

## Assignment - 4

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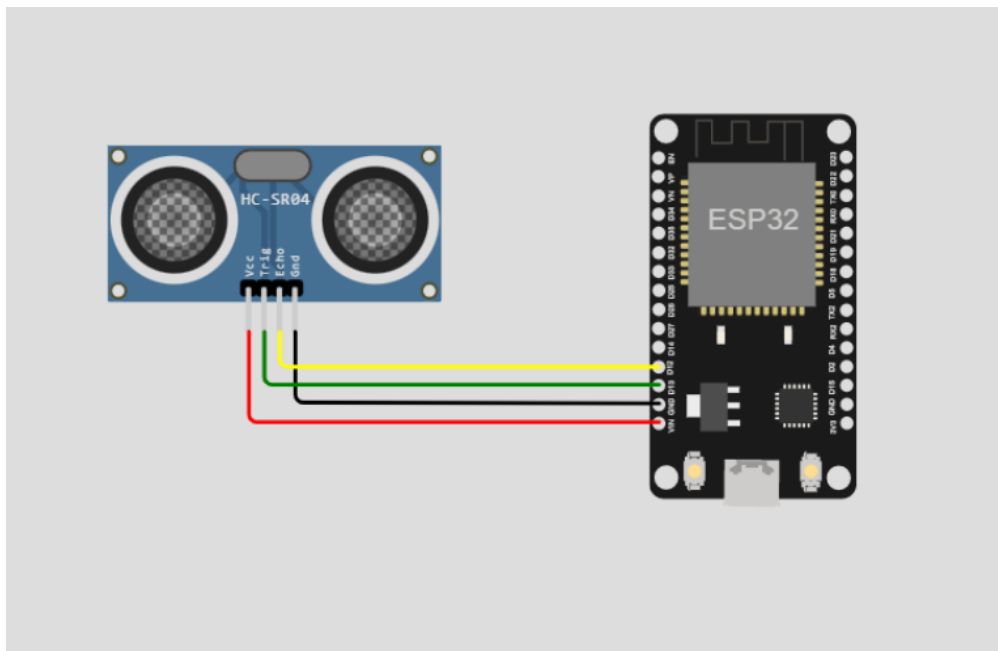
**ROLL.No:-** *110719106033*

### **OBJECTIVES:-**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

**LINK :-** [sketch.ino - Wokwi Arduino and ESP32 Simulator](#)

### **CIRCUIT:-**



### **CODE:-**

```
#include <WiFi.h> //library for wifi
#include <PubSubClient.h> //library for MQTT
#define TRIG_PIN 13
#define ECHO_PIN 12
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
```

```
//-----credentials of IBM Accounts-----
```

```
#define ORG "hg0hl1"//IBM ORGANITION ID
```

```
#define DEVICE_TYPE "123"//Device type mentioned in ibm watson IOT Platform
```

```
#define DEVICE_ID "abcd"//Device ID mentioned in ibm watson IOT Platform
```

```
#define TOKEN "12345678" //Token
```

```
//----- Customise the above values -----
```

```
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
```

```
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in  
which data to be send
```

```
char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT command type AND  
COMMAND IS TEST OF FORMAT STRING
```

```
char authMethod[] = "use-token-auth";// authentication method
```

```
char token[] = TOKEN;
```

```
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
```

```
//-----
```

```
WiFiClient wifiClient; // creating the instance for wificlient
```

```
PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing  
parameter like server id,portand wificredential
```

```
void setup()// configuring the ESP32
```

```
{  
  Serial.begin(115200);  
  pinMode(TRIG_PIN, OUTPUT);  
  digitalWrite(TRIG_PIN, LOW);  
  pinMode(ECHO_PIN, INPUT);  
  delay(10);  
  Serial.println();  
  wificonnect();  
  mqttconnect();  
}
```

```
void loop()// Recursive Function
```

```
{
```

```

digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
float duration_us = pulseIn(ECHO_PIN, HIGH);
float distance = 0.017 * duration_us;

if(distance<100)
{
    PublishData(distance,"ALERT");
} else{
    PublishData(distance,"SAFE");
}

delay(1000);
if(!client.loop()) {
    mqttconnect();
}
}

/*.....retrieving to Cloud.....*/

void PublishData(float d,char s[]) {
    mqttconnect();//function call for connecting to ibm
    /*
        creating the String in in form JSon to update the data to ibm cloud
    */
    String payload = "{\"Distance\":";
    payload+=d;
    payload+=",";
    payload+="\"MESSAGE\":";
    payload+="\"";
    payload+=s;
    payload+="\"";
    payload+="}";

    Serial.print("Sending payload: ");

```

```

Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish ok
    in Serial monitor or else it will print publish failed
} else {
    Serial.println("Publish failed");
}
}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void wificonnect() //function defination for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");
    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {

```

```

if(client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
} else {
    Serial.println("subscribe to cmd FAILED");
}
}
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
}
}

```

## OUTPUT:-

