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Dept : ECE

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# **Ultrasonic sensor simulation in Wokwi**

#### **Question-1:**

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than

100cms send an "Alert" to IBM cloud and display in the device recent events.

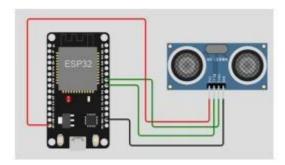
#### Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//-----tredentials of IBM Accounts----#define
ORG "kotoq5"//IBM ORGANITION ID
#define DEVICE TYPE "ESP32"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE_ID "12345"//Device ID mentioned in ibm watson IOT
Platform
#define TOKEN "12345678" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json"; char
subscribetopic[] = "iot-2/cmd/test/fmt/String"; char
authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration; float
distance; void setup() {
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
} void
loop() {
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
```

```
distance = duration *
SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)</pre>
Serial.println("ALERT!!");
delay(1000);PublishData(distance);
delay(1000); if (!client.loop()) {
mqttconnect();
} }
delay(1000);
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
} } void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}initManagedDevice();
Serial.println();
}
}
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while
(WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
```

```
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic); for
(int i = 0; i < payloadLength; i++)</pre>
{//Serial.print((char)payload[i]);
data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
}
Diagram.json:
"version": 1,
"author": "sweetysharon",
"editor": "wokwi",
"parts": [
{ "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -
114.67, "attrs": {} },
{ "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left":
89.17, "attrs": {} }
],
"connections": [
[ "esp:TX0", "$serialMonitor:RX", "", [] ],
[ "esp:RX0", "$serialMonitor:TX", "", [] ],
"esp:VIN",
"ultrasonic1:VCC",
"red",
[ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
[ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04",
"h170" ] ],
[ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07",
"h130.67" ] ],
[ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01",
"h110" ] ]]
}
```

## **Circuit Diagram:**



### **Output:**

#### Wokwi output:

```
Connecting to ....

Wifi commercial

IF address:

10.18.0.2

Recommercing client to ythese messaging intermetefihings itecloud com

Lot-2/cmd/test/fmt/String

sabscribe to cmd OK

Oistance (cm): 309.00

Distance (cm): 399.00

Distance (cm): 399.00
```