## Assignment – 4

| Assignment Date     | 28 October 2022 |
|---------------------|-----------------|
| Student Name        | Jagadish K      |
| Student Roll Number | 2019503018      |
| Maximum Marks       | 2 Marks         |

## Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

```
Solution:

// Pins

const int TRIG_PIN = 7;

const int ECHO_PIN = 8;

// Anything over 400 cm (23200 us pulse) is "out of range" const unsigned int MAX_DIST = 23200;

void setup() {

// The Trigger pin will tell the sensor to range find pinMode(TRIG_PIN, OUTPUT);

digitalWrite(TRIG_PIN, LOW);

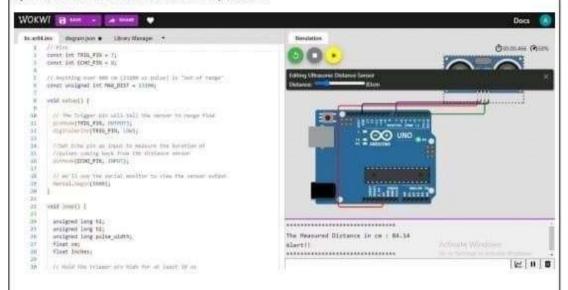
//Set Echo pin as input to measure the duration of //pulses coming back from the distance sensor pinMode(ECHO_PIN, INPUT);
```

```
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}
void loop() {
unsigned long t1; unsigned
long t2; unsigned long
pulse_width; float cm;
float inches:
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10); digitalWrite(TRIG_PIN,
LOW);
// Wait for pulse on echo pin while (
digitalRead(ECHO PIN) == 0 );
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after ~70 min
t1 = micros(); while ( digitalRead(ECHO_PIN) == 1); t2 =
micros(); pulse width = t2 - t1;
// Calculate distance in centimeters and inches. The constants
// are found in the datasheet, and calculated from the
```

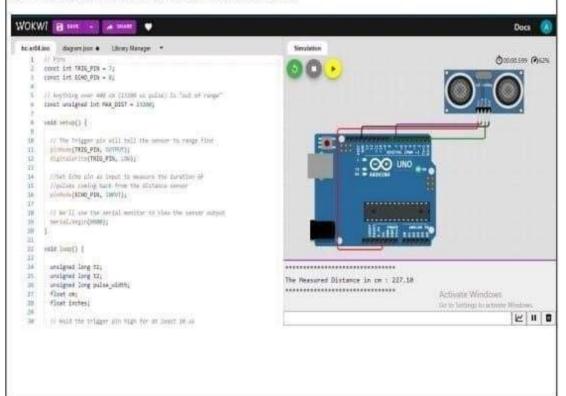
```
assumed speed //of sound in air at sea level (~340 m/s). cm =
pulse width / 58.0; inches = pulse width / 148.0;
// Print out results if (
pulse width > MAX DIST) {
Serial.println("Out of range");
} else {
Serial.println("**************************);
Serial.print("The Measured Distance in cm:");
Serial.println(cm); if(cm<100){</pre>
 // while(true){
 Serial.println("Alert!!");
 //}
}
Serial.print("*****************************);
}
// Wait at least 1000ms before next measurement delay(1000);
}
```

## Output:

1) If the distance is less than 100 cms, it alerts.



2) If the distance is more than 100 cms, it won't alert.



## 3) Simulation and code execution







