

NAME : BALASUBRAMANIAN

Rollno: 412319106002

### ASSIGNMENT 1-HOME AUTOMATION

#### PROGRAM:

```
#include <Servo.h>

int output1Value = 0;
int sen1Value = 0;
int sen2Value = 0;
int const gas_sensor = A1;
int const LDR = A0;
int limit = 400;

long readUltrasonicDistance(int triggerPin, int echoPin)
{
    pinMode(triggerPin, OUTPUT); // Clear the trigger
    digitalWrite(triggerPin, LOW);
    delayMicroseconds(2);
    // Sets the trigger pin to HIGH state for 10 microseconds
    digitalWrite(triggerPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(triggerPin, LOW);
    pinMode(echoPin, INPUT);
    // Reads the echo pin, and returns the sound wave travel time in microseconds
    return pulseIn(echoPin, HIGH);
}

Servo servo_7;

void setup()
```

```

{
    Serial.begin(9600);          //initialize serial communication
    pinMode(A0, INPUT);         //LDR
    pinMode(A1, INPUT);         //gas sensor
    pinMode(13, OUTPUT);         //connected to relay
    servo_7.attach(7, 500, 2500); //servo motor

    pinMode(8, OUTPUT);         //signal to piezo buzzer
    pinMode(9, INPUT);          //signal to PIR
    pinMode(10, OUTPUT);        //signal to npn as switch
    pinMode(4, OUTPUT);         //Red LED
    pinMode(3, OUTPUT);         //Green LED

}

```

```

void loop()

```

```

{

    //-----light intensity control-----//
    //-----
    int val1 = analogRead(LDR);
    if (val1 > 500)
    {
        digitalWrite(13, LOW);
        Serial.print("Bulb ON = ");
        Serial.print(val1);
    }
    else
    {
        digitalWrite(13, HIGH);
        Serial.print("Bulb OFF = ");
    }
}

```

```

Serial.print(val1);
    }

//-----
    //----- light & fan control -----//
//-----

sen2Value = digitalRead(9);
if (sen2Value == 0)
    {
        digitalWrite(10, LOW); //npn as switch OFF
        digitalWrite(4, HIGH); // Red LED ON,indicating no motion
        digitalWrite(3, LOW); //Green LED OFF, since no Motion detected
        Serial.print("  || NO Motion Detected  ");
    }

if (sen2Value == 1)
    {
        digitalWrite(10, HIGH); //npn as switch ON
        delay(3000);
        digitalWrite(4, LOW); // RED LED OFF
        digitalWrite(3, HIGH); //GREEN LED ON , indicating motion detected
        Serial.print("  || Motion Detected!  ");
    }
    delay(300);

//-----
    // ----- Gas Sensor -----//
//-----

int val = analogRead(gas_sensor); //read sensor value
Serial.print(" || Gas Sensor Value = ");
Serial.print(val); //Printing in serial monitor

```

```

//val = map(val, 300, 750, 0, 100);

if (val > limit)
{
    tone(8, 650);
}

delay(300);

noTone(8);


//-----

//----- servo motor -----//

//-----

sen1Value = 0.01723 * readUltrasonicDistance(6, 6);


if (sen1Value < 100)
{
    servo_7.write(90);

    Serial.print("  || Door Open! ; Distance = ");

    Serial.print(sen1Value);

    Serial.print("\n");

}

else
{
    servo_7.write(0);

    Serial.print("  || Door Closed! ; Distance = ");

    Serial.print(sen1Value);

    Serial.print("\n");

}

delay(10); // Delay a little bit to improve simulation performance
}

```

**OUTPUT:**

