS7y?dM"
void setup() {
// put your setup code here, to run once:
Serial.begin(9600);
pinMode(TRIG_PIN,OUTPUT);
pinMode(ECHO_PIN, INPUT);
}
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop() {
// put your main code here, to run repeatedly:
float distance = readDistanceCM();
if(distance <= 100)
{
Serial.println("person detected ");
}
else{
Serial.print("Measured distance: ");
Serial.println(readDistanceCM());
}
```

```
delay(1000);  
}
```

Wokwi Project Link: <https://wokwi.com/projects/347409837693338195>

Aurdino Uno:



sketch.ino diagram.json Library Manager

```
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5 #define deviceId ="12345"
6 #define authMethod ="use-token-auth"
7 #define authToken ="2YvKHr)ujgdHS7y?d4"
8 void setup() {
9 // put your setup code here, to run once:
10 Serial.begin(9600);
11 pinMode(TRIG_PIN,OUTPUT);
12 pinMode(ECHO_PIN, INPUT);
13 }
14 float readDistanceCM() {
15 digitalWrite(TRIG_PIN, LOW);
16 delayMicroseconds(2);
17 digitalWrite(TRIG_PIN, HIGH);
18 delayMicroseconds(10);
19 digitalWrite(TRIG_PIN, LOW);
20 int duration = pulseIn(ECHO_PIN, HIGH);
21 return duration * 0.034 / 2;
22 }
23 void loop() {
24 // put your main code here, to run repeatedly:
25 float distance = readDistanceCM();
26 if(distance <= 100)
27 {
28 Serial.println("person detected ");
29 }
30 else{
31 Serial.print("Measured distance: ");
32 Serial.println(readDistanceCM());
```

22°C
Cloudy



Simulation

