

ASSIGNMENT-4

1. Write code and connections in wokwi for ultrasonic sensor. whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Solution:

```
//Pins const int TRIG_PIN = 7 ;
const int ECHO_PIN = 8;
//Anything over 400 cm (23200 us pulse) is "out of range" const unsigned
int MAX_DIST = 23200;
void setup() {
  // The Trigger pin will tell the sensor to range find
  Pin Mode(TRIG_PIN, OUTPUT);
  digital Write(TRIG_PIN, LOW);
  //Set Echo pin as input to measure the duration of
  //pulses coming back from the distance sensor
  pinMode(ECHO_PIN, INPUT ) ;
  // We'll use the serial monitor to view the sensor output
  Serial.begin(9600); }
void loop() {
  unsigned long t1;
  unsigned long t2;
  unsigned long pulse_width;
  float cm;
  float inches;
  // Hold the trigger pin high for at least 10 us
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  // Wait for pulse on echo pin while
  (digitalRead( ECHO_PIN )==0 );
  // Measure how long the echo pin was held high (pulse width)
  // Note: the micros() counter will overflow after-70 min
  t1= micros ();
  while (digitalRead(ECHO_PIN) == 1)
  ; t2= micros ();
  pulse_width = t2-t1;
  // Calculate distance in centimeters and inches.
  The constants //are found in the datasheet, and calculated from the assumed speed
```

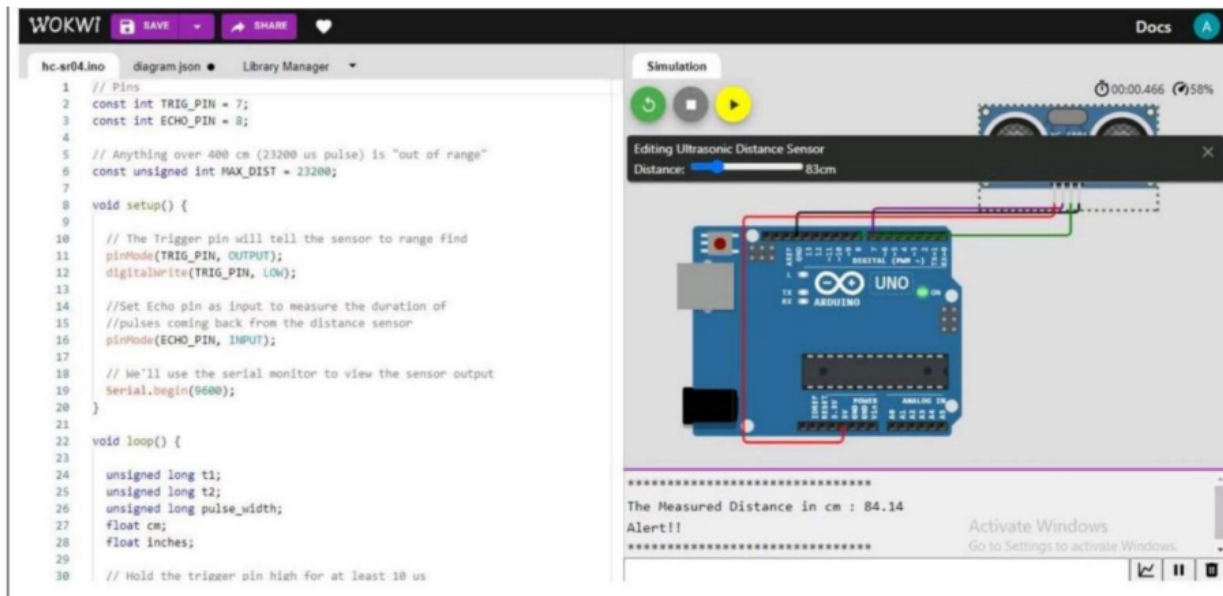
```

// of sound in air at sea level (- 340m/s) cm=pulse_Width / 58 ;
inches = pulse_width/148.0;
// Print out results
if (pulse_width > MAX _ DIST ){
Serial.println("Out of range"); }
else { Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm); if( cm < 100 ){ //while(true)
{
Serial.println("Alert!!");
//}
}
Serial.print("*****"); }
//wait at least 1000ms before next measurement
Delay(1000);
}

```

OUTPUT:

1.If the distance is less than 100 cms ,it alerts



2.If the distance is more than 100 cms,it won't alert

WOKWI

SAVE SHARE

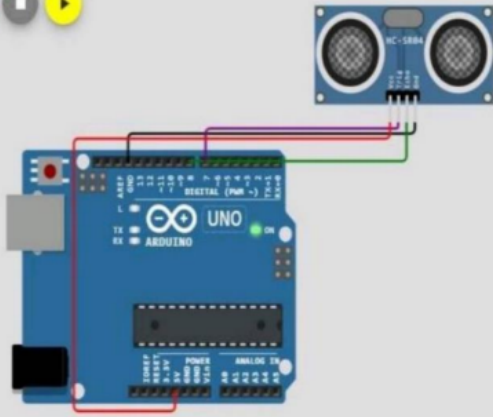
Docs

hc-sr04.ino diagram.json Library Manager

```
1 // Pins
2 const int TRIG_PIN = 7;
3 const int ECHO_PIN = 8;
4
5 // Anything over 400 cm (23200 us pulse) is "out of range"
6 const unsigned int MAX_DIST = 23200;
7
8 void setup() {
9
10 // The Trigger pin will tell the sensor to range find
11 pinMode(TRIG_PIN, OUTPUT);
12 digitalWrite(TRIG_PIN, LOW);
13
14 //Set Echo pin as input to measure the duration of
15 //pulses coming back from the distance sensor
16 pinMode(ECHO_PIN, INPUT);
17
18 // We'll use the serial monitor to view the sensor output
19 Serial.begin(9600);
20 }
21
22 void loop() {
23
24 unsigned long t1;
25 unsigned long t2;
26 unsigned long pulse_width;
27 float cm;
28 float inches;
```

Simulation

00:00.599 62%



The Measured Distance in cm : 227.10

Activate Windows
Go to Settings to activate Windows.

3.Simulation and code execution

