Assignment-4

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Topic	Smart Solutions for Railways
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Write code and connections in wokwi for ultrasonic sensor

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.upload wokwi share link and images of ibm cloud

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic,byte* payload, unsigned int payloadLength);
#define ORG "eugl@y"
#define DEVICE TYPE "iot"
#define DEVICE ID "456"
#define TOKEN "12345678"
String data3;
char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[]="iot-2/evt/distance/fmt/json";
char subscribeTopic[]="iot-2/cmd/test/fmt/String";
char authMethod[]="use-token-auth";
char token[]=TOKEN;
char clientID[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server,1883,callback,wifiClient);
#define ECHO PIN 2
#define TRIG PIN 4
#define led 5
void setup() {
 // put your setup code here, to run once:
```

```
Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
  wificonnect();
  mqttconnect();
}
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration=random(1,200);
  //Serial.println(duration);
  //duration = pulseIn(ECHO_PIN, HIGH);
  return duration ;
  //Serial.println(duration);
}
void loop() {
  float distance = readDistanceCM();
  //Serial.println(distance);
  bool isNearby = distance < 100;</pre>
  digitalWrite(led, isNearby);
  Serial.print("Measured distance: ");
  Serial.println(distance);
  if(distance<100){</pre>
    PublishData2(distance);
  }else{
    PublishData1(distance);
  }
  //PublishData(distance);
  delay(1000);
  if(!client.loop()){
   mqttconnect();
  }
  //delay(2000);
void PublishData1(float dist){
  mqttconnect();
  String payload= "{\"distance\":";
```

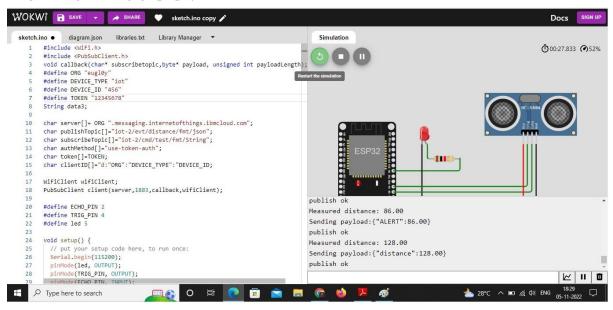
```
payload += dist;
  payload+="}";
  Serial.print("Sending payload:");
  Serial.println(payload);
  if(client.publish(publishTopic,(char*)payload.c_str())){
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
  }
}
void PublishData2(float dist){
  mqttconnect();
  String payload= "{\"ALERT\":";
  payload += dist;
  payload+="}";
  Serial.print("Sending payload:");
  Serial.println(payload);
  if(client.publish(publishTopic,(char*)payload.c_str())){
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
  }
}
void mqttconnect(){
  if(!client.connected()){
    Serial.print("Reconnecting to ");
    Serial.println(server);
   while(!!!client.connect(clientID, authMethod, token)){
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
   Serial.println();
  }
}
void wificonnect(){
  Serial.println();
  Serial.print("Connecting to");
  WiFi.begin("Wokwi-GUEST","",6);
  while(WiFi.status()!=WL_CONNECTED){
    delay(500);
    Serial.print(".");
```

```
}
  Serial.println("");
  Serial.println("WIFI CONNECTED");
  Serial.println("IP address:");
  Serial.println(WiFi.localIP());
}
void initManagedDevice(){
  if(client.subscribe(subscribeTopic)){
    Serial.println((subscribeTopic));
    Serial.println("subscribe to cmd ok");
  }else{
    Serial.println("subscribe to cmd failed");
  }
}
void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength){
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++){</pre>
    data3 += (char)payload[i];
  }
  Serial.println("data:"+ data3);
  if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
  }else{
    Serial.println(data3);
   digitalWrite(led,LOW);
  }
 data3="";
}
```

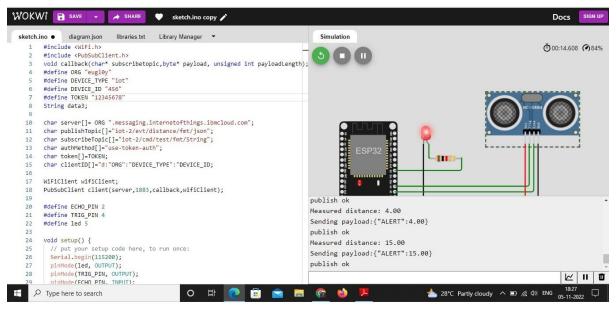
LINK: https://wokwi.com/projects/347492831664800339

Output:

Normal Case:



Alter Case:



IBM CLOUD:

