## **Assignment -4**

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Maximum mark	2mark

### **Question-1:**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

#### **CODE:**

```
#include <WiFi.h>
 #include < PubSubClient.h > void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
#define ORG " j3bgcj"
#define DEVICE_TYPE "esp32" #define
 DEVICE_ID "1234"
 #define TOKEN "12345678" String data3; char server[] = ORG
 ".messaging.internetofthings.ibmcloud.com"; char publishTopic[] =
 "iot-2/evt/Data/fmt/json"; char subscribetopic[]
 = "iot-2/cmd/test/fmt/String"; char authMethod[] = "use-token-
 auth"; char token[] = TOKEN; char clientId[] = "d:" ORG ":"
 DEVICE_TYPE ":" DEVICE_ID;
 WiFiClient wifiClient;
 PubSubClient client(server, 1883, callback, wifiClient); const
 int trigPin = 5; const int echoPin = 18; #define
 SOUND_SPEED 0.034 long duration; float distance; void
 setup() { Serial.begin(115200); pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT); wificonnect(); mqttconnect();
 } void loop() { digitalWrite(trigPin,
 LOW);
              delayMicroseconds(2);
 digitalWrite(trigPin,
                            HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW); duration
```

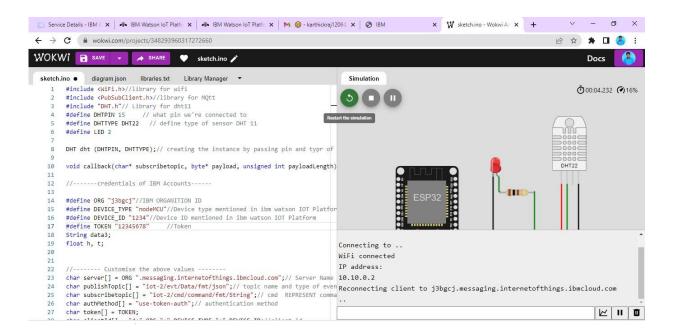
```
= pulseIn(echoPin, HIGH); distance
= duration * SOUND_SPEED/2; Serial.print("Distance
(cm): "); Serial.println(distance); if(distance<100)
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000); if (!client.loop())
{ mqttconnect(); } }
delay(1000)
; }
void PublishData(float dist) { mqttconnect(); String payload
= "{\"Distance\":"; payload += dist; payload
+= ",\"ALERT!!\":""\"Distance less than 100cms\""; payload
+= "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
} } void mqttconnect()
{ if
(!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print("."); delay(500);
initManagedDevice();
Serial.println();
} }
void wificonnect()
Serial.println();
Serial.print("Connecting to "); WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status() !=
WL_CONNECTED) { delay(500); Serial.print(".");
Serial.println(""); Serial.println("WiFi connected");
Serial.println("IP address:
"); Serial.println(WiFi.localIP());
}
void initManagedDevice() {
if (client.subscribe(subscribetopic)) { Serial.println((subscribetopic)); Serial.println("subscribe to
cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
} }
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength) {
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic); for (int i = 0; i
< payloadLength; i++)
{
    data3 += (char)payload[i];
}
Serial.println("data: "+ data3); data3="";
}</pre>
```

#### Wokwi Link:

https://wokwi.com/projects/348293960317272660

# Output and Simulation:



Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

