

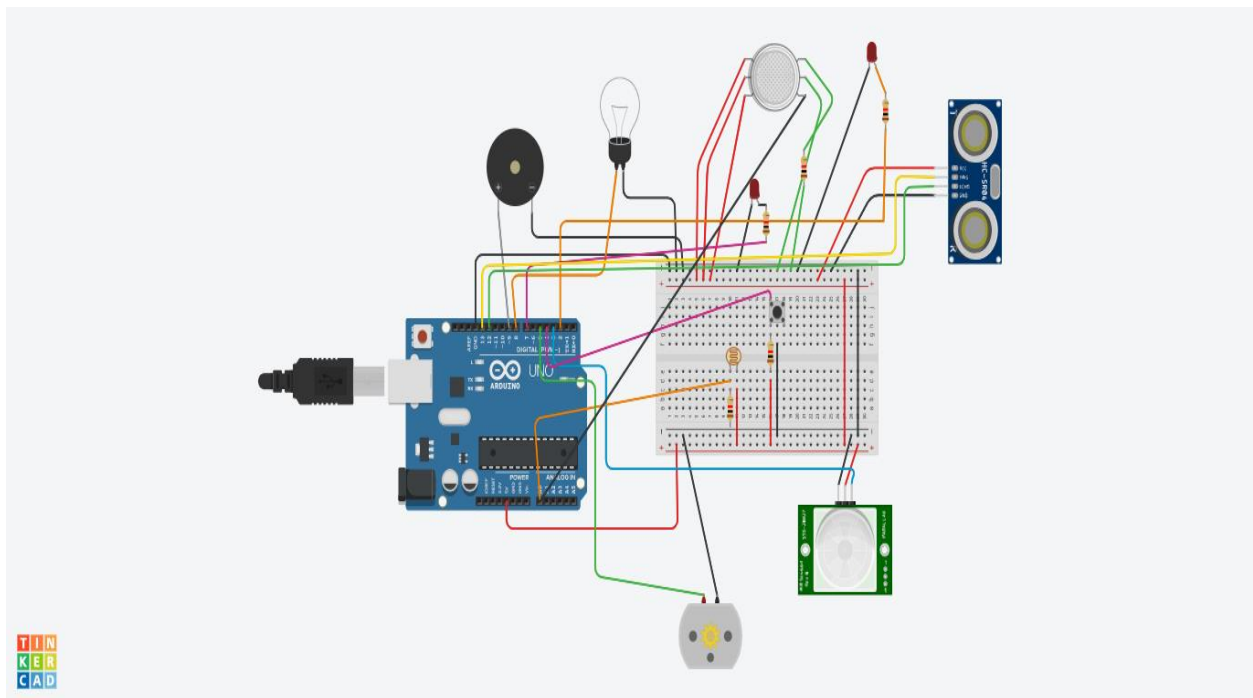
# ASSIGNMENT 1

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## OBJECTIVE:

To build a small home in tinkercad using atleast 2 sensors ,  
buzzer, LED in a circuit and to stimulate in a single code.



## CODE:

```
int sensorReading = 0;
```

```
int inches = 0;
```

```
int cm = 0;
```

```
int triggerPin = 13;
int echoPin = 12;
int default = 0;
long readUltrasonicDistance(int triggerPin,int echoPin)
{
pinMode(triggerPin, OUTPUT);
digitalWrite(triggerPin, LOW);
delayMicroseconds(2);
digitalWrite(triggerPin, HIGH);
delayMicroseconds(10);
digitalWrite(triggerPin, LOW);
pinMode(echoPin, INPUT);
return pulseIn(echoPin, HIGH);
}
int adcPin = 0;
int adcValue = 0;
float v; float rs,ppm;
int buttonState = 0;
void setup()
{
pinMode(8, OUTPUT);
pinMode(A0, INPUT);
Serial.begin(9600);
```

```

pinMode(2, OUTPUT);

cm = 0.01723*readUltrasonicDistance(triggerPin, echoPin);

default = cm;

Serial.print(default);

pinMode(3, INPUT);

pinMode(9, OUTPUT);

pinMode(5, OUTPUT);

pinMode(4, INPUT);

//Motor

pinMode(7, OUTPUT);

pinMode(A1, INPUT);

}

void loop()

sensorReading = analogRead(A0);

if(sensorReading < 900)

{

digitalWrite(8, HIGH);

}

Else

{

digitalWrite(8, LOW);

}

cm = 0.01723*readUltrasonicDistance(triggerPin, echoPin) ;

```

```
if(cm < default){ digitalWrite(2,HIGH);
delay(50); digitalWrite(2,LOW);
}
Else
{
digitalWrite(2,LOW);
}
int value = digitalRead(3);
if (value == 1)
{
tone(9, 440, 1000);
}
buttonState = digitalRead(4);
if(buttonState == 1)
{
digitalWrite(5,0);

}
Else
{
digitalWrite(5,HIGH);
}
int sensor_gas = analogRead(A1);
```

```
if(sensor_gas >= 400)
{
digitalWrite(7,HIGH);
}
Else
{
digitalWrite(7,LOW);
}
delay(1000);
}
```