# **ASSIGNMENT-4**

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# **OBJECTIVE**

Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud aand display indevicerecent events.

# **SOLUTION**

```
//Pins
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;
void setup() {

// The Trigger pin will tell the sensor to range find Pin Mode(TRIG_PIN, OUTPUT);
digital Write(TRIG_PIN, LOW);
```

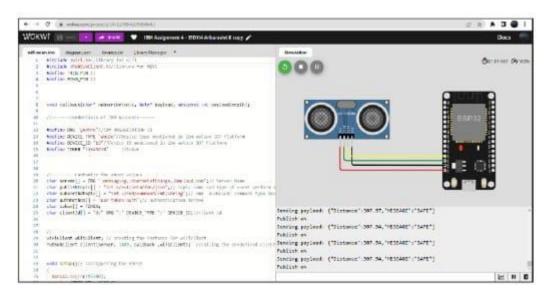
```
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT );
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}
void loop()
{ unsigned long
t1:
unsigned long t2;
unsigned long pulse_width;
float cm:
float inches:
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN )==0 );
// Measure how long the echo pin was held high (pulse
width)
// Note: the micros() counter will overflow after-70 min
t1 = micros();
```

```
while (digitalRead(ECHO_PIN) == 1);
t2 = micros();
pulse\_width = t2-t1;
// Calculate distance in centimeters and inches. The
constants
//are found in the datasheet, and calculated from the
assumed speed
// of sound in air at sea level (- 340m/s)
cm=pulse_Width / 58;
inches = pulse_width/148.0;
// Print out results
if (pulse_width > MAX _ DIST ) { Serial.println("Out of
range"); }
else {
Serial.println("*******************************);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if (cm < 100)
{ //while(true)
{ Serial.println("Alert!!"); //
```

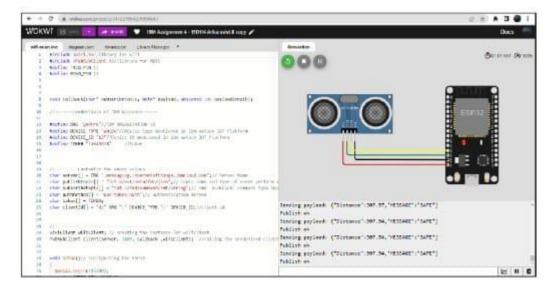
```
Serial.print("*************************
*"); }
//wait at least 1000ms before next measurement
Delay(1000);
}
```

### **OUTPUT**

1.If the distance is less than 100cm, it alerts.



2. If the distance is more than 100 cm, it won't alert.



### 3. Simulation and code execution

