ASSIGNMENT-4
DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	27 October 2022
Team ID	PNT2022TMI25602
Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to IBM cloud and display in device recent events.

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();


const int trigpin=5;
const int echopin=18;
String command;
String data="";

long duration;
float dist;
```

```
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);

  publishData();
  delay(500);

  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
```

```
 }
   initManagedDevice();
   Serial.println();
  }
}

void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    }

  }
    if(dist>101 && dist<111){
    String payload = "{\"Alert distance\":";
    payload += dist;
    payload += "}";
```

```
Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
   if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
    digitalWrite(led,HIGH);
  }else {
    Serial.println("Publish FAILED");
  }

 }


 }
 void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
 Serial.print("callback invoked for topic:");
 Serial.println(subscribeTopic);
 for(int i=0; i<payloadLength; i++){
  dist += (char)payload[i];
 }
 Serial.println("data:"+ data3);
 if(data3=="lighton"){
  Serial.println(data3);
  digitalWrite(led,HIGH);
 }
 data3="";
}
```

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt


void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

//-------credentials of IBM Accounts------

#define ORG "4hn0jp"//IBM ORGANITION ID
#define DEVICE_TYPE "ULTRASON"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "DISTANCEDETECT"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "wuo5s7PR)ZSegVk&Rx"//Token
String data3;
float dist;


//-------- Customise the above values --------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd  REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id


//-----------------------------------------
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
Serial.begin(115200);
```

esp32-blink.ino ● diagram.json ● libraries.txt ● Library Manager

```
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
}
void loop()// Recursive Function
{

 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);


  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}



/*.....retrieving to Cloud.....*/

void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
  /*
     creating the String in in form JSon to update the data to ibm cloud
```

```
    creating the String in in form JSon to update the data to ibm cloud
  */
  String object;
  if (dist <100)
  {
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
  }
  else
  {
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
  }

  String payload = "{\"distance\":";
  payload += dist;
  payload += "," "\"object\":\"";
  payload += object;
  payload += "\"}";


  Serial.print("Sending payload: ");
  Serial.println(payload);
```

esp32-blink.ino ● diagram.json ● libraries.txt ● Library Manager

```
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
  } else {
    Serial.println("Publish failed");
  }

}
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }

    initManagedDevice();
    Serial.println();
  }
}
void wificonnect() //function defination for wificonnect
{
  Serial.println();
  Serial.print("Connecting to ");

  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
```

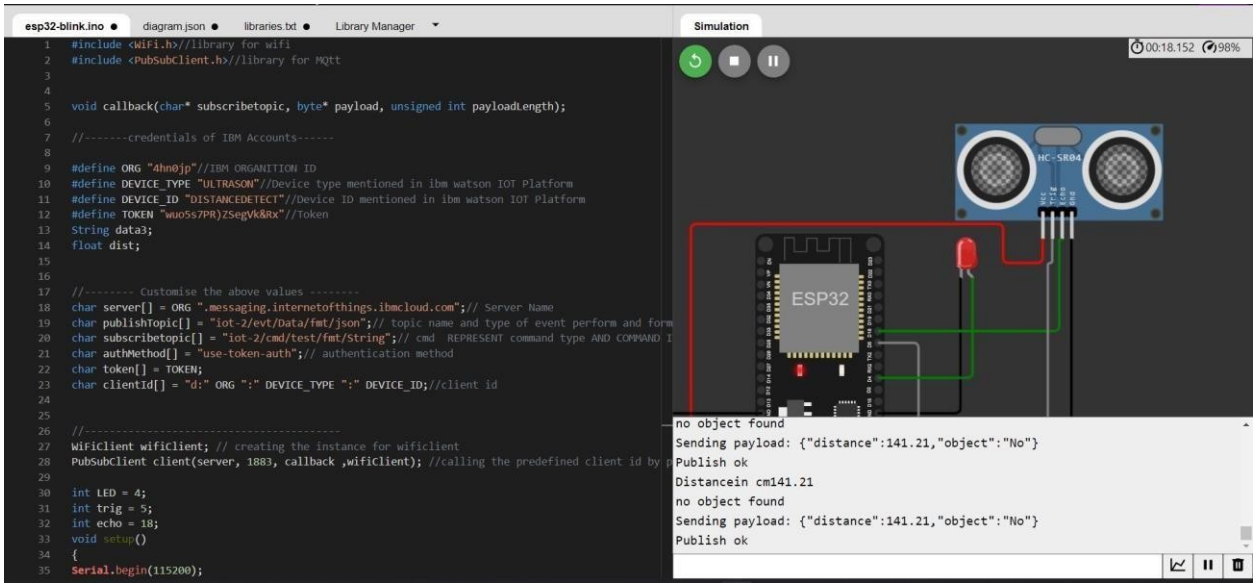
esp32-blink.ino ● diagram.json ● libraries.txt ● Library Manager

```
  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
}

void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }

//   Serial.println("data: "+ data3);
//   if(data3=="Near")
//   {
// Serial.println(data3);
```

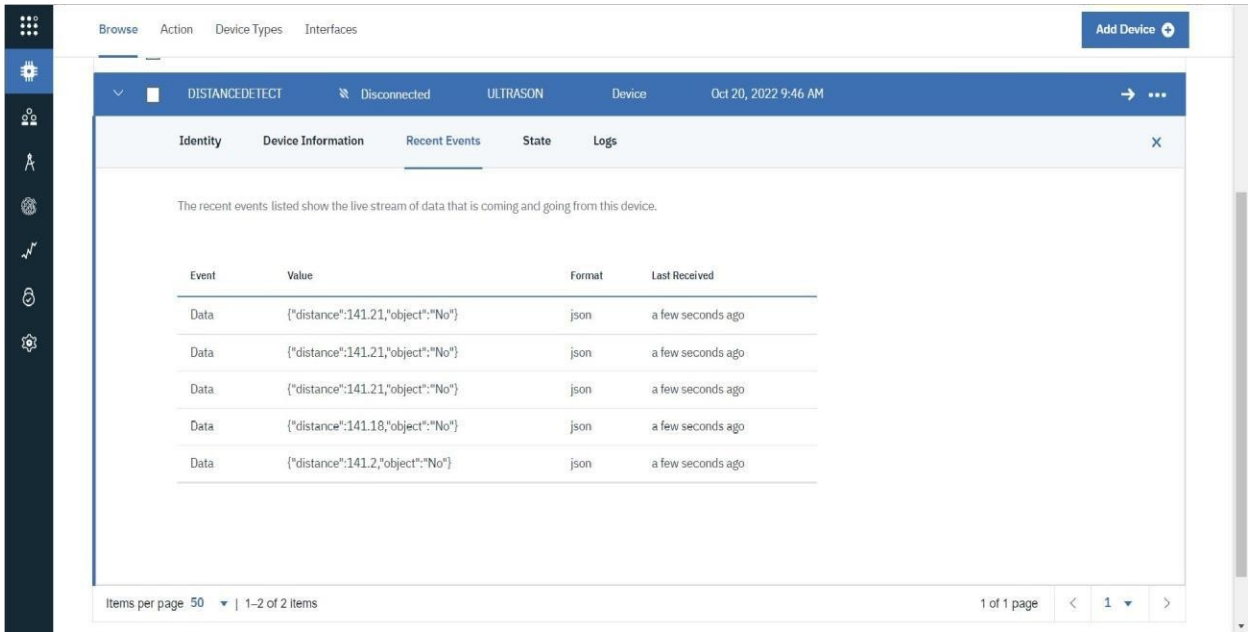
esp32-blink.ino ● diagram.json ● libraries.txt ● Library Manager

```
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }

//   Serial.println("data: "+ data3);
//   if(data3=="Near")
//   {
// Serial.println(data3);
// digitalWrite(LED,HIGH);

//   }

//   else
//   {
// Serial.println(data3);
// digitalWrite(LED,LOW);

//   }
data3="";


}
```

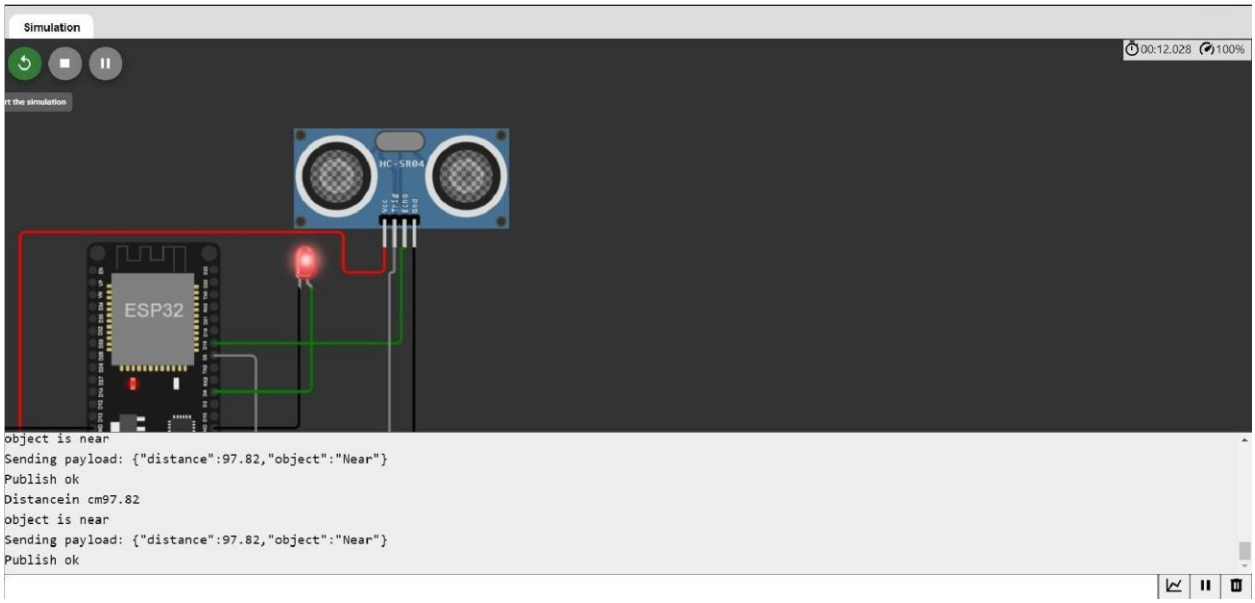
OUTPUT:



Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near