Project Design Phase-II

Solution Requirements (Functional & Non-functional)

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| Date | 12 October 2022 |
| Team ID | PNT2022TMID07532 |
| Project Name | SMART WASTE MANAGEMENT SYSTEM FOR METROPOLITAN CITIES |
| Maximum Marks | 4 Marks |

# Functional Requirements:

Following are the functional requirements of the proposed solution.

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| **FR No.** | **Functional Requirement (Epic)** | **Sub Requirement (Story / Sub-Task)** |
| FR-1 | Detailed bin inventory. | All monitored bins and stands can be seen on the map, and you can visit them at any time via the Street View feature from Google.  Bins or stands are visible on the map as green, orange or red circles.  You can see bin details in the Dashboard – capacity, waste type, last measurement, GPS location and  collection schedule or pick recognition. |
| FR-2 | Real time bin monitoring. | The Dashboard displays real-time data on fill-levels of bins monitored by smart sensors.  In addition to the % of fill-level, based on the historical data, the tool predicts when the bin will become full, one of the functionalities that are not included even in the best waste management software..  Sensors recognize picks as well; so you can check when the bin was last collected.  With real-time data and predictions, you can eliminate the overflowing bins and stop collecting half-empty  ones. |
| FR-3 | Expensive bins. | We help you identify bins that drive up your collection costs. The tool calculates a rating for each bin in terms of collection costs.  The tool considers the average distance depo-bin- discharge in the area. The tool assigns bin a rating  (1-10) and calculates distance from depo-bin discharge. |
| FR-4 | Adjust bin distribution. | Ensure the most optimal distribution of bins. Identify areas with either dense or sparse bin distribution.  Make sure all trash types are represented within a stand.  Based on the historical data, you can adjust bin capacity  or location where necessary. |
| FR-5 | Eliminate unefficient picks. | Eliminate the collection of half-empty bins. The sensors recognize picks.  By using real-time data on fill-levels and pick recognition, we can show you how full the bins you  collect are. |

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|  |  | The report shows how full the bin was when picked. You immediately see any inefficient picks below 80%  full. |
| FR-6 | Plan waste collection routes. | The tool semi-automates waste collection route planning. Based on current bin fill-levels and predictions of reaching full capacity, you are ready to respond and schedule waste collection.  You can compare planned vs. executed routes to  identify any inconsistencies. |
| FR-7 | Cash dispenser | It ensure that customer are getting sufficient cash to the waste material . |