

## Assignment – 4

Assignment Date	28 October 2022
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Maximum Marks	2 Marks

### Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

### Solution:

```
// Pins
```

```
const int TRIG_PIN = 7;
```

```
const int ECHO_PIN = 8;
```

```
// Anything over 400 cm (23200 us pulse) is "out of range"
```

```
const unsigned int MAX_DIST = 23200;
```

```
void setup() {
```

```
  // The Trigger pin will tell the sensor to range find
```

```
  pinMode(TRIG_PIN, OUTPUT);
```

```
  digitalWrite(TRIG_PIN, LOW);
```

```
  //Set Echo pin as input to measure the duration of
```

```
  //pulses coming back from the distance sensor
```

```
  pinMode(ECHO_PIN, INPUT);
```

```

// We'll use the serial monitor to view the sensor output
Serial.begin(9600);

}

void loop() {

    unsigned long t1; unsigned
    long t2; unsigned long
    pulse_width; float cm;
    float inches;

    // Hold the trigger pin high for at least 10 us
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10); digitalWrite(TRIG_PIN,
    LOW);

    // Wait for pulse on echo pin while (
    digitalRead(ECHO_PIN) == 0 );

    // Measure how long the echo pin was held high (pulse width)
    // Note: the micros() counter will overflow after ~70 min
    t1 = micros(); while ( digitalRead(ECHO_PIN) == 1); t2 =
    micros(); pulse_width = t2 - t1;
    // Calculate distance in centimeters and inches. The constants
    // are found in the datasheet, and calculated from the

```

```

assumed speed //of sound in air at sea level (~340 m/s). cm =
pulse_width / 58.0; inches = pulse_width / 148.0;
// Print out results if (
pulse_width > MAX_DIST ) {
Serial.println("Out of range");
} else {
Serial.println("*****");
Serial.print("The Measured Distance in cm : ");
Serial.println(cm); if(cm<100){
    // while(true){
    Serial.println("Alert!!");
    // }

}
Serial.print("*****");
}
// Wait at least 1000ms before next measurement delay(1000);
}

```

### Output:

1) If the distance is less than 100 cms , it alerts.

WOKWI

```
1 // Pin
2 const int TRIG_PIN = 7;
3 const int ECHO_PIN = 8;
4
5 // Anything over 400 cm (131238 us pulse) is "out of range"
6 const unsigned int MAX_DIST = 131000;
7
8 void setup() {
9
10   // The Trigger pin will tell the sensor to range find
11   pinMode(TRIG_PIN, OUTPUT);
12   digitalWrite(TRIG_PIN, LOW);
13
14   // Set Echo pin as input to measure the duration of
15   // pulses coming back from the distance sensor
16   pinMode(ECHO_PIN, INPUT);
17
18   // We'll use the serial monitor to view the sensor output
19   Serial.begin(9600);
20 }
21
22 void loop() {
23
24   unsigned long t1;
25   unsigned long t2;
26   unsigned long pulse_width;
27   float cm;
28   float inches;
29
30   // Hold the trigger pin high for at least 10 us
```

Simulation

Editing Ultrasonic Distance Sensor

Distance: 64.34

The Measured Distance in cm : 64.34

Alert!!

2) If the distance is more than 100 cms, it won't alert.

WOKWI

```
1 // Pin
2 const int TRIG_PIN = 7;
3 const int ECHO_PIN = 8;
4
5 // Anything over 400 cm (131238 us pulse) is "out of range"
6 const unsigned int MAX_DIST = 131000;
7
8 void setup() {
9
10   // The Trigger pin will tell the sensor to range find
11   pinMode(TRIG_PIN, OUTPUT);
12   digitalWrite(TRIG_PIN, LOW);
13
14   // Set Echo pin as input to measure the duration of
15   // pulses coming back from the distance sensor
16   pinMode(ECHO_PIN, INPUT);
17
18   // We'll use the serial monitor to view the sensor output
19   Serial.begin(9600);
20 }
21
22 void loop() {
23
24   unsigned long t1;
25   unsigned long t2;
26   unsigned long pulse_width;
27   float cm;
28   float inches;
29
30   // Hold the trigger pin high for at least 10 us
```

Simulation

The Measured Distance in cm : 217.10

### 3) Simulation and code execution

