Assignment-4

Distance Detection Using Ultrasonic Sensor

Assignment Date	19 October 2022
Student Name	SHAIK MARIAM FATHIMA
Student Roll Number	113319106071
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK : https://wokwi.com/projects/346518948162830932

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

#define ORG "f59trs"
#define DEVICE_TYPE "ultrasonicsensor"
#define DEVICE_ID "distancedetection"
#define TOKEN "AlGMGaaF01nawa1QA3"
String data3;
float dist;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;


WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
Serial.begin(115200);
pinMode(trig,OUTPUT);
```

```
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
}
void loop()
{

 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distance in cm :");
  Serial.println(dist);

  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}

void PublishData(float dist) {
  mqttconnect();
  String object;
  if (dist <100)
```

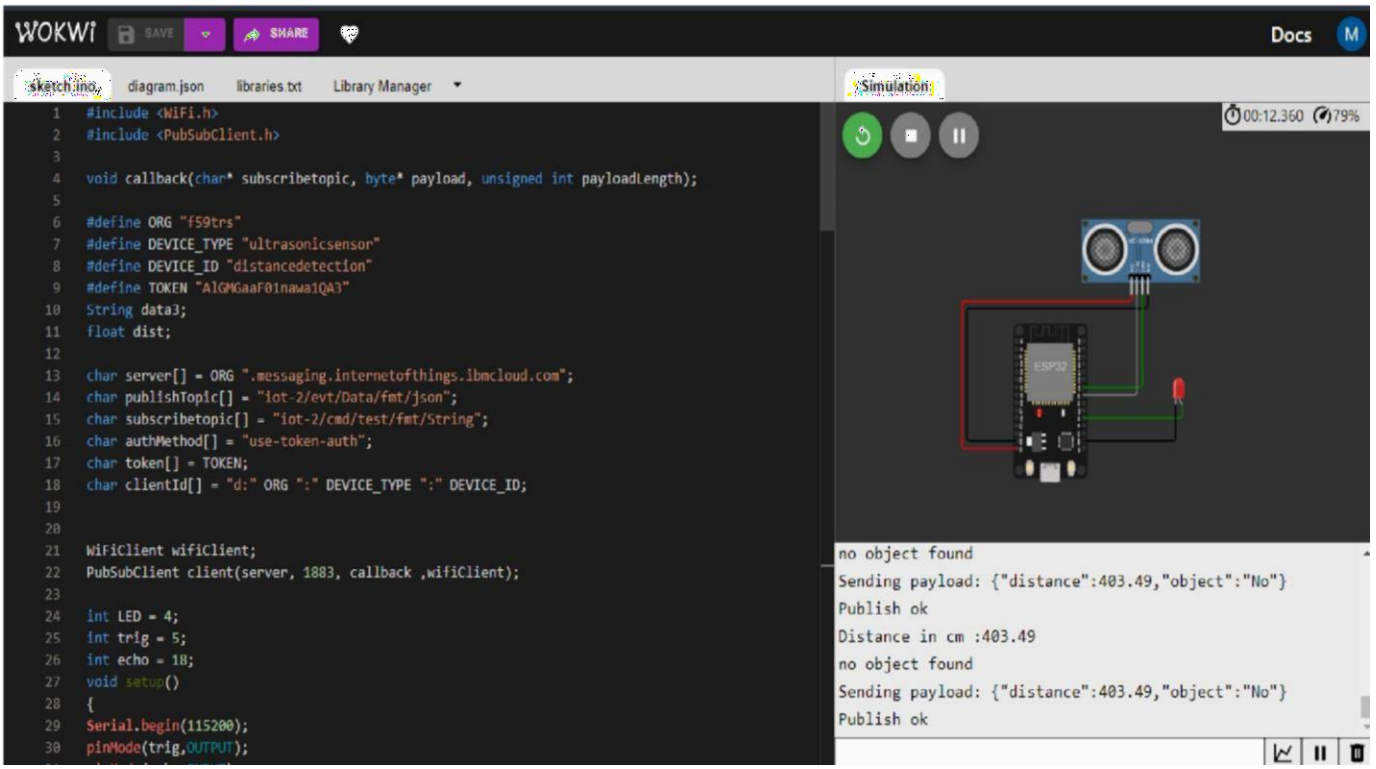
```
  if (dist <100)
  {
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
  }
  else
  {
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
  }

  String payload = "{\"distance\":";
  payload += dist;
  payload += "," "\"object\":\"";
  payload += object;
  payload += "\"}";

    Serial.print("Sending payload: ");
  Serial.println(payload);

  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");
  } else {
    Serial.println("Publish failed");
  }
}
void mqttconnect() {
  if (!client.connected()) {
```

```
      Serial.print("Reconnecting client to ");
      Serial.println(server);
      while (!!!client.connect(clientId, authMethod, token)) {
        Serial.print(".");
        delay(500);
      }
       initManagedDevice();
       Serial.println();
    }
}
void wificonnect()
{
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
```

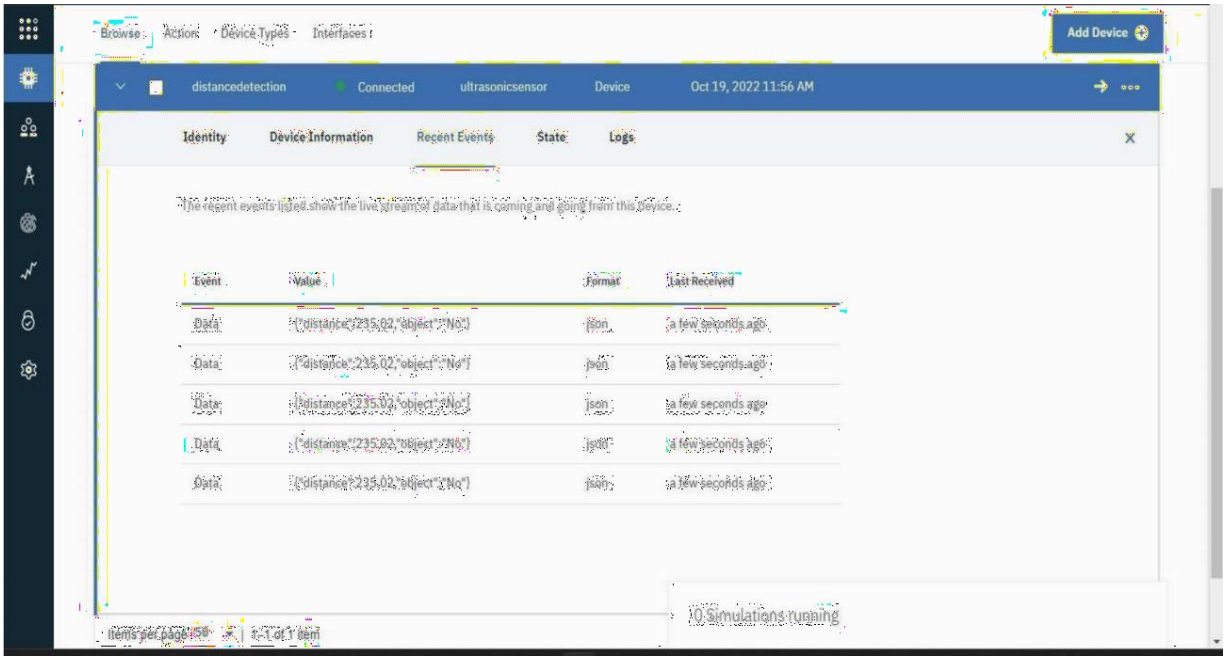
```
  }
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    data3 += (char)payload[i];
  }
data3="";
}
```

OUTPUT:

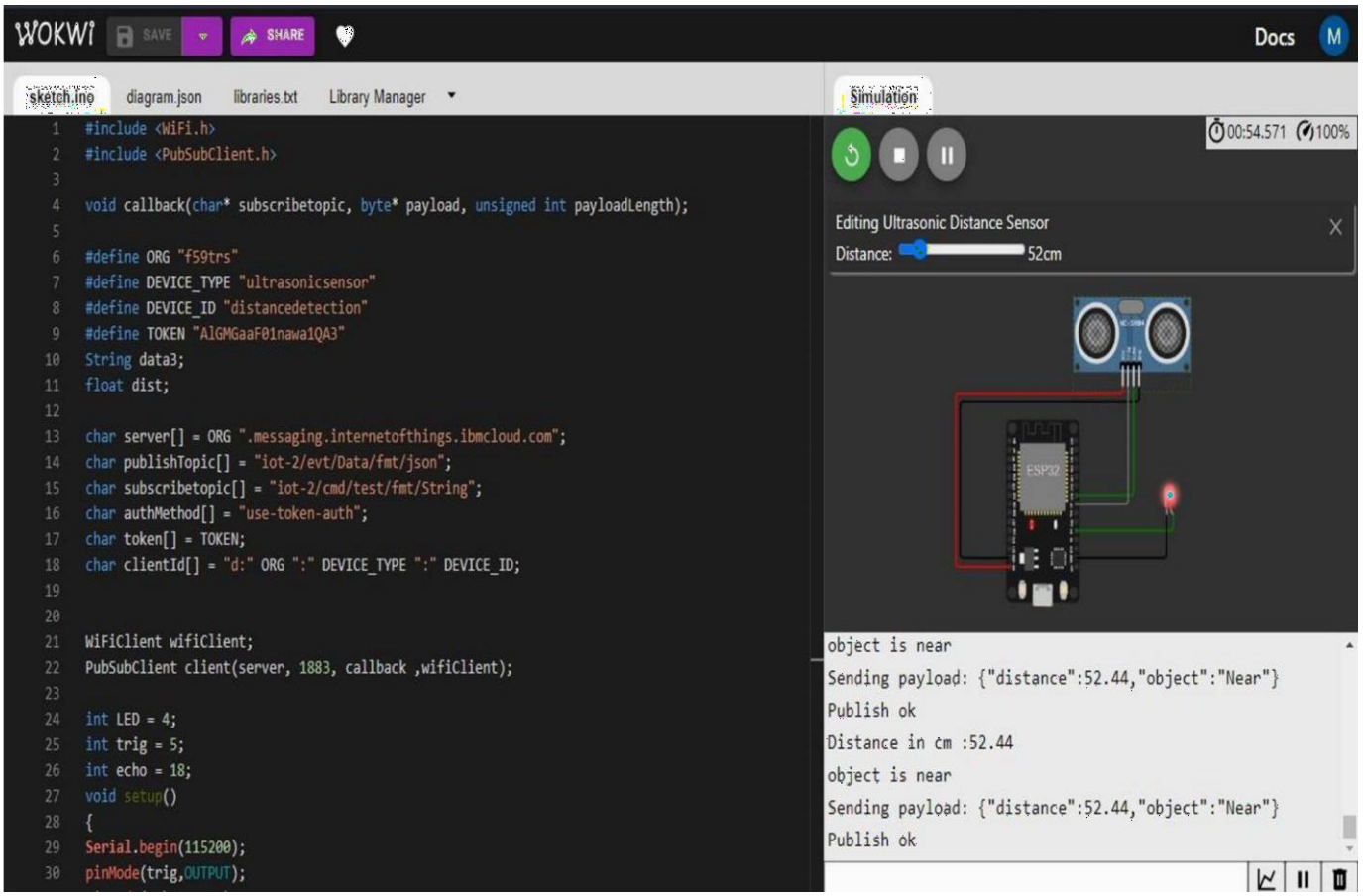
When object is not near to the ultrasonic sensor



Data sent to the IBM cloud device when the object is far



When object is nearer to the ultrasonic sensor

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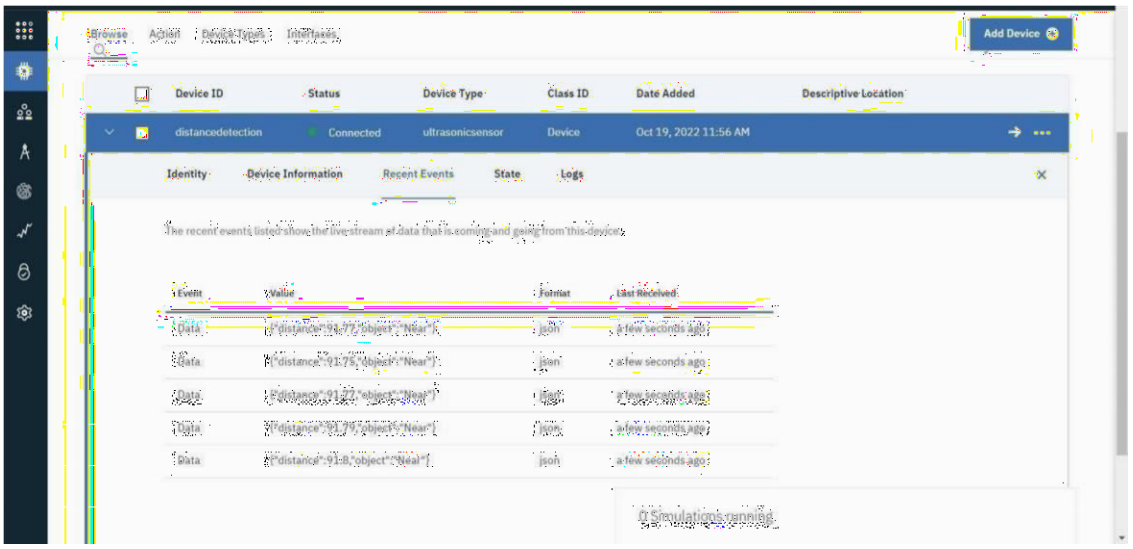
Data sent to the IBM cloud device when the object is near



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