

Assignment date	07 November 2022
Student Name	Ms.K.Vanisri
Student Roll Number	821719106027
Maximum Marks	2 Marks

Question-4

Write code and connections in wokwi for the ultrasonic sensor

Code

```

/*
  Ultrasonic Simple
  Prints the distance read by an ultrasonic sensor in
  centimeters. They are supported to four pins ultrasound
  sensors (like HC-SC04) and three pins (like PING))
  and Seed Studio sensors).

  The circuit:
  * * Module HR-SC04 (four pins) or PING))) (and other with
    three pins), attached to digital pins as follows:

  -----
  | HC-SC04 | Arduino |   | 3 pins | Arduino |
  -----
  |   Vcc   |   5V    |   |   Vcc   |   5V    |
  |   Trig  |   12    | OR |   SIG  |   13    |
  |   Echo  |   13    |   |   Gnd   |   GND    |
  |   Gnd   |   GND   |   | -----
  -----

  Note: You do not obligatorily need to use the pins defined above

  By default, the distance returned by the read()
  method is in centimeters. To get the distance in inches,
  pass INC as a parameter.
  Example: ultrasonic.read(INC)

  created 3 Apr 2014
  by Erick Simões (github: @ErickSimoes | twitter: @AloErickSimoes)
  modified 23 Jan 2017
  by Erick Simões (github: @ErickSimoes | twitter: @AloErickSimoes)
  modified 03 Mar 2017
  by Erick Simões (github: @ErickSimoes | twitter: @AloErickSimoes)
  modified 11 Jun 2018
  by Erick Simões (github: @ErickSimoes | twitter: @AloErickSimoes)

  This example code is released into the MIT License.
*/

#include "Ultrasonic.h"

/*
  Pass as a parameter the trigger and echo pin, respectively,
  or only the signal pin (for sensors 3 pins), like:
  Ultrasonic ultrasonic(13);
*/
Ultrasonic ultrasonic(12, 13);
int distance;

```

```

void setup() {
  Serial.begin(9600);
}

void loop() {
  // Pass INC as a parameter to get the distance in inches

  distance = ultrasonic.read(CM);

  Serial.print("Distance in CM: ");
  Serial.println(distance);

  distance = ultrasonic.read(INC);

  Serial.print("Distance in Inches: ");
  Serial.println(distance);

  delay(1000);
}

```

Output

The screenshot displays the Wokwi IDE interface for a project named "hc-sr04-Ultrasonic-Simulation.ino". The code editor on the left shows the following code:

```

23  pass INC as a parameter.
24  Example: ultrasonic.read(INC)
25
26  created 3 Apr 2014
27  by Erick Simões (github: @ErickSimoes |
28  modified 23 Jan 2017
29  by Erick Simões (github: @ErickSimoes |
30  modified 03 Mar 2017
31  by Erick Simões (github: @ErickSimoes |
32  modified 11 Jun 2018
33  by Erick Simões (github: @ErickSimoes |
34
35  This example code is released into the P
36  */
37
38  #include "Ultrasonic.h"
39
40  /*
41  Pass as a parameter the trigger and echo pins
42  or only the signal pin (for sensors 3 pin)
43  Ultrasonic ultrasonic(13);
44  */
45  Ultrasonic ultrasonic(12, 13);
46  int distance;
47
48  void setup() {
49    Serial.begin(9600);
50  }
51

```

The simulation output on the right shows the following sequence of readings:

```

Distance in Inches: 41
Distance in CM: 104
Distance in Inches: 41
Distance in CM: 105
Distance in Inches: 41
Distance in CM: 105
Distance in Inches: 41

```

The simulation interface includes a "Simulation" tab with play, stop, and pause buttons, a timer showing 00:11.331, and a battery level indicator at 65%. The bottom status bar shows the system temperature as 29°C Cloudy, the time as 02:55 PM, and the date as 07-11-2022.