ASSIGNMENT NO-1

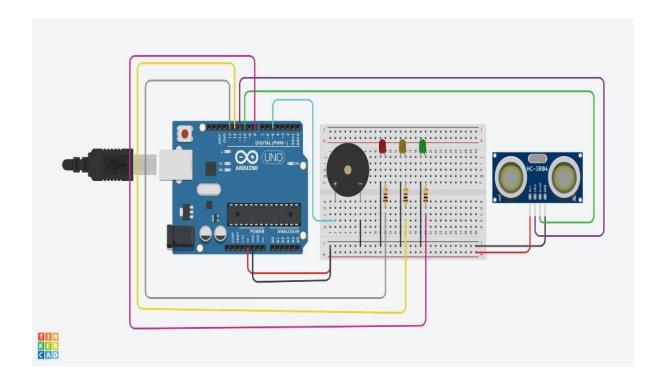
Project Name: SmartFarmer - IoT Enabled Smart Farming
Application

Batch Number: B1-1M3E

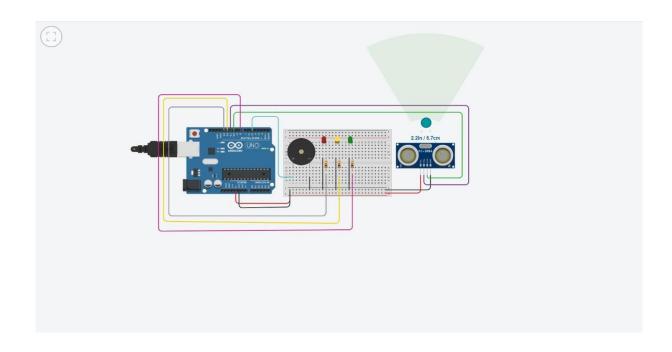
Assignment Topic: smart home automation using sensor leds and buzzer

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Before Simulation



After Simulation



Code:

```
1 // C++ code
  2 //
  3 int distancia = 0;
  4
  5 int i = 0;
  6
  7
    long readUltrasonicDistance(int triggerPin, int echoPin)
  9
      pinMode(triggerPin, OUTPUT); // Clear the trigger
 10
      digitalWrite(triggerPin, LOW);
      delayMicroseconds(2);
 11
      // Sets the trigger pin to HIGH state for 10 microseconds
 12
 13
      digitalWrite(triggerPin, HIGH);
      delayMicroseconds (10);
 14
 15
      digitalWrite(triggerPin, LOW);
 16
      pinMode (echoPin, INPUT);
 17
      // Reads the echo pin, and returns the sound wave travel time i
      return pulseIn(echoPin, HIGH);
 18
 19
 20
 21
    void setup()
      pinMode(8, OUTPUT);
 23
      pinMode(12, OUTPUT);
 24
 25
      pinMode (13, OUTPUT);
26 pinMode(5, OUTPUT);
```

```
26
     pinMode (5, OUTPUT);
27
   }
28
29 void loop()
31
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
      if (distancia > 10) {
33
        digitalWrite(8, HIGH);
34
        digitalWrite(12, LOW);
35
        digitalWrite(13, LOW);
36
        digitalWrite(5, LOW);
37
        delay(200); // Wait for 200 millisecond(s)
        digitalWrite(5, LOW);
39
        delay(200); // Wait for 200 millisecond(s)
40
      } else {
41
        digitalWrite(8, LOW);
42
        digitalWrite(5, LOW);
43
44
45
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
46
      if (distancia <= 10) {
47
        digitalWrite(8, LOW);
48
        digitalWrite(12, HIGH);
49
        digitalWrite(13, LOW);
50
        digitalWrite(5, HIGH);
51
        delay(200); // Wait for 200 millisecond(s)
52 ◀
```

```
51
       delay(200); // Wait for 200 millisecond(s)
52
       digitalWrite(5, LOW);
53
       delay(200); // Wait for 200 millisecond(s)
54
     } else {
55
       digitalWrite(12, LOW);
56
       digitalWrite(5, LOW);
57
58
59
     distancia = 0.01723 * readUltrasonicDistance(11, 10);
60
     if (distancia <= 5) {
61
       digitalWrite(8, LOW);
62
       digitalWrite(12, LOW);
       digitalWrite(13, HIGH);
63
       digitalWrite(5, HIGH);
64
65
       delay(100); // Wait for 100 millisecond(s)
66
       digitalWrite(5, LOW);
67
       delay(100); // Wait for 100 millisecond(s)
68
      } else {
69
       digitalWrite(13, LOW);
       digitalWrite(5, LOW);
71
   }
```